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A Cooperated Imperialist Competitive Algorithm for Unrelated Parallel Batch Machine Scheduling Problem

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ABSTRACT

This study focuses on the scheduling problem of unrelated parallel batch processing machines (BPM) with release times, a scenario derived from the moulding process in a foundry. In this process, a batch is initially formed, placed in a sandbox, and then the sandbox is positioned on a BPM for moulding. The complexity of the scheduling problem increases due to the consideration of BPM capacity and sandbox volume. To minimize the makespan, a new cooperated imperialist competitive algorithm (CICA) is introduced. In CICA, the number of empires is not a parameter, and four empires are maintained throughout the search process. Two types of assimilations are achieved: The strongest and weakest empires cooperate in their assimilation, while the remaining two empires, having a close normalization total cost, combine in their assimilation. A new form of imperialist competition is proposed to prevent insufficient competition, and the unique features of the problem are effectively utilized. Computational experiments are conducted across several instances, and a significant amount of experimental results show that the new strategies of CICA are effective, indicating promising advantages for the considered BPM scheduling problems.

KEYWORDS

Release time; assimilation; imperialist competitive algorithm; batch processing machines scheduling

1 Introduction

Unlike traditional scheduling, batch processing machines (BPM) scheduling consists of at least one BPM, and on BPM all jobs in a batch are processed simultaneously after the batch is formed. BPM scheduling problems widely exist in many real-life industries such as casting, chemical engineering, semiconductors, transportation, etc. BPM can be divided into parallel BPM and serial BPM, the processing time of a batch on the former is defined as the maximum processing time of all jobs in the batch, and the processing time of a batch on the latter is defined as the sum of processing time of all jobs in the batch. BPM scheduling problems can be divided into single BPM scheduling, parallel machine scheduling, and hybrid flow shop scheduling with BPM, etc., which have received extensive attention.

There are some works about single BPM scheduling problem, in which all batches are processed by a BPM. Uzsoy [1] first studied the problem with job size, proved that it is NP-hard, and proposed a heuristic algorithm to minimize makespan and total completion time. Lee [2] presented a polynomial



algorithm and pseudo-polynomial-time algorithm to solve the problem with dynamic job arrivals. Melouk et al. [3] solved the problem with job sizes by a simulated annealing algorithm. Zhou et al. [4] considered the problem with unequal release times and job sizes and proposed a self-adaptive differential evolution algorithm with adaptively chosen mutation operators based on their historical performances to minimize makespan. Yu et al. [5] proposed a branch-and-price algorithm to solve additive manufacturing problems with the minimization of makespan. Zhang et al. [6] presented two heuristics to minimize total weighted earliness and tardiness penalties of jobs.

The parallel BPM scheduling problem has attracted much attention. Regarding the uniform parallel BPM scheduling problem, some results are obtained. Xu et al. [7] presented a Pareto-based ant colony system to simultaneously minimize makespan and maximum tardiness. Jiang et al. [8] presented a hybrid algorithm with discrete particle swarm optimization and genetic algorithm (GA), in which a heuristic and a local-search strategy are introduced. Zhang et al. [9] proposed a multi-objective artificial bee colony (ABC) to solve the problem of machine eligibility in fabric dyeing process. Jia et al. [10] proposed a fuzzy ant colony optimization (ACO) for the problem with fuzzy processing time. Liu et al. [11] designed a GA and a fast heuristic for the problem in coke production. Jia et al. [12] applied two heuristics and an ACO for the problem with arbitrary capacities. Li et al. [13] developed a discrete bi-objective evolutionary algorithm to minimize maximum lateness and total pollution emission cost. Xin et al. [14] developed an efficient 2-approximation algorithm for the problem with different BPM capacities and arbitrary job sizes.

A number of works have been obtained on unrelated parallel BPM scheduling problems. Arroyo et al. [15] proposed an effective iterated greedy for the problem with non-identical capacities and unequal ready times. Lu et al. [16] presented a hybrid ABC with tabu search to minimize the makespan of the problem with maintenance and deteriorating jobs. Zhou et al. [17] provided a random key GA for the problem with different capacities and arbitrary job sizes. Zhang et al. [18] proposed an improved evolutionary algorithm by combining a GA with a heuristic placement strategy for the problem in additive manufacturing. Kong et al. [19] applied a shuffled frog-leaping algorithm with variable neighborhood search for the problem with nonlinear processing time. Song et al. [20] developed a self-adaptive multi-objective differential evolution algorithm to minimize total energy consumption and makespan. Zhang et al. [21] formulated a mixed-integer programming (MIP) model and presented an improved particle swarm optimization algorithm for the problem with production and delivery in cloud manufacturing. Fallahi et al. [22] studied the problem in production systems under carbon reduction policies and used non-dominated sorting genetic algorithm-II and multi-objective gray wolf optimizer to simultaneously minimize makespan and total cost. Xiao et al. [23] proposed a tabu-based adaptive large neighborhood search algorithm for the problem with job sizes, ready times, and the minimization of makespan. Zhang et al. [24] provided a MIP model and a modified elite ant system with local search (MEASL) to minimize the total completion time of the problem with release times, and job sizes. Jiang et al. [25] applied an iterated greedy (IG) algorithm for the problem of release times, job sizes, and incompatible job families. Ji et al. [26] developed a hybrid large neighborhood search (HLNS) with a tabu strategy and local search to solve the problem with job sizes, ready times, and incompatible family. Ou et al. [27] presented an efficient polynomial time approximation scheme with near-linear-time complexity to solve the problem with dynamic arrivals job and rejection.

As stated above, the existing works on single BPM scheduling and parallel BPM scheduling are mainly about job sizes, incompatible family, and BPM capacity constraints, that is, the sum of the weight of all jobs in a batch cannot exceed the prefixed capacity, parallel BPM scheduling problems are handled in actual production processes like coke production, fabric dyeing, and additive

manufacturing, which are close to the real situation of manufacturing process and their optimization results have high application values; however, parallel BPM scheduling problems with more constraints are not studied fully. For example, in the moulding process of a foundry [28,29], a batch is first allocated into a sandbox and then the sandbox is added to the assignment machine of the batch, for each batch, has to meet sandbox volume constraint and machine capacity constraint, and complexity of the problem increases. This is a challenge in moulding process in a foundry. On the other hand, release times of all jobs are mostly different in unrelated parallel BPM scheduling problems [24,25], release times have a positive impact on the performance of the schedule and are a frequently considered real-life condition, which also exist in moulding process, so it is necessary to deal with parallel BPM scheduling problem with sandbox volume constraint and release times.

The imperialist competitive algorithm (ICA) is an intelligent optimization algorithm inspired by social and political behavior [30]. Each intelligent optimization algorithm has its own advantages [31–34]. ICA has many notable features such as good neighborhood search ability, effective global search property, good convergence rate, and flexible structure [35]. As the main method of production scheduling [36–40], ICA has been successfully applied to solve parallel machine scheduling problem (PMSP) [41–45]. Lei et al. [37] proposed an ICA with a novel assimilation strategy to deal with low-carbon PMSP. Yadani et al. [46] developed a hybrid ICA for PMSP with two-agent and tool change activities. The good searchability and advantages of ICA in solving PMSP are tested and proven. The parallel BPM scheduling problem is the extended PMSP and the same coding can be used in these two problems. The successful applications of ICA to PMSP reveal that ICA has potential advantages in solving parallel BPM scheduling, so ICA is used.

In this study, an unrelated parallel BPM scheduling problem with release times is considered, which is refined from moulding process of a foundry, and a cooperated imperialist competitive algorithm (CICA) is presented to minimize makespan. To produce high-quality solutions, the number of empires is not used as a parameter and four empires always exist throughout the search process, cooperation between the strongest empire and the weakest empire is applied in the assimilation of these two empires, and a combination of the two remaining empires is used in the assimilation of these two empires. A new imperialist competition is given. Extensive experiments are conducted and the computational results demonstrate that new strategies of CICA are effective and that CICA has promising advantages on considered problems.

The remainder of the paper is organized as follows. The problem description is described in Section 2. Section 3 shows the proposed CICA for unrelated parallel BPM scheduling problems with the release times stage. Numerical test experiments on CICA are reported in Section 4. Conclusions and some topics of future research are given in the final section.

2 Problem Description

Unrelated parallel BPM scheduling problem in moulding process of a foundry is described as follows. n jobs J_1, J_2, \dots, J_n are processed by m parallel BPM M_1, M_2, \dots, M_m , r_i indicates release times of J_i , p_{ik} denotes processing time of J_i on machine M_k . All jobs are divided into l families according to materials. Each material corresponds to a job family and jobs of different families cannot be grouped into a batch. $f_i \in \{1, 2, \dots, l\}$ indicates the family of job J_i , J_i has weight w_i and volume v_i . There are sufficient sandbox and all sandboxes have the same volume V , all machines are given the same capacity W . Each batch is placed in a sandbox and then sandbox is placed in BPM for moulding, so two constraints are required to be satisfied for each batch: Total volume of all jobs in the batch cannot exceed V and total weight of all jobs in the batch cannot exceed W . Processing time of a batch

is maximum processing time of all jobs in the batch. Release time of a batch is maximum release time of job in the batch.

There are some constraints on jobs and machines:

Each BPM can only handle one batch at a time.

No job can be processed in different batches on more than one BPM.

Operations cannot be interrupted.

The problem has three sub-problems: (1) batch formation for deciding which jobs used to form each batch, (2) BPM assignment for choosing a BPM for each batch, (3) batch scheduling for determining processing sequence of all batches on each machine. There are strong coupled relations among them. Batch formation decides directly the optimization content of other two sub-problems and optima solution of the problem can be obtained by comprehensive coordination of three sub-problems.

The goal of problem is to minimize makespan under the condition that all constraints are met.

$$C_{\max} = \max_{i=1,2,\dots,n} C_i \quad (1)$$

where C_i is completion time of J_i , C_{\max} indicates maximum completion time of all jobs.

Table 1 shows an example with 12 jobs, 3 families and 3 parallel BPMs, $W = 10$, $V = 10$. A schedule of the example is shown in Fig. 1.

Table 1: Processing data of the example

J_i	w_i	v_i	f_i	r_i	p_{i1}	p_{i2}	p_{i3}
J_1	4	5	1	2	2	3	4
J_2	2	1	2	4	3	6	4
J_3	2	2	1	5	1	3	2
J_4	3	4	2	3	3	2	4
J_5	2	5	1	7	5	3	5
J_6	8	10	3	1	2	4	3
J_7	9	1	3	3	4	2	3
J_8	5	5	1	1	6	5	2
J_9	1	7	3	4	6	7	4
J_{10}	5	4	2	3	5	3	3
J_{11}	9	5	1	1	3	2	7
J_{12}	4	7	2	0	3	6	5

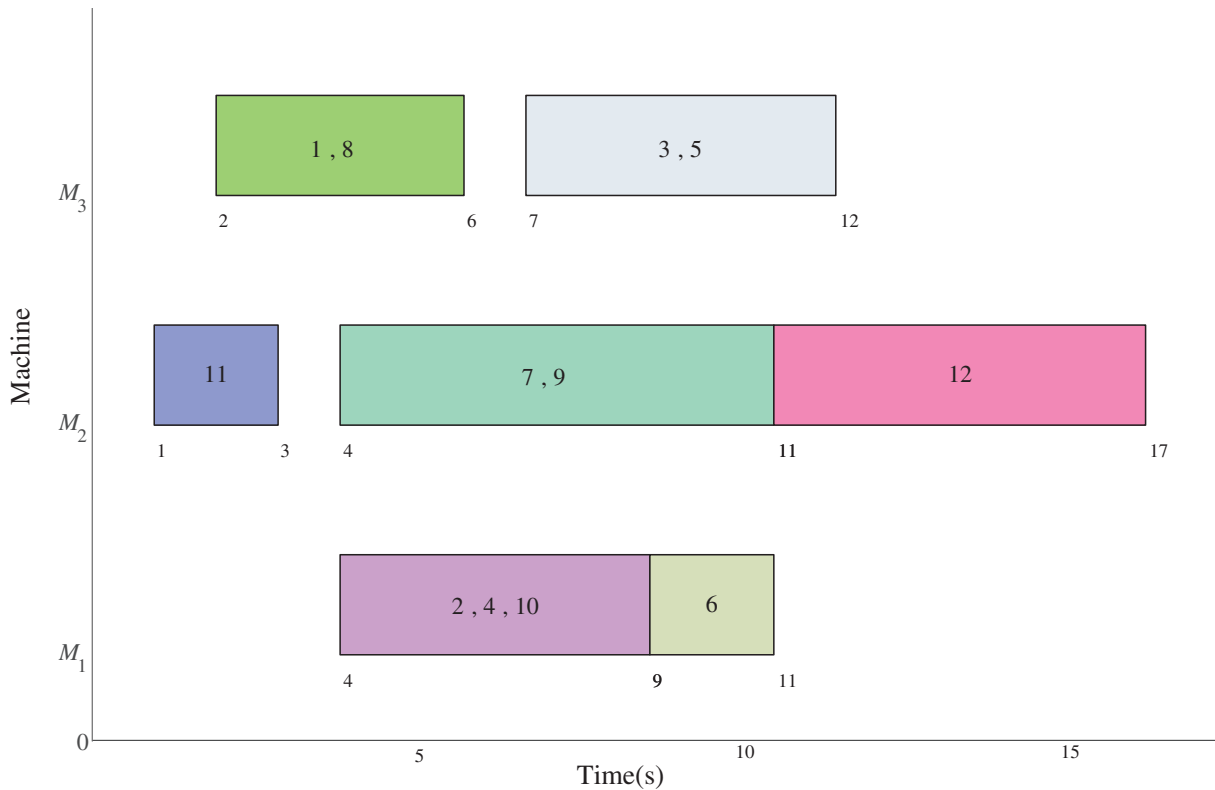


Figure 1: A schedule of the example

3 CICA for Parallel BPM Scheduling

In the existing ICAs [30,35], there are N_{im} initial empires and N_{im} is used as parameter. In this study, CICA is proposed, in which N_{im} is not a parameter and set to be 4 in the whole search process, then assimilation based on cooperation between two empires and assimilation with empire combination are implemented respectively and a new imperialist competition is given. The detailed steps of CICA are shown below.

3.1 Initialization and Formation of Four Empires

Lei et al. [47] presented a two-string representation to describe solution of unrelated PMSP, which can be directly used to describe solution of unrelated parallel BPM scheduling problem. For the problem with n jobs and m BPM, its solution is represented as a scheduling string $[\pi_1, \pi_2, \dots, \pi_n]$, and a machine assignment string $[\theta_1, \theta_2, \dots, \theta_n]$, where $\pi_i \in \{1, 2, \dots, n\}$, $\theta_i \in \{1, 2, \dots, m\}$.

There are some differences of the above method from coding method [47]: Scheduling string is a permutation of all jobs, machine assignment string is used for all batches, the number η of batches is determined by batch formation. Usually, $\eta < n$, so only the first η elements of machine assignment string are used in decoding.

The decoding procedure is described below:

Step 1: Let $k = 1, b\text{-th} = 1, WB_{b\text{-th}} = 0, VB_{b\text{-th}} = 0$, let $B_{b\text{-th}}$ be empty. Each job J_i is assigned a $mark_i$, if job is not in a batch, $mark_i = 0$, otherwise $mark_i = 1$.

Step 2: Repeat the following steps until each job is assigned into a batch.

1) choose first job π_b with $mark_{\pi_b} = 0$ and the first machine M_{θ_k} from machine assignment string, then $B_{b-th} = B_{b-th} \cup \{J_{\pi_b}\}$, $mark_{\pi_b} = 1$, $WB_{b-th} = w_{\pi_b} + WB_{b-th}$, $VB_{b-th} = v_{\pi_b} + VB_{b-th}$.

2) repeat the following steps until no job π_c can be chosen or $WB_{b-th} + w_{\pi_c} > W$ or $VB_{b-th} + v_{\pi_c} > V$: Choose a job π_c with $mark_{\pi_c} = 0$ and $f_{\pi_c} = f_{\pi_b}$ from scheduling string, if $WB_{b-th} + w_{\pi_c} < W$, $VB_{b-th} + v_{\pi_c} < V$, then $B_{b-th} = B_{b-th} \cup \{J_{\pi_c}\}$, $mark_{\pi_c} = 1$, $WB_{b-th} = w_{\pi_c} + WB_{b-th}$, $VB_{b-th} = v_{\pi_c} + VB_{b-th}$.

3) Obtain batch B_{b-th} , $b-th = b-th + 1$, let B_{b-th} be empty, $WB_{b-th} = 0$, $VB_{b-th} = 0$, $k = k + 1$.

Step 3: η batches are finally formed and processed sequentially in terms of B_1, B_2, \dots, B_η .

Where WB_{b-th} and VB_{b-th} are total weight of all jobs and total volume of all jobs in batch B_{b-th} .

For the example in Table 1, a solution is scheduling string [8, 2, 6, 4, 11, 1, 10, 9, 5, 12, 7, 3] and machine as-signment string [3, 1, 1, 2, 2, 3, 2, 3, 1, 2, 1, 3]. The corresponding schedule is shown in Fig. 1. Job J_8 is chosen first, $B_1 = \{J_8\}$, $WB_1 = 5$, $VB_1 = 5$, then find a job J_1 with the same family with J_8 , $WB_1 + w_1 = 9$, $VB_1 + v_1 = 10$, $B_1 = \{J_8, J_1\}$. When job J_3 is considered, sandbox volume constraint is violated, so $B_1 = \{J_8, J_1\}$. Other batches are obtained in the same way. $B_2 = \{J_2, J_4, J_{10}\}$, $B_3 = \{J_6\}$, $B_4 = \{J_{11}\}$, $B_5 = \{J_9, J_7\}$, $B_6 = \{J_5, J_3\}$. On M_1 , processing sequence of B_1, B_6 . The processing sequence on M_2 and M_3 are B_4, B_5, B_7 and B_2, B_3 , respectively. C_{max} is 17.

An initial population P with N solutions are randomly generated, then four initial empires are constructed based on initial population P .

Four initial empires are constructed in the following way:

Step 1: Calculate cost $c_i = C_{max}^{x_i}$ of each solution $x_i \in P$, sort all solutions in P in ascending order of cost.

Step 2: Choose four solutions with lowest cost as imperialists, which are IM_1, IM_2, IM_3, IM_4 , and calculate normalized cost \bar{c}_k of IM_k , pow_k and $NC_k = round(N_{col} \times pow_k)$.

Step 3: Randomly allocate NC_k colonies for each imperialist k .

Where $round(x)$ is a function that gives the nearest integer of x , $N_{col} = N - 4$ denotes total number of colonies. $pow_k = \bar{c}_k / \sum_{i=1}^4 c_i$ is power of imperialist k , NC_k indicates the number of colonies in empire k .

Normalized cost \bar{c}_k of IM_k is usually defined as $\bar{c}_k = \max_l \{c_l\} - c_k$, so at least one imperialist has $\bar{c}_k = 0$, $pow_k = 0$ and no allocated colonies and the corresponding empire will have no colony, as a result, assimilation and revolution cannot be done in the empire, \bar{c}_k is defined to avoid the above case:

$$\bar{c}_k = 2 \times \max_l \{c_l\} - c_k \quad (2)$$

\overline{TC}_k of empire k is defined and four empires are sorted in the descending order of \overline{TC}_k , suppose $\overline{TC}_1 \geq \overline{TC}_2 \geq \overline{TC}_3 \geq \overline{TC}_4$, the strongest empire is empire 1, empire 4 is the weakest empire, empires 2,3 have close normalization total cost.

$$\overline{TC}_k = \bar{c}_k + \xi \sum_{\lambda \in T_k} \frac{\bar{c}_\lambda}{NC_k}, k = 1, 2, 3, 4. \quad (3)$$

where T_k is set of colonies possessed by imperialist k and ξ is real number, $\xi = 0.1$.

3.2 Assimilation and Revolution

Unlike the previous ICAs [30,35], CICA has new implementation way for assimilation. In CICA, assimilations of empires 1,4 are executed together based on their cooperation because there has greater difference on their normalization total cost, empires 2,3 have close normalization total cost, when their assimilations are done, they are first merged and assimilation is conducted for the merged empire. N_{im} is fixed to be 4 to achieve the above two kinds of assimilations; moreover, imperialist competition will be simplified.

Cooperation-based assimilation of empires 1,4 is shown as follows:

Step 1: Sort all colonies in empire 1 in the ascending order of c_i , decide the first α colonies including the best colony $\lambda^* \in T_1$, determine the best α colonies of empire 4 using the same approach and include them into a set Λ , $\tau = 1$.

Step 2: Repeat the following steps until $\tau > \alpha$: Choose the τ -th colony $\lambda \in T_1$ and the τ -th colony $\bar{\lambda} \in T_4$ execute global search between $\lambda, \bar{\lambda}$, a new solution z is obtained, if C_{max}^z less than one of $C_{max}^\lambda, C_{max}^{\bar{\lambda}}$, suppose $C_{max}^z < C_{max}^\lambda$, then update the set θ with λ and let z substitute for λ ; if $C_{max}^z < C_{max}^{\bar{\lambda}}$ and $C_{max}^z < C_{max}^\lambda$, then update the set θ with the worse one of $\lambda, \bar{\lambda}$ and let z substitute for the worse one of $\lambda, \bar{\lambda}$.

Step 3: For each colony $\lambda \in \Lambda$, execute global search between λ and $\lambda^* \in T_1$, a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then update the set θ with λ and let z substitute for λ . If $C_{max}^z \geq C_{max}^\lambda$, then conduct global search between λ and IM_1 , a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then update the set θ with λ and replace λ with z .

Step 4: Choose the best colony in Λ , if it better than IM_4 , then exchange it with IM_4 .

Step 5: For each colony $\lambda \in T_1 \setminus \{\lambda^*\}$, conduct global search between λ and λ^* , a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then update θ with λ and replace λ with z ; else, execute global search between λ and IM_1 , a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then update the set θ with λ and replace λ with z .

Step 6: For each colony $\lambda \in T_4 \setminus \Lambda$, choose a $\bar{\lambda} \in \Lambda \cup \{IM_4\}$, by using roulette selection, execute global search between λ and $\bar{\lambda}$, a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then update the set θ with λ and let z substitute for λ .

Where selection probability of each solution x_i is $(\sum_{y \in \Lambda \cup \{IM_4\}} C_{max}^y - C_{max}^{x_i}) / \sum_{y \in \Lambda \cup \{IM_4\}} C_{max}^y$ for roulette selection.

After the best α colonies of empires 1, 4 are decided respectively, then cooperation is conducted by global search on α pairs of the decided best colonies $\lambda \in T_1, \bar{\lambda} \in T_4$ in step 2, and the usage of the best colony $\lambda^* \in T_1$ or IM_1 for improving solution quality of the best α colonies of empire 4 in step 3.

Empires 2,3 have close $\overline{TC}_2, \overline{TC}_3$ and there are high similarity between them, to avoid the waste of computing resource on the worst solutions, empires 2,3 are first combined into a new empire D , assimilation is done on all colonies of D except Q the chosen worst solutions in D .

Combination-based assimilation in empires 2,3 is described below:

Step 1: Obtain temporary empire D by combining empires 2,3 together, imperialists of empire D are defined as IM_2 and IM_3 , choose Q colonies with the biggest cost, let Θ be a set of these colonies.

Step 2: For each colony $\lambda \in D \setminus \Theta$, select one imperialist from IM_2 and IM_3 by roulette selection, suppose IM_2 is selected, execute global search between λ and IM_2 , a new solution z is obtained, if $C_{max}^z < C_{max}^\lambda$, then if λ is one of Q colonies of D with the lowest cost, then random select colony $\bar{\lambda} \in \Theta$,

update θ with $\bar{\lambda}$, replace λ with z ; if λ is not one of the best Q colonies in D , then conduct multiple neighborhood search on colony λ , random select colony $\bar{\lambda} \in \Theta$, update θ with $\bar{\lambda}$, replace λ with z .

Step 3: Assign all solutions of D into their original empire.

where roulette selection is done, $\{IM_2, IM_3\}$ substitutes for $\Lambda \cup \{IM_4\}$.

The set θ is used to retain historical optimization data in the search process. The process of updating θ with solution x is shown as follows: If the number of solutions in θ is than its maximum size I , then the worst solution is eliminated and x is added to θ if x is better than the worst solution in θ , otherwise, x is added to θ .

Global search is described below: For solutions x and y , if $rand \leq 0.5$, order crossover [48] is executed for scheduling strings of x , y , otherwise, two-point crossover [40] is performed between machine assign-ent string of x and y . Where $rand$ is random number following uniform distribution on $[0,1]$.

5 neighborhood structures are applied, \mathcal{N}_1 is used to swap two randomly selected π_{k_1} and π_{k_2} . \mathcal{N}_2 is swap operator on machine assignment string and applied to swap two randomly selected θ_{k_1} and θ_{k_2} , $k_1, k_2 < \eta$. \mathcal{N}_3 is shown as follows: Decide machine M_{k_1} with smallest completion time and M_{k_2} with the biggest completion time, randomly choose $\theta_{i_1} = k_1$ and $\theta_{i_2} = k_2$, $i_1, i_2 \leq \eta$ and swap $\theta_{i_1}, \theta_{i_2}$. \mathcal{N}_4 is executed in the following way: Choose machine M_{k_1} with biggest completion time, randomly select $\theta_i = k_1, i \leq \eta$, randomly choose M_{k_2} , let $\theta_i = k_2$. \mathcal{N}_5 is described as follows: Decide all jobs on a machine with biggest completion time in scheduling string, and sort these jobs in ascending order of release times.

Multiple neighborhood search is below: Let $\vartheta = 1$, repeat the following steps until $\vartheta = 5$: a new solution $z \in \mathcal{N}_\vartheta(x)$ is obtained, if $C_{\max}^z < C_{\max}^x$, then update θ with x , replace x with z , $\vartheta = \vartheta + 1$. Where $\mathcal{N}_\vartheta(x)$ is denotes neighborhood solution set of solution x by using \mathcal{N}_ϑ .

When N_{im} is fixed to be 4, empires 1, 4 with bigger differences on \overline{TC}_k can be easily obtained, cooperation between them can be done and global search ability can be enhanced; meanwhile, empires 2,3 will have close normalized total cost and the search in empire 2 is similar with the search in empire 3 and the waste of computing resource will occur on some worst solutions twice. When the above assimilation is done on empires 2,3, the waste of computing resource will diminish greatly, thus, it can be found that the usage of four empires is appropriate, so N_{im} is not parameter in CICA and always equal to 4.

Revolution of empire k is conducted in the following way:

Step 1: Determine the number δ of colonies in empire k according to revolution probability R .

Step 2: Sort all colonies of empire k in ascending order of cost and decide δ colonies with the smallest cost, then for each decided colony λ , perform multiple neighborhood on colony λ , a new solution z is obtained, if $C_{\max}^z < C_{\max}^\lambda$, then replace the worst colony in T_k with λ , replace λ with z ; otherwise, if solution z is better than the worst colony of T_k , replace the worst colony of T_k with z .

3.3 Algorithm Description

As stated above, CICA is made up of initialization, formation of four empires, assimilation, revolution and imperialist competition.

Its detailed steps of CICA are shown below:

Step 1: Randomly produce initial population P and construct four initial empires.

Step 2: While the stopping condition is not met, **do**

Sort four empires in the descending order of \overline{TC}_k .

Execute assimilation in empires 1,4.

Perform assimilation in empires 2,3.

Execute revolution.

Apply imperialist competition.

End While

Only four empires are used and exist in the whole search process, so a new imperialist competition is given to adapt this new situation.

The new imperialist competition is described as follows:

1) Calculate \overline{TC}_k and $EP_k, k = 1, 2, 3, 4$, construct vector $[EP_1 - rand, EP_2 - rand, EP_3 - rand, EP_4 - rand]$, choose empire g with the biggest $EP_g - rand$ as winning empire. Suppose $g = 1$.

2) Choose I colonies with the lowest cost in empire g , for each chosen colony λ , execute global search between λ and IM_g , a new solution z is obtained, if $C_{\max}^z < C_{\max}^\lambda$, then update θ with λ and replace λ with z , then execute multiple neighborhood search on colony λ .

3) Construct vector $[EP_2 - rand, EP_3 - rand, EP_4 - rand]$, empire g with the biggest $EP_g - rand$ as winning empire, suppose $g = 2$, then choose I colonies with the lowest cost of empire 2 and execute global search between each chosen colony and IM_g as done in step 2).

4) Choose empire g with the biggest $EP_g - rand$ from vector $[EP_3 - rand, EP_4 - rand]$, suppose $g = 3$, then choose I colonies with the lowest cost of empire 3 and execute global search between each chosen colony and IM_g as done in step 2).

5) In empire 4, execute multiple neighborhood search for each solution $x \in \theta$, delete I worst colony from empire 4, add all solutions of θ into empire 4.

Where EP_k denotes power of empire k ,

$$EP_k = \left| \frac{\overline{TC}_k}{\sum_{i=1}^4 \overline{TC}_i} \right| \quad (4)$$

Unlike the existing ICAs [30,35], CICA has four empires and no elimination of empire. In CICA, assimilations of empires 1,4 are handled together and cooperation is used, assimilations of empires 2,3 are conducted on the temporary empire formed by these two empires, a new imperialist competition is also given. These new features can lead to the enhanced global search ability and the avoidance of the waste of computing resource.

4 Computational Experiments

Extensive experiments are conducted to test the performance of CICA for considered parallel BPM scheduling problem. All experiments are implemented by using Microsoft Visual Studio C++2022 and run on 8.0 G RAM 2.4 Hz CPU PC.

4.1 Instances, Comparative Algorithms and Metrics

96 instances are used, each of which depicted by $n \times l \times m$, where $n \in \{10, 20, 40, 60, 100, 140, 180, 220, 260, 300\}$, $l \in \{3, 4\}$, $m \in \{3, 4, 5\}$, $p_{ik} \in [10, 50]$, $v_i \in [1, 10]$, $w_i \in [1, 10]$, $V = 10$, $W = 10$, $r_i \in [0, 25]$. p_{ik} , v_i , w_i and r_i are integer following uniform distribution in the above intervals. These instances consist of small-scale ones, medium-scale ones and large-scale ones and can be show the optimization ability differences of different algorithms.

Zhang et al. [24] proposed a MEASL to minimize makespan for parallel BPM scheduling problem with release time, job size and processing time. Jiang et al. [25] presented IG algorithm for parallel BPM scheduling problem with release time, job sizes, incompatible job families. Ji et al. [26] provided HLNS to solve parallel BPM scheduling problem with release time, job sizes, incompatible job families and makespan minimization.

MEASL, IG and HLNS can be directly applied to solve the considered parallel BPM scheduling problem and the computational results show that these three algorithms have promising advantages on solving parallel BPM scheduling, so they are chosen as comparative algorithms.

To show the effect of new strategies of CICA, CICA is compared with ICA [30,35], in ICA, assimilation of empire k , is done below: For each colony $\lambda \in T_k$, execute global search between λ , IM_k , a new solution z is obtained, if $C_{\max}^z < C_{\max}^\lambda$, then replace λ with z . When revolution is done, multiple neighborhood search acts on the chosen colony.

Three metrics are used. For each instance, each algorithm randomly runs 10 times and an elite solution with the smallest makespan is obtained in a run, MIN is the best solution found in 10 runs, MAX denotes the worst elite solutions in 10 runs and AVG indicates the average makespan of 10 elite solutions. MIN, AVG, MAX are used to measure convergence, average performance and stability of algorithms. These metrics are often used to evaluate results of single objective problem.

4.2 Parameter Settings

It can be found that CICA can converges well when $0.6 \times n$ s CPU time reaches; moreover, when $0.6 \times n$ s CPU time is applied, MEASL, IG, HLNS and ICA also converge fully within this CPU time, so this time is chosen as stopping condition.

Other parameters of CICA, namely N , α , Q , R and I , are tasted by using Taguchi method [49] on instance $140 \times 3 \times 3$. The levels of each parameter are shown in Table 2. CICA with each combination runs 10 times independently for the chosen instance.

Table 2: Levels of parameters

Parameters	Factor Level		
	1	2	3
N	50	60	70
α	3	5	7
Q	5	6	7
R	0.4	0.5	0.6
I	5	6	7

Fig. 2 shows the result of MIN and S/N ratio, which is defined as $-10 \times \log_{10}(\text{MIN}^2)$. It can be found in Fig. 2 that CICA with following combination $N = 60, \alpha = 5, Q = 6, R = 0.5, I = 6$ can be obtain better results than CICA with other combinations, so above combination is adopted.

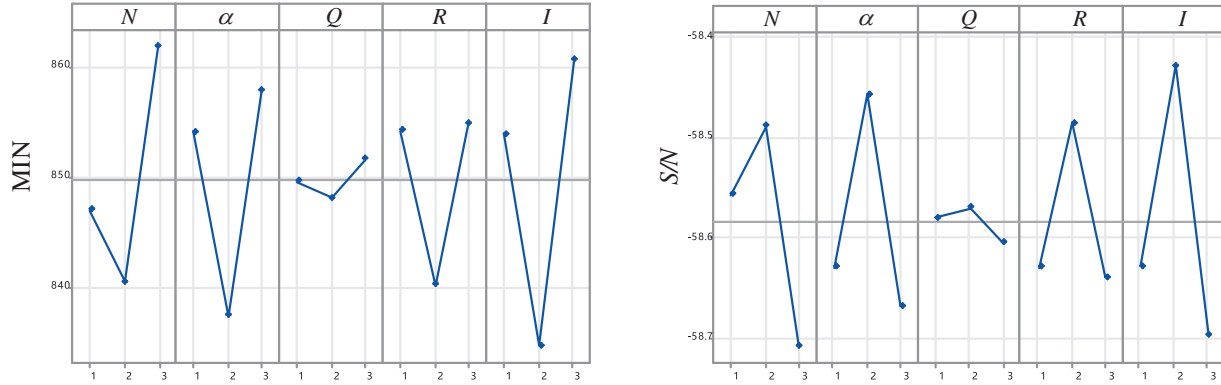


Figure 2: Main effect plot for mean MIN and S/N ratio

Parameters of ICA are shown below. $N = 60, R = 0.5, N_{im} = 4$ and stopping condition is $0.6 \times ns$ CPU time. These settings are obtained by experiments. All parameters of MEASL, IG and HLNS except stopping condition are obtained directly from [24–26]. The experimental results show that those setting of each comparative algorithm are still effective and comparative algorithms with those setting can produce better results than MEASL, IG and HLNS with other settings.

4.3 Results and Discussions

CICA is compared with MEASL, IG, HLNS and ICA. Each algorithm randomly runs 10 times on each instance. Tables 3–5 describe corresponding results of five algorithms. Figs. 3 and 4 show box plots of all algorithms and convergence curves of instances $100 \times 3 \times 3$ and $220 \times 3 \times 3$. The relative percentage deviation (RPD) between the best performs algorithm and other four algorithms is used in Fig. 3. $RPD_{\text{MIN}}, RPD_{\text{AVG}}, RPD_{\text{MAX}}$ are defined:

$$RPD_{\text{MIN}} = \frac{\text{MIN} - \text{MIN}^*}{\text{MIN}^*} \times 100\% \tag{5}$$

where MIN^* ($\text{MAX}^*, \text{AVG}^*$) is the smallest MIN (MAX, AVG) obtained by all algorithms, when MIN and MIN^* are replaced with $\text{MAX}(\text{AVG})$ and $\text{MAX}^*(\text{AVG}^*)$, respectively, RPD_{MAX} (RPD_{AVG}) is obtained in the same way.

Table 3: Computational results of five algorithms on MIN

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
$10 \times 3 \times 3$	50	50	51	55	53	$160 \times 3 \times 3$	980	1196	1088	1459	1248
$10 \times 3 \times 4$	48	56	54	65	62	$160 \times 3 \times 4$	741	907	824	1081	948
$10 \times 3 \times 5$	46	46	46	47	48	$160 \times 3 \times 5$	565	724	620	836	727
$10 \times 4 \times 3$	51	56	53	60	63	$160 \times 4 \times 3$	1018	1212	1101	1471	1278
$10 \times 4 \times 4$	52	53	51	50	46	$160 \times 4 \times 4$	752	913	823	1086	940
$10 \times 4 \times 5$	47	50	53	59	56	$160 \times 4 \times 5$	575	726	618	853	700

(Continued)

Table 3 (continued)

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
20 × 3 × 3	121	146	131	158	158	180 × 3 × 3	1156	1299	1187	1611	1466
20 × 3 × 4	95	102	102	120	117	180 × 3 × 4	815	995	864	1141	980
20 × 3 × 5	79	99	81	72	94	180 × 3 × 5	657	821	707	943	827
20 × 4 × 3	122	146	130	160	157	180 × 4 × 3	1177	1356	1217	1620	1452
20 × 4 × 4	100	110	100	117	121	180 × 4 × 4	832	1003	870	1170	1009
20 × 4 × 5	79	106	79	95	95	180 × 4 × 5	675	856	704	978	848
40 × 3 × 3	230	264	241	294	280	200 × 3 × 3	1235	1446	1336	1797	1545
40 × 3 × 4	162	197	159	237	202	200 × 3 × 4	906	1109	975	1328	1135
40 × 3 × 5	124	169	126	187	152	200 × 3 × 5	723	887	759	1064	872
40 × 4 × 3	231	265	238	295	282	200 × 4 × 3	1305	1481	1363	1822	1611
40 × 4 × 4	155	196	171	235	187	200 × 4 × 4	925	1122	992	1346	1150
40 × 4 × 5	135	169	130	191	133	200 × 4 × 5	758	937	791	1105	915
60 × 3 × 3	317	374	394	477	417	220 × 3 × 3	1402	1635	1492	1934	1769
60 × 3 × 4	244	287	313	370	302	220 × 3 × 4	995	1194	1071	1463	1280
60 × 3 × 5	174	225	242	274	221	220 × 3 × 5	787	917	865	1179	938
60 × 4 × 3	325	384	414	475	437	220 × 4 × 3	1432	1653	1540	1948	1823
60 × 4 × 4	237	291	310	359	315	220 × 4 × 4	1028	1218	1087	1482	1273
60 × 4 × 5	180	232	253	280	226	220 × 4 × 5	806	989	862	1189	1011
80 × 3 × 3	448	534	554	657	585	240 × 3 × 3	1463	1719	1611	2165	1913
80 × 3 × 4	338	427	451	494	438	240 × 3 × 4	1086	1273	1175	1587	1416
80 × 3 × 5	254	329	346	385	318	240 × 3 × 5	933	951	903	1243	926
80 × 4 × 3	474	542	590	673	585	240 × 4 × 3	1508	1720	1630	2160	1930
80 × 4 × 4	336	433	456	501	419	240 × 4 × 4	1093	1316	1195	1630	1402
80 × 4 × 5	243	336	356	392	319	240 × 4 × 5	941	983	946	1268	952
100 × 3 × 3	543	626	676	838	689	260 × 3 × 3	1615	1843	1729	2381	2094
100 × 3 × 4	420	514	457	659	541	260 × 3 × 4	1205	1393	1266	1709	1491
100 × 3 × 5	313	407	339	488	412	260 × 3 × 5	949	1153	1014	1417	1228
100 × 4 × 3	548	631	683	840	680	260 × 4 × 3	1647	1871	1709	2367	2105
100 × 4 × 4	423	530	559	664	545	260 × 4 × 4	1211	1440	1319	1767	1563
100 × 4 × 5	317	408	330	506	409	260 × 4 × 5	960	1162	1034	1417	1233
120 × 3 × 3	726	838	754	1033	859	280 × 3 × 3	1809	2037	1966	2581	2127
120 × 3 × 4	517	647	579	792	681	280 × 3 × 4	1348	1552	1405	1969	1511
120 × 3 × 5	418	521	436	618	479	280 × 3 × 5	1006	1200	1100	1499	1133
120 × 4 × 3	735	868	782	1046	876	280 × 4 × 3	1874	2105	1967	2675	2155
120 × 4 × 4	555	665	591	815	667	280 × 4 × 4	1367	1570	1401	1945	1662
120 × 4 × 5	410	534	454	625	517	280 × 4 × 5	1036	1221	1111	1537	1194
140 × 3 × 3	820	923	865	1216	943	300 × 3 × 3	1988	2236	2128	2864	2313
140 × 3 × 4	590	719	614	917	763	300 × 3 × 4	1400	1621	1491	2076	1615
140 × 3 × 5	462	585	499	737	612	300 × 3 × 5	1131	1312	1210	1652	1250
140 × 4 × 3	822	937	886	1226	1063	300 × 4 × 3	2043	2306	2210	2843	2454
140 × 4 × 4	602	722	631	904	777	300 × 4 × 4	1442	1650	1496	2054	1610
140 × 4 × 5	478	595	472	721	599	300 × 4 × 5	1158	1350	1208	1653	1283

Table 4: Computational results of five algorithms on AVG

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
10 × 3 × 3	52	53	59	58	57	160 × 3 × 3	1036	1205	1116	1512	1310
10 × 3 × 4	50	59	51	58	58	160 × 3 × 4	767	917	839	1111	971
10 × 3 × 5	48	56	49	57	57	160 × 3 × 5	592	738	636	872	747
10 × 4 × 3	53	65	56	68	68	160 × 4 × 3	1052	1224	1129	1506	1326
10 × 4 × 4	53	57	52	56	55	160 × 4 × 4	780	932	848	1118	970
10 × 4 × 5	50	61	55	69	68	160 × 4 × 5	585	743	641	875	733
20 × 3 × 3	135	160	138	168	166	180 × 3 × 3	1181	1336	1261	1670	1502
20 × 3 × 4	104	122	107	129	134	180 × 3 × 4	837	1010	898	1210	1035
20 × 3 × 5	91	109	88	86	102	180 × 3 × 5	682	836	732	991	850
20 × 4 × 3	133	152	136	168	163	180 × 4 × 3	1206	1364	1275	1675	1506
20 × 4 × 4	109	126	105	126	129	180 × 4 × 4	856	1021	912	1225	1058
20 × 4 × 5	87	112	86	112	103	180 × 4 × 5	700	872	743	1008	900
40 × 3 × 3	248	279	253	319	292	200 × 3 × 3	1278	1463	1374	1836	1616
40 × 3 × 4	173	215	167	251	212	200 × 3 × 4	941	1129	1013	1365	1183
40 × 3 × 5	137	179	137	206	166	200 × 3 × 5	750	919	799	1109	926
40 × 4 × 3	251	277	247	322	293	200 × 4 × 3	1318	1499	1403	1850	1662
40 × 4 × 4	166	204	181	251	204	200 × 4 × 4	963	1140	1019	1398	1191
40 × 4 × 5	140	177	141	205	138	200 × 4 × 5	780	954	827	1128	937
60 × 3 × 3	329	384	409	502	437	220 × 3 × 3	1470	1658	1545	2050	1835
60 × 3 × 4	258	297	320	387	320	220 × 3 × 4	1029	1227	1112	1502	1320
60 × 3 × 5	183	234	253	291	237	220 × 3 × 5	819	1003	887	1209	961
60 × 4 × 3	344	400	427	503	450	220 × 4 × 3	1457	1668	1582	2073	1856
60 × 4 × 4	256	303	324	384	329	220 × 4 × 4	1053	1241	1130	1519	1313
60 × 4 × 5	190	244	262	298	241	220 × 4 × 5	823	1024	899	1219	1051
80 × 3 × 3	472	546	580	702	602	240 × 3 × 3	1513	1727	1639	2197	1961
80 × 3 × 4	360	439	466	526	452	240 × 3 × 4	1117	1298	1201	1638	1453
80 × 3 × 5	269	345	367	409	329	240 × 3 × 5	958	966	933	1303	955
80 × 4 × 3	493	565	608	687	612	240 × 4 × 3	1548	1748	1669	2219	1981
80 × 4 × 4	354	442	471	535	458	240 × 4 × 4	1141	1344	1228	1681	1464
80 × 4 × 5	262	344	373	415	383	240 × 4 × 5	977	990	979	1311	972
100 × 3 × 3	561	650	701	863	715	260 × 3 × 3	1655	1871	1767	2421	2147
100 × 3 × 4	444	524	469	679	561	260 × 3 × 4	1229	1413	1309	1772	1554
100 × 3 × 5	329	414	357	515	424	260 × 3 × 5	983	1175	1057	1449	1263
100 × 4 × 3	576	667	700	863	713	260 × 4 × 3	1692	1897	1785	2432	2172
100 × 4 × 4	451	538	574	679	561	260 × 4 × 4	1260	1459	1358	1812	1601
100 × 4 × 5	334	418	355	516	423	260 × 4 × 5	992	1195	1069	1474	1254
120 × 3 × 3	735	856	788	1060	924	280 × 3 × 3	1868	2072	2003	2681	2177
120 × 3 × 4	548	663	611	820	697	280 × 3 × 4	1369	1574	1471	1993	1615
120 × 3 × 5	429	535	463	648	526	280 × 3 × 5	1043	1234	1125	1543	1212
120 × 4 × 3	752	885	817	1072	916	280 × 4 × 3	1919	2114	2037	2720	2227
120 × 4 × 4	567	679	604	829	687	280 × 4 × 4	1399	1587	1488	2002	1728
120 × 4 × 5	429	544	472	649	535	280 × 4 × 5	1065	1251	1152	1579	1227

(Continued)

Table 4 (continued)

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
140 × 3 × 3	842	952	895	1268	969	300 × 3 × 3	2034	2259	2261	2868	2356
140 × 3 × 4	619	737	657	951	790	300 × 3 × 4	1446	1662	1452	2101	1660
140 × 3 × 5	483	600	518	763	623	300 × 3 × 5	1164	1350	1248	1679	1314
140 × 4 × 3	842	956	914	1262	1087	300 × 4 × 3	2076	2359	2374	2890	2583
140 × 4 × 4	619	740	667	951	793	300 × 4 × 4	1492	1685	1557	2108	1657
140 × 4 × 5	492	607	522	755	622	300 × 4 × 5	1177	1374	1253	1688	1342

Table 5: Computational results of five algorithms on MAX

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
10 × 3 × 3	57	57	63	63	60	160 × 3 × 3	1077	1225	1170	1539	1367
10 × 3 × 4	58	67	58	63	66	160 × 3 × 4	783	932	862	1149	999
10 × 3 × 5	56	63	56	68	67	160 × 3 × 5	616	754	651	898	774
10 × 4 × 3	56	73	61	73	76	160 × 4 × 3	1085	1239	1147	1541	1380
10 × 4 × 4	55	64	53	67	63	160 × 4 × 4	794	943	867	1153	1003
10 × 4 × 5	55	70	60	74	77	160 × 4 × 5	597	763	665	900	768
20 × 3 × 3	144	163	147	174	174	180 × 3 × 3	1216	1355	1327	1717	1534
20 × 3 × 4	115	132	115	137	150	180 × 3 × 4	865	1022	917	1254	1067
20 × 3 × 5	102	118	97	95	116	180 × 3 × 5	697	856	757	1028	891
20 × 4 × 3	142	164	150	175	170	180 × 4 × 3	1239	1379	1328	1702	1566
20 × 4 × 4	115	133	113	137	140	180 × 4 × 4	884	1039	936	1275	1096
20 × 4 × 5	96	122	95	121	114	180 × 4 × 5	718	896	768	1041	1086
40 × 3 × 3	259	290	266	336	304	200 × 3 × 3	1322	1478	1408	1864	1694
40 × 3 × 4	184	226	181	258	223	200 × 3 × 4	994	1143	1044	1398	1231
40 × 3 × 5	153	196	149	223	178	200 × 3 × 5	779	941	841	1144	961
40 × 4 × 3	274	286	262	338	318	200 × 4 × 3	1340	1520	1446	1889	1715
40 × 4 × 4	173	212	192	266	234	200 × 4 × 4	1014	1149	1047	1448	1243
40 × 4 × 5	152	188	148	218	147	200 × 4 × 5	801	975	857	1156	976
60 × 3 × 3	339	396	422	526	464	220 × 3 × 3	1540	1676	1581	2082	1898
60 × 3 × 4	275	305	335	404	346	220 × 3 × 4	1050	1243	1153	1534	1371
60 × 3 × 5	197	246	263	300	256	220 × 3 × 5	861	1020	914	1250	986
60 × 4 × 3	357	407	442	542	462	220 × 4 × 3	1487	1681	1625	2123	1896
60 × 4 × 4	266	311	332	400	349	220 × 4 × 4	1077	1279	1125	1555	1344
60 × 4 × 5	200	259	268	317	252	220 × 4 × 5	851	1046	919	1262	1084
80 × 3 × 3	517	557	598	733	637	240 × 3 × 3	1557	1737	1666	2249	2012
80 × 3 × 4	371	449	490	547	478	240 × 3 × 4	1147	1321	1230	1695	1487
80 × 3 × 5	277	353	385	434	342	240 × 3 × 5	997	987	966	1352	989
80 × 4 × 3	516	576	623	701	682	240 × 4 × 3	1581	1775	1709	2282	2043
80 × 4 × 4	382	452	486	551	544	240 × 4 × 4	1173	1359	1274	1722	1519
80 × 4 × 5	293	349	392	433	429	240 × 4 × 5	1037	1154	1052	1341	1009
100 × 3 × 3	599	663	715	884	766	260 × 3 × 3	1694	1902	1796	2470	2191

(Continued)

Table 5 (continued)

Instance	CICA	ICA	MEASL	IG	HLNS	Instance	CICA	ICA	MEASL	IG	HLNS
100 × 3 × 4	465	535	499	700	588	260 × 3 × 4	1249	1432	1353	1827	1596
100 × 3 × 5	350	429	373	524	444	260 × 3 × 5	1027	1196	1124	1488	1302
100 × 4 × 3	598	680	719	888	744	260 × 4 × 3	1745	1920	1854	2491	2220
100 × 4 × 4	475	550	588	710	587	260 × 4 × 4	1290	1477	1458	1846	1661
100 × 4 × 5	350	431	372	532	439	260 × 4 × 5	1038	1212	1109	1518	1278
120 × 3 × 3	749	865	820	1089	960	280 × 3 × 3	1918	2105	2046	2726	2205
120 × 3 × 4	562	670	637	847	714	280 × 3 × 4	1409	1596	1508	2024	1785
120 × 3 × 5	444	550	484	664	549	280 × 3 × 5	1077	1253	1158	1578	1261
120 × 4 × 3	776	899	844	1093	965	280 × 4 × 3	1958	2124	2100	2768	2365
120 × 4 × 4	590	691	617	850	721	280 × 4 × 4	1437	1606	1596	2061	1794
120 × 4 × 5	447	560	495	688	556	280 × 4 × 5	1098	1284	1193	1613	1266
140 × 3 × 3	884	964	936	1295	999	300 × 3 × 3	2112	2298	2293	2937	2416
140 × 3 × 4	648	752	704	981	826	300 × 3 × 4	1477	1686	1591	2159	1690
140 × 3 × 5	495	619	535	793	640	300 × 3 × 5	1222	1372	1314	1737	1361
140 × 4 × 3	876	975	940	1301	1114	300 × 4 × 3	2131	2305	2435	2938	2686
140 × 4 × 4	646	754	701	958	816	300 × 4 × 4	1530	1701	1626	2176	1712
140 × 4 × 5	503	622	556	793	640	300 × 4 × 5	1204	1391	1285	1718	1389

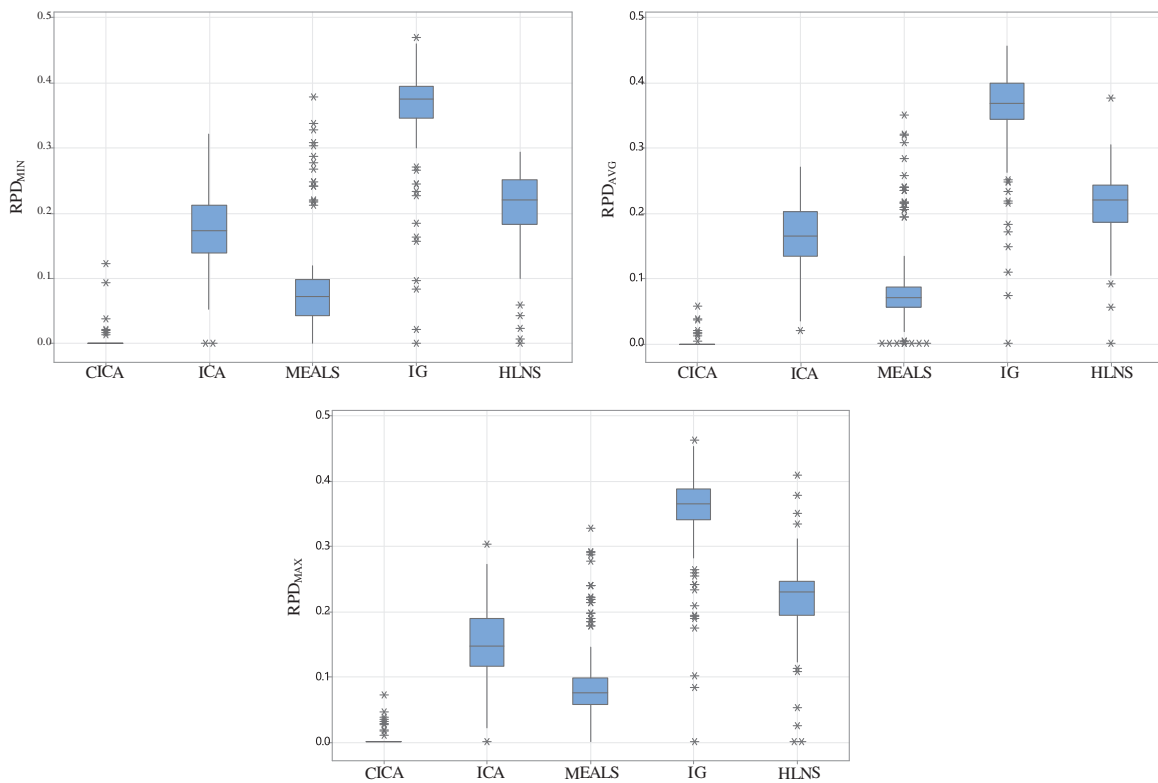


Figure 3: Box plots of five algorithms

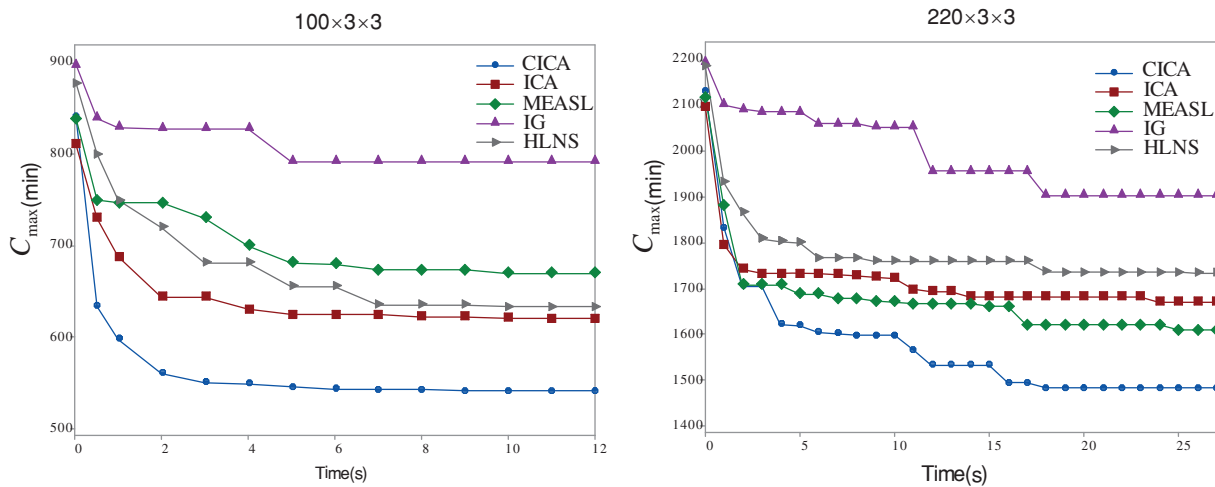


Figure 4: convergence curves of instances $100 \times 3 \times 3$ and $220 \times 3 \times 3$

As shown in Table 3, CICA obtains smaller MIN than ICA on all instances and MIN of CICA is lower than that of ICA by at least 20 on 87 instances. CICA converges better than ICA. This conclusion also can be obtained from Figs. 3 and 4. It can be also found from Tables 4, 5 and Figs. 3, 4 that CICA performs significantly than ICA on AVG and MAX. CICA obtain smaller AVG and MAX than ICA on all instances. It can be concluded that cooperation-based assimilations, combination-based assimilations and new imperial competition process have a positive impact on the performance of CICA.

It can be found from Table 3 that CICA performs better than its comparative algorithms on MIN. CICA produces smaller MIN than three comparative algorithms on 90 of 96 instances; moreover, MIN of CICA is less than that of MEASL by at least 20 on 73 instances, that of IG by at least 20 on 87 instances and that of HLNS by at least 20 on 85 instances. When l and m are the same, with increasing of n , the gap between MIN of CICA and three comparative algorithms is also increasing. CICA has better convergence than MEASL, IG and HLNS. This conclusion can also be drawn from Figs. 3 and 4.

Table 4 describes that CICA obtains smaller AVG than MEASL, IG and HLNS on 88 instances; moreover, AVG of CICA is better than that of its all comparative algorithms by at least 20 on 75 instances. CICA possesses better average performance than its three comparative algorithms. Fig. 3 also illustrates notable average performance differences between CICA and each comparative algorithm.

It also can be seen from Table 5 that MAX of CICA only exceeds that of three comparative algorithms only 10 instances. CICA has smaller MAX than comparative algorithms by at least 20 on 76 instances. Fig. 3 also demonstrates that CICA possesses better stability than its comparative algorithms.

As analyzed above, CICA performs better convergence, average performance and stability than its co-comparative algorithms. The good performances of CICA mainly result from its new strategies. Cooperation-based assimilations of empires 1,4, and combination-based assimilations of empires can effectively improve quality of empires and avoid the waste of computing resources. High diversity can be kept by new imperial competition process. These strategies can make good balance between

exploration and exploitation, thus, CICA is a very promising method for solving parallel BPM scheduling problem with release times.

5 Conclusions and Future Topics

This study examines a scheduling problem involving unrelated parallel batch processing machines (BPM) with release times, a scenario that is derived from the moulding process in a foundry. The Cooperated Imperialist Competitive Algorithm (CICA), which does not use the number of empires as a parameter and maintains four empires throughout the search process, is introduced. The algorithm provides two new methods for assimilation through cooperation and combination between empires, and presents a new form of imperialist competition. Extensive experiments are conducted to compare CICA with existing methods and test its performance. The computational results demonstrate that CICA is highly competitive in solving the considered parallel BPM scheduling problems. BPM is prevalent in many real-life manufacturing processes, such as foundries, and scheduling problems involving BPM are more complex than those without BPM. Future research will focus on scheduling problems with BPM, such as the hybrid flow shop scheduling problem with the BPM stage. We aim to use the knowledge of the problem and new optimization mechanisms in CICA to solve these problems. To obtain high-quality solutions, new optimization mechanisms, such as machine learning, are incorporated into meta-heuristics like the imperialist competitive algorithms. We also plan to apply new meta-heuristics, such as teaching-learning-based optimization, to solve the problem. Energy-efficient scheduling with BPM is another future topic. Furthermore, the application of CICA to other problems is also worth further investigation.

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