Boundary Layer Effect in Regularized Meshless Method for Laplace Equation

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Abstract: This paper presents an efficient strategy for the accurate evaluation of near-boundary solutions in the regularized meshless method (RMM), also known as the boundary layer effect associated with the boundary element method. The RMM uses the double layer potentials as its interpolation basis function. When the field point is close to the boundary, the basis function will present nearly strongand hyper-singularities, respectively, for potentials and its derivative. This paper represents the first attempt to apply a nonlinear transformation, based on sinh function, to the accurate evaluation of nearly singular kernels associated with the RMM. The accuracy and efficiency of the proposed strategy are demonstrated through several numerical examples, where the solutions at as close as 1.0E–6 distance to the boundary are accurately evaluated.

Keywords: Regularized meshless method, Double layer potentials, Near singularity, Boundary layer effect, nonlinear transformation.

1 Introduction

The regularized meshless method (RMM) belongs to the family of meshless boundary collocation methods [Young, Chen and Lee (2005)] and can be viewed as a regularized method of fundamental solutions (MFS) [Fairweather and Karageorghis (1998)] for the solution of certain boundary value problems. The method circumvents the fictitious boundary issue long perplexing the MFS [Ling, Opfer and Schaback (2006)] while being truly free of mesh and integral, and easy-to-program. Prior to this study, this method has been successfully applied to a variety of physical problems, such as potential [Young, Chen and Lee (2005)], exterior acoustics [Young, Chen and Lee (2006)], anti-plane shear [Chen, Chen and Kao (2008)],

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acoustic eigenvalue [Chen, Chen and Kao (2006)] and anti-plane piezoelectricity problems [Chen, Kao and Chen (2009)]. Like to the other boundary-type numerical methods, the RMM, however, encounters a dramatic drop of solution accuracy at the region nearby the boundary, because of singularity of its double layer fundamental solutions.

Accurate evaluation of near-boundary solutions plays an important role in solving many engineering problems [Johnston and Elliott (2005)], such as contact [Aliabadi and Martin (2000)], inverse and sensitivity [Zhang, Rizzo and Rudolphi (1999)], thin- body [Luo, Liu and Berger (1998)], and crack problems [Dirgantara and Aliabadi (2000)], just to mention a few. In such cases, the calculation point is often placed very closely to, but not on, the physical boundary. Theoretically, the values of singular RMM kernel functions at these boundary-adjacent points are finite but not smooth at all. Nearby boundary, the kernels may have a sharp peak as the calculation point approaches closer to the boundary. Consequently, the kernels become *nearly singular* and cannot be accurately calculated.

Inspired by the recent work on handling near singularity in the boundary element method and the singular boundary method [Gu, Chen and Zhang (2013); Gu, Chen and Zhang (2012)], this study applies an efficient nonlinear transformation [Johnston and Elliott (2005)], based on the sinh function, to remove or damp out the near singularity of the double layer fundamental solutions associated with the RM-M. Compared with a straightforward implementation of the RMM, the transformed RMM proposed in this paper can improve the numerical accuracy and stability n-earby boundary by several orders of magnitude in terms of relative errors.

A brief outline of the rest of this paper is as follows. The RMM formulation and its implementation for potential problems are presented in Section 2. And then Section 3 explains the principle of the nearly singular properties of the RMM formulation, and introduces the sinh transformation. In Section 4, the accuracy and validity of the transformed RMM are verified through three 2D potential examples, in which the solutions at interior points very close to the boundary are investigated in details. Finally, the conclusions and remarks are provided in Section5.

2 RMM formulation for 2D potential problems

Without a loss of generality, we consider the following Laplace problem:

$$\nabla^2 u(\mathbf{x}) = 0, \quad \mathbf{x} \in \Omega \tag{1}$$

subject to the following boundary conditions

$$u(\mathbf{x}) = \bar{u}(\mathbf{x}), \quad \mathbf{x} \in \Gamma_D \quad \text{(Dirichlet boundary condition)}$$
(2)

$$q(\mathbf{x}) = \bar{q}(\mathbf{x}), \quad \mathbf{x} \in \Gamma_N$$
 (Neumann boundary condition) (3)

$$\lim_{\|x\|_2 \to \infty} u(\mathbf{x}) = \text{const},\tag{4}$$

where *u* is the potential field, Ω represents the computational domain, $\Gamma = \Gamma_D \cup \Gamma_N = \partial \Omega$ denotes the boundary of the domain Ω , the barred quantities indicate the given values on the boundary. The flux q(x) along the boundary Γ_N is given by

$$q(\mathbf{x}) = \frac{\partial u(\mathbf{x})}{\partial \mathbf{n}} \tag{5}$$

where *n* denotes the outward normal at the calculation point. In Eq.(4), $||x||_2$ represents the Euclidean distance, and const stands for a finite constant. It is noted that, for exterior problems, the potential u(x) satisfies not only boundary conditions (2) and (3) but also the boundary condition (4) at infinity.

By using the radial basis function (RBF) method [Cheng, Young and Tsai (2000); Li, Lu, Hu and Cheng (2008); Liu (2007)], the solutions u(x) and q(x) for interior problems can be approximated by:

$$u(\mathbf{x}^{i}) = \sum_{j=1}^{N} \alpha^{j} A^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}), \tag{6}$$

$$q(\mathbf{x}^{i}) = \sum_{j=1}^{N} \alpha^{j} B^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}),$$
(7)

where $A^{(I)}(\mathbf{x}^i, \mathbf{s}^j)$ and $B^{(I)}(\mathbf{x}^i, \mathbf{s}^j)$ are RBF of choice, x^i the *i*th collocation point, s^j the *j*th source point, $\{\alpha^j\}_{j=1}^N$ denote the unknown coefficients to be determined, and *N* represents the numbers of source points.

The kernel basis function of the RMM are the following double layer potentials

$$A^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}) = \frac{-((\mathbf{x}^{i} - \mathbf{s}^{j}), \mathbf{n}_{j})}{r_{ij}^{2}},$$
(8)

$$B^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}) = \frac{2((\mathbf{x}^{i} - \mathbf{s}^{j}), n_{j})((\mathbf{x}^{i} - \mathbf{s}^{j}), \bar{\mathbf{n}}_{i})}{r_{ij}^{4}} - \frac{(\mathbf{n}_{j}, \bar{\mathbf{n}}_{i})}{r_{ij}^{2}},$$
(9)

where (,) respresents the product of two vectors, $r_{ij}^2 = \|\mathbf{s}^j - \mathbf{x}^i\|_2$ denotes the distance between the collocation and source points, \mathbf{n}_j is the normal vector at \mathbf{s}^j , $\bar{\mathbf{n}}_i$ the normal vector at \mathbf{x}^i , superscript (I) denotes interior domain problems. The unknown coefficients $\{\alpha^j\}_{j=1}^N$ can be determined by collocating at *N* observation points with the boundary conditions Eqs.(6) and (7). Then, physical quantities at interior points can be evaluated using Eq.(6). Similarly, the representation of the solution of exterior problem can be approximated as

$$u(\mathbf{x}^{i}) = \sum_{j=1}^{N} \alpha^{j} A^{(E)}(\mathbf{x}^{i}, \mathbf{s}^{j}),$$
(10)

$$q(\mathbf{x}^i) = \sum_{j=1}^N \alpha^j B^{(E)}(\mathbf{x}^i, \mathbf{s}^j), \tag{11}$$

where the superscript (E) denotes the exterior problems.

It is noted that, in the traditional MFS, the source points are placed on the fictitious boundary, for example, see Fig.1(a) and (b), outside the problem domain to avoid the singularity of kernel functions. However, the placement of fictitious boundary is largely based on experiences, especially for complex geometric and high dimensional problems [Berger and Karageorghis (2001); Fan, Chan, Kuo and Yeih (2012); Marin (2010)]. Overcoming the abovementioned shortcoming, the source points of the RMM are distributed on the physical boundary, coincident with the collocation points, see Fig.1(c) and (d).



Figure 1: Problem sketch and nodes distribution using the conventional MFS and the RMM for interior and exterior problems: (a) interior problems (MFS), (b) exterior problems (MFS), (c) interior problems (RMM), and (d) exterior problems (RMM).

2.1 The RMM formulation for interior problems

When the collocation point x^i approaches the source point s^j , the distance between these two nodes tends to zero, and the basis function kernels in Eqs.(6) and (7) present singular and hyper-singular. The RMM uses a subtracting and adding-back technique to remove the singularities of Eqs.(6) and (7) [Young, Chen and Lee (2005)]. The diagonal elements of influence matrices can be derived from nullfield integral equations [Song and Chen (2009)] or the boundary integral equations (BIEs) [Sun, Chen and Zhang (2013)] at the domain point. The main results for 2D interior problems are summarized hereafter.

According to Ref. [Sun, Chen and Zhang (2013)], Eqs.(6) and (7) can be desingularized as follows:

$$u(\mathbf{x}^{i}) = \sum_{j=1, j \neq i}^{N} \alpha^{j} A^{(l)}(\mathbf{x}^{i}, \mathbf{s}^{j}) + \frac{\alpha^{i}}{l^{i}} \left(2\pi - \sum_{j=1, j \neq i}^{N} A^{(l)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right),$$
(12)

$$q(\mathbf{x}^{i}) = \sum_{j=1, j\neq i}^{N} \alpha^{j} B^{(l)}(\mathbf{x}^{i}, \mathbf{s}^{j}) - \frac{\alpha^{i}}{l^{i}} \left(\sum_{j=1, j\neq i}^{N} B^{(l)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right).$$
(13)

where l^{j} is half distance between the source points s^{j-1} and s^{j+1} , and can be obtained by numerical integration, for example, the 8-points Gaussian quadrature.

Then the diagonal elements of the RMM interpolation matrix for interior problems can be derived by

$$A^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{i}) = \frac{1}{l^{i}} \left(2\pi - \sum_{j=1, j \neq i}^{N} A^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right),$$
(14)

$$B^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{i}) = -\frac{1}{l^{i}} \left(\sum_{j=1, j \neq i}^{N} B^{(I)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right).$$
(15)

2.2 The RMM formulation for exterior problems

For exterior problems, the diagonal elements can be determined via null-field integral equations [Song and Chen (2009)]. Eqs.(10) and (11) can be regularized as follows:

$$u(\mathbf{x}^{i}) = \sum_{j=1, j\neq i}^{N} \alpha^{j} A^{(E)}(\mathbf{x}^{i}, \mathbf{s}^{j}) - \frac{\alpha^{i}}{l^{i}} \left(\sum_{j=1, j\neq i}^{N} A^{(E)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right),$$
(16)

$$q(\mathbf{x}^{i}) = \sum_{j=1, j\neq i}^{N} \alpha^{j} B^{(E)}(\mathbf{x}^{i}, \mathbf{s}^{j}) - \frac{\alpha^{i}}{l^{i}} \left(\sum_{j=1, j\neq i}^{N} B^{(E)}(\mathbf{x}^{i}, \mathbf{s}^{j}) l^{j} \right).$$
(17)

The diagonal elements of the RMM interpolation matrix for exterior problems can be obtained by

$$A^{(E)}(\boldsymbol{x}^{i}, \boldsymbol{s}^{i}) = -\frac{1}{l^{i}} \left(\sum_{j=1, j \neq i}^{N} A^{(E)}(\boldsymbol{x}^{i}, \boldsymbol{s}^{j}) l^{j} \right),$$
(18)

$$B^{(E)}(\boldsymbol{x}^{i}, \boldsymbol{s}^{i}) = -\frac{1}{l^{i}} \left(\sum_{j=1, j \neq i}^{N} B^{(E)}(\boldsymbol{x}^{i}, \boldsymbol{s}^{j}) l^{j} \right).$$
⁽¹⁹⁾

By collocating BCs from Dirichlet boundary Eq. (2) and Neumann boundary Eq. (3) at *N* observation points, the unknown coefficients $\{\alpha^j\}_{j=1}^N$ can be calculated by linear solvers.

A technique using the moment condition can be implemented in the RMM to remedy the wrong solution for the problem whose solution includes a constant potential [Chen, Fu and Wei (2009)]. The potential at the point y inside the domain is given by

$$u(\mathbf{y}) = \sum_{j=1}^{N} \alpha^{j} A(\mathbf{y}, \mathbf{x}^{j}) + c, \qquad (20)$$

with the constraint

$$\sum_{j=1}^{N} \alpha_j = 0. \tag{21}$$

where $x^j \in \Gamma$, $A(y, x^j) = A^{(I)}(y, x^j)$ and $A(y, x^j) = A^{(E)}(y, x^j)$ correspond to interior or exterior problems, respectively.

3 A sinh transformation for nearly singular kernels in the RMM

From mathematical point of views, the RMM is equivalent to the indirect BEM (IBEM) and can be derived from a discretization formulation of the IBEM via a quadrature rule, as shown below

$$u(\mathbf{y}) = \int_{\Gamma_x} \boldsymbol{\sigma}(\mathbf{x}) A(\mathbf{y}, \mathbf{x}) d\Gamma_x \approx \sum_{j=1}^N \alpha^j A(\mathbf{y}, \mathbf{x}^j), \qquad (22)$$

where $\sigma(\mathbf{x})$ denotes the unknown density function.

If the calculation point y is far away from the boundary, the numerical results by a straight forward application of the boundary integral equation(BIE) (22) will be sufficient to obtain accurate numerical results. However, if the calculation y moves

closer to the boundary, the distance function r approaches to zero. Consequently, the BIE (22) will present nearly singularity. From the mathematical point of view, the integrand remains regular because it is finite at all points. However, instead of being smooth, the integrand may have a finite but very large gradient as the calculation point gets closer to the boundary. The whole integral, therefore, cannot accurately be calculated using the standard Gauss-quadrature. As a result, the RMM-expansion fails to yield reliable results nearby boundary.

As shown in Fig.2, we assume the calculation point y is close to the boundary Γ_k containing the point x^k , then Eq. (22) can be rewritten as

$$u(\mathbf{y}) = \sum_{j=1, j \neq k}^{N} \alpha^{j} A(\mathbf{y}, \mathbf{x}^{j}) + \alpha^{k} u^{k},$$
(23)

where u^k is defined as the nearly singular factor, which should be evaluated via special treatments. In this work, the nearly singular factor u^k is directly calculated as an average value of the kernel functions over Γ_k by

$$u^{k} = \frac{1}{l^{k}} \int_{\Gamma_{k}} A(\mathbf{y}, \mathbf{x}) d\Gamma_{k}(\mathbf{x})$$
(24)

where l^k is half distance between the source nodes \mathbf{x}^{k-1} and \mathbf{x}^{k+1} (see Fig.2).



Figure 2: A field point near the boundary.

In order to numerically calculate the above integral equation (24), the integral can be transformed and mapped onto the interval [1, 1] in terms of some intrinsic coordinate ξ . If a quadratic boundary element is used, Eq. (24) can be rewritten as follows [Gu, Chen and Zhang (2013)]

$$u^{k} = \frac{1}{l^{k}} \int_{\Gamma_{k}} \frac{f(\mathbf{x})}{r^{2}} d\Gamma_{k}(\mathbf{x}) = \frac{1}{l^{k}} \int_{-1}^{1} \frac{f(\xi)J(\xi)}{(\xi - \eta)^{2}g(\xi) + b^{2}} d\xi$$
(25)

where $\eta \in [-1,1]$ stands for the position of the projection of the field point onto the element (see Fig.2), *b* represents the shortest distance from the field point to the element, $g(\xi)$ is a low order and non-negative polynomial, $J(\xi)$ represents the Jacobian of the transformation from the quadratic boundary element to the interval [1, 1], $f(\cdot)$ is a low-order polynomial which is a part of the kernel function. Further details can be found in Ref. [Gu, Chen and Zhang (2013)].

Due to the peaked nature of the integral, the above integral is difficult to numerically evaluate as $b \rightarrow 0$. To improve the accuracy of the numerical results in the RMM, a sinh transformation [Gu, Chen and Zhang (2013)] is used in this study

$$\xi = \eta + b \sinh(k_1 t - k_2), \tag{26}$$

where

$$k_1 = \frac{1}{2} \left\{ \operatorname{arcsinh}\left(\frac{1+\eta}{b}\right) + \operatorname{arcsinh}\left(\frac{1-\eta}{b}\right) \right\},\tag{27}$$

$$k_1 = \frac{1}{2} \left\{ \operatorname{arcsinh}\left(\frac{1+\eta}{b}\right) - \operatorname{arcsinh}\left(\frac{1-\eta}{b}\right) \right\}.$$
 (28)

Then, the integral is changed as

$$u^{k} = \frac{k_{1}}{l^{k}b} \int_{-1}^{1} \frac{f(t)J(t)\cosh(k_{1}t - k_{2})}{\sinh^{2}(k_{1}t - k_{2})g(t) + 1} dt,$$
(29)

As mentioned above, g(t) is a non-negative function, and thus the function $\sinh^2(k_1t - k_2)g(t) + 1$ in Eq.(29) is always greater than 1. Thus, an oscillating integrand is smoothed, and can now be accurately evaluated via the standard Gaussian quadrature, even if the value of *b*, distance between boundary source and inner collocation points, is very small.

4 Numerical examples and discussions

To verify the scheme developed above, three 2D potential problems are investigated in this section. The numerical results will be compared with exact solutions by the relative error defined below

Relative error =
$$\left[\frac{1}{M}\sum_{k=1}^{M} \left(\frac{I_{numerical}^{k} - I_{exact}^{k}}{I_{exact}^{k}}\right)^{2}\right]^{1/2},$$
(30)

where $I_{numerical}^{k}$ and I_{exact}^{k} represent the numerical and analytical solutions at the k^{th} calculation point, respectively.

4.1 Interior Dirichlet problem with gear wheel domains

First, we consider a bounded domain with gear wheel shape which is defined by

$$\Gamma = \left\{ (r\cos\theta, r\sin\theta) : r = \frac{1}{9} \left[17 - 8\cos(3\theta) \right], \quad 0 \le \theta \le 2\pi \right\}.$$
(31)

Problem sketch and the nodes distribution are depicted in Fig.3. The analytical solution is given by the global function

$$u(x_1, x_2) = e^{x_1} \cos x_2 + x_1, \tag{32}$$

For the numerical implantation, N=1000 source points are selected on the boundary. Tab.1 and 2 list the potential results at calculation points A and B in terms of the function of distance b from the boundary. The results using the original RMM are also given for a fair comparison.

As shown in Tab.1 and 2, when the calculation point A and B are not very close to the boundary, the original RMM can obtain accurate results. However, if A and B get closer to the boundary, i.e., when the distance b is less than 1.0E-1, the RMM performs less accurate or even inaccurate. In contrast, results using the present transformed RMM are accurate and stable, even when the distance b is as small as 1.0E-6. This clearly shows that the transformed RMM performs much better than the original RMM in near-boundary regions.

Fig.4 shows the relative error curves of the potentials at point A and B with b=1.0E-6, against the number of boundary nodes. As illustrated in this figure, the transformed RMM converges quickly with an increasing number of boundary nodes even when the distance from the field point to the boundary is as small as 1.0E-6.

b	Exact	Original	Relative	Transformed	Relative error
		RMM	error	RMM	
0.5	2.1487	2.1490	1.2965e-04	2.1490	1.2196e-04
1.0E-1	3.3596	3.3609	3.7753e-04	3.3607	3.2483e-04
1.0E-2	3.6812	3.6851	1.0001e-03	3.6298	1.3978e-02
1.0E-3	3.7146	13.0602	2.5159e+00	3.4582	6.9020e-02
1.0E-4	3.7179	1.5558e+02	4.0845e+01	3.6888	7.8212e-03
1.0E-5	3.7182	1.5923e+03	4.2724e+02	3.7149	8.9817e-04
1.0E-6	3.7183	1.5961e+04	4.2915e+03	3.7175	2.0483e-04

Table 1: Results of potential u at the calculation point A

b	Exact	Original	Relative	Transformed	Relative error
		RMM	error	RMM	
0.5	-	-2.1753	1.2549e-06	-2.1753	1.9806e-06
	2.1753				
1.0E-1	-	-2.6091	2.7271e-05	-2.6088	1.0571e-04
	2.6091				
1.0E-2	-	-2.8718	6.1674e-02	-2.5760	4.7692e-02
	2.7050				
1.0E-3	-	-16.7623	5.1750e+00	-2.6756	1.4337e-02
	2.7145				
1.0E-4	-	-168.9075	6.1201e+01	-2.7115	1.4559e-03
	2.7155				
1.0E-5	-	-	6.2206e+02	-2.7152	1.5497e-04
	2.7156	1.6920e+03			
1.0E-6	-	-	6.2307e+03	-2.7139	6.3903e-04
	2.7156	1.6923e+04			

Table 2: Results of potential u at the calculation point B.



Figure 3: A bounded domain with gear wheel boundary shape.



Figure 4: Relative error curves of the transformed RMM.

4.2 Exterior Dirichlet problem with amoeba-like domain

Next, we consider an infinite domain with amoeba-like shape which is defined by

$$\Gamma = \left\{ (r\cos\theta, r\sin\theta) : r = e^{\sin\theta}\sin^2(2\theta) + e^{\cos\theta}\cos^2(2\theta), \quad 0 \le \theta \le 2\pi \right\}.$$
(33)

Figure 4 shows the profile of the ameba-like shape boundary and the distribution of the source points. The symbols \cdot and + represent the source points and computed points, respectively.

The exact solution is given by

$$u(x_1, x_2) = e^{x_1/x_1^2 + x_2^2} \cos\left(\frac{x_1}{x_1^2 + x_2^2}\right)$$
(34)

To solve the problem numerically, N=1000 source points are placed on the boundary. The numerical solution accuracies are examined on a total of M=90 calculation points with the off-boundary distance b, as shown in Fig. 5.

The relative error curves of the original and transformed RMMs are given in Fig.6 as functions of the off-boundary distance b. We can observe from Fig.6 that the transformation technique increases a large degree of the accuracy near boundary solutions. It also illustrates that the relative errors decrease greatly, when the field point is far from the boundary, because the peak of integrand is becoming smooth.



Figure 5: The profile of an infinite domain with amoeba-like boundary shape.



Figure 6: Relative error curves of potentials at interior points near the boundary using the transformed RMM and original RMM.

4.3 Multiply-connected domain with mixed boundary conditions

Finally, consider a multiply-connected domain problem. The shape of the domain and the nodes distribution are depicted in Fig.7. The symbols \cdot and+represent source points and computation points, respectively. The boundary Γ is composed of the outer curve Γ_1 and the two inner curves $\Gamma_2 \cup \Gamma_3$ as

$$\Gamma_1 = \left\{ (r\cos\theta, r\sin\theta) : r = \sqrt{82 - 18\cos(8\theta)}, \quad 0 \le \theta \le 2\pi \right\},\tag{35}$$

$$\Gamma_2 = \{ (r\cos\theta, r\sin\theta) : r = 1 \}, \tag{36}$$

$$\Gamma_3 = \{ (r\cos\theta + 4, r\sin\theta) : r = 0.5 \},$$
(37)

The mixed boundary conditions are given by

$$\begin{cases} u(x_1, x_2) = \sin x_1 \cosh x_2 & (x_1, x_2) \in \Gamma_1, \\ \frac{\partial u(x_1, x_2)}{\partial n} = \cos x_1 \cosh x_2 n_{x_1} + \cos x_1 \cosh x_2 n_{x_2} & (x_1, x_2) \in \Gamma_2 \cup \Gamma_3, \end{cases}$$
(38)

where (n_{x_1}, n_{x_2}) is a unit normal vector, and the analytical solution is given by $u(x_1, x_2) = \sin x_1 \cosh x_2$.



Figure 7: Multiply-connected domain with mixed boundary conditions.

Taking N=800, 80 and 40 source points on the outer boundary and two inner boundary, respectively. Selecting the same number of calculation points distributed inside the domain near the physical boundaries, whose distance *b* to the physical boundary varies from 0.5 to 1.0E-6. Fig. 8 shows the relative error curves of potential results at the calculation points as functions of various values of *b*.



Figure 8: Relative error curves of the potentials at interior points near the boundary using the transformed RMM and original RMM.

As shown in Fig.8, when the distance b is greater than 0.1, the results of the original RMM and the transformed RMM are both accurate. However, when the calculation points get closer to the boundary, the original RMM tends less accurate and stable. In stark contrast, the results using the proposed method remain accurate and numerically stable. It is also noting that when the distance to the boundary researches 1.0E-6, application of the transformation yields an improvement in relative error by about six orders of magnitude. As in the previous examples, the relative error of the proposed scheme is generally independent of the distance b from the boundary.

5 Conclusions

This paper introduces an efficient transformation technique to circumvent the boundary layer effect associated with the RMM formulation. Compared with a straight forward implementation of the original RMM, the present transformed RMM produces an improvement in terms of relative error by several orders of magnitude. In general, the accuracy of the present RMM is less sensitive to the location of the nearly singular point and the distance between the field point and the boundary. The numerical experiments verify that accurate and stable results can be obtained using the proposed strategy even when the distance between the calculation point and the boundary is as small as1.0E-6. It is also observed from the foregoing numerical experiments that the proposed scheme performs numerically stable and its accuracy is largely independent of the distance from the calculated point to the boundary.

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