

# Hybrid Imperialist Competitive Evolutionary Algorithm for Solving Biobjective Portfolio Problem

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**Abstract:** Portfolio optimization is an effective way to diversify investment risk and optimize asset management. Many multiobjective optimization mathematical models and metaheuristic intelligent algorithms have been proposed to solve portfolio problem under an ideal condition. This paper presents a biobjective portfolio optimization model under the assumption of no short selling. In order to obtain sufficient number of portfolio optimal solutions uniformly distributed on the portfolio efficient Pareto front, a hybrid imperialist competitive evolutionary algorithm which combines a multi-colony levy crossover operator and a simple-colony moving operator with random perturbation is also given. The performance of the given algorithm is verified by four criterion portfolio test problems, and the simulation results and comparison analyses illustrate that the proposed algorithm could obtain faster convergence toward the portfolio true Pareto front compared with the other two state of the art multiobjective optimization methods. The results can provide optimal portfolio plans and investment strategies for investors to allocate and manage assets effectively.

**Keywords:** Portfolio optimization; biobjective mathematical model; imperialist competitive algorithm; asset management

## 1 Introduction

Diversified investment is a well-practiced approach to avoid investment risk and obtain maximum portfolio return [1]. How to select and allocate limited capital in financial management and portfolio field is still one of the most challenging and important problem [2]. A pioneering portfolio optimization model, called mean-variance (M–V) model was addressed by Markowitz [3], which laid the foundation for modern financial theory. The M–V model has significant application value, and it provides insightful perspective for the research of the investment return and risk of portfolio optimization problems. In fact, M–V portfolio model is usually considered as a simple-objective portfolio optimization model which aims at minimizing the investment risk or maximizing the return of the capital. Therefore, M–V model made significant contribution for the development of modern finance and portfolio theories, and it is deemed as a classical method for the measurement of the performance of portfolio optimization problems [4–7].



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Since the publication of Harry M. Markowitz's M–V portfolio theory, it has gained widespread application and promotion as a practical mathematic method for portfolio optimization, and large amount of publications modifying or extending the portfolio optimization models and developing new effective portfolio optimization algorithms have been found [8,9]. Generally speaking, we can classify portfolio models into simple-objective portfolio optimization and multiobjective portfolio optimization. As far as simple-objective portfolio model (problem) is concerned, many researches usually minimize the variance of the portfolio while satisfying the bound of a portfolio return and the threshold of the invested assets in the portfolio optimization [10–12].

For the past few years, several metaheuristic intelligence evolution methods have been extended and used to solve multiobjective portfolio optimization in financial and economic fields. For example, Fernandez et al. [13] put forward a hybrid metaheuristic optimization algorithm to handle multiobjective project portfolio optimization problems; Li et al. [14] jointly presented a multiobjective portfolio selection optimization model and genetic algorithm based on fuzzy random returns; Lwin et al. [15] focused on solving complex constrained portfolio optimization and proposed a learning-guided multiobjective algorithm; Anagnostopoulos and Mamanis built a three objectives discrete portfolio model [16], and Deng et al. [17] discussed the multiobjective portfolio problem with a vision of intuitionistic fuzzy set, and so on [18,19].

Imperialist competitive algorithm (ICA) [20] is an intelligence optimization algorithm similar to the particle swarm method and the fish swarm algorithm, which has been used to solve the complex practical problems. As we know, ICA possesses polynomial convergent velocity or convergent order and can easily jump out the constraint of local convergence. For example, an ICA for solving nonlinear dynamic simple-objective constrained optimization problems is introduced in [21], and an enhanced ICA for optimum design of skeletal structures is given in [22], etc.

To reduce the complexity of the algorithm due to the non-smooth quadratic property of Markowitz's mean-variance model and find a reasonable intelligent method in solving portfolio optimization, this research presents a biobjective portfolio mathematical model with no short selling. Also, a hybrid imperialist competitive evolutionary algorithm combining a multi-colony levy crossover operator and a simple-colony moving operator with random perturbation is proposed to obtain sufficient uniformly distributed and representative portfolio optimal solutions on the portfolio effective Pareto frontier. The numerical simulations are made on four standard portfolio problems, the simulation results show that the given hybrid ICA is effective in solving multiobjective portfolio optimization problem and can obtain better portfolio optimal solutions.

The rest of the paper is arranged as follows. Section 2 is related concepts and biobjective portfolio model. The main operators of the proposed hybrid ICA to solve biobjective portfolio model are given in Section 3. Section 4 is the detailed procedure of the given algorithm. Section 5 is the simulation result and experimental analysis, and the conclusion is made in Section 6.

## 2 Related Concepts and Biobjective Portfolio Optimization Model

To describe the biobjective portfolio model, related terminologies of multiobjective optimization are briefly introduced in the following subsection.

### 2.1 Multiobjective Optimization

An unconstrained multiobjective minimized optimization problem is described as follows:

$$\min_{y \in \Omega} F(y) = (f_1(y), f_2(y), \dots, f_m(y)) \quad (1)$$

where  $y$  is decision variable,  $y = (y_1, y_2, \dots, y_n) \in \mathcal{R}^n$ , and

$$\Omega = \{y | y = (y_1, y_2, \dots, y_n) \in \mathcal{R}^n, l_s \leq y_s \leq u_s, s = 1 \sim n\} \tag{2}$$

is called feasible region.

The objective vector  $F(y)$  which contains  $m$  objectives maps the feasible region  $\Omega$  into objective space of problem (1). All feasible solutions of multiobjective programming problem (1) constitutes the Pareto optimal solution set, and the images of these feasible solutions form efficient Pareto front of problem (1).

**Definition 1.** Reference [23] Suppose  $y = (y_1, y_2, \dots, y_m)$  and  $z = (z_1, z_2, \dots, z_m)$  are two multi-dimensional vectors; if  $\forall i \in \{1, 2, \dots, m\}$ ,  $y_k \leq z_k$  and  $y_k < z_k$  for at least one index  $k \in \{1, 2, \dots, m\}$  hold; then, vector  $y$  is said to dominate vector  $z$  (denoted as  $y \prec z$ ).

**Definition 2.** Reference [23] Solution  $y \in \mathcal{R}^n$  is defined as Pareto optimal solution of problem (1); if not exists solution  $z \in \mathcal{R}^n$ , and  $F(z)$  dominates  $F(y)$ .

**Definition 3.** Suppose that  $U^1, U^2, \dots, U^k$  are Pareto optimal solution sets obtained by  $k$  algorithm  $A_1, A_2, \dots, A_k$ , respectively. Then, solution set

$$U^* = \left\{ y \in \bigcup_{j=1}^k U^j \mid \nexists z \in \bigcup_{j=1}^k U^j, \text{ s.t. } F(z) \prec F(y) \right\} \tag{3}$$

is regarded as a Pareto optimal filtration set.

### 2.2 Biobjective Portfolio Optimization Model

Classical portfolio optimization model, such as Markowitz's M–V portfolio selection model, assumes  $n$  available assets and one investment period. The investor can choose the proportion weights of the initial investment which will be allocated in the available assets. In fact, Markowitz's M–V portfolio model can be regarded as a single-objective portfolio mathematical model. The prevalent method dealing with the M–V optimization model is either to minimize risk (variance) of security while constraining return of security to a lower level, or to maximize the return of security (mean) while controlling risk of security in a ceiling level. The biobjective portfolio optimization model described in this section is based on two measures: one is the portfolio risk measure function and the other is the non-positive function of portfolio return.

Suppose that  $y = (y_1, y_2, \dots, y_n)$  is the column vector of portfolio,  $y_i$  is the  $i$ -th investment proportional weight of security, we define  $\mu_{it}$  as a history return value of the  $i$ -th security at the  $t$ -th phase ( $1 \leq t \leq T$ ), and  $\mu_i$  as investment expected return value of the  $i$ -th security, then, function

$$f_1(y) = \frac{1}{T} \sum_{t=1}^T \max \left\{ 0, \sum_{i=1}^n (\mu_i - \mu_{it}) y_i \right\} \tag{4}$$

is defined as a measure of portfolio risk, and non-positive function

$$f_2(y) = - \sum_{i=1}^n \mu_i y_i \tag{5}$$

is taken as a measure of portfolio return; then, we define

$$\min_{y \in [l, u]} f(y) = (f_1(y), f_2(y)) \tag{6}$$

as a new biobjective portfolio model, where  $y \in \mathcal{R}^n$  is decision vector,  $[l, u]$  is  $n$ -dimension search space, and

$$[l, u] = \{(y_1, y_2, \dots, y_n) | 0 < l_i \leq y_i \leq u_i \leq 1, i = 1 \sim n\} \quad (7)$$

$\|y\|_1 = 1$  is the tight constraint, where the constraints condition (7) indicates that short selling is not allowed for biobjective portfolio optimization problem (6).

**Definition 4** Suppose that  $pop(k)$  presents the evolution country population of the  $k$ -th generation,  $z(\tau) \in pop(k)$  and  $r(z(\tau))$  is the number of these feasible points (individuals) which dominate  $z(\tau)$  in country population  $pop(k)$ , and  $z(1), z(2), \dots, z(N)$  are  $N$  feasible individuals which dominate the feasible individual  $z$ . Denote

$$\text{rank}(z) = 1 + \sum_{\kappa=1}^N r(z(\kappa)) \quad (8)$$

where  $\text{rank}(z)$  can be regarded as the accumulation rank value of individual  $z$ .

### 3 Main Operators of Imperialist Competitive Algorithm

ICA [20] contains a population of countries and mimics the social and political competition process of imperialism. In the competition, some best original individuals (countries) were chosen to constitute the original imperialists, and the rest of countries were regarded as colonies of the original imperialist according to reasonable rules. Then, each of original imperialists with its colonies was called an empire. The competitive behavior will carry out among all the empires. If an empire could not win among the competition, it would become the colony of the strongest imperialist. Thus, all the colonies will move to the imperialist associated with it. At last, this collapse mechanism makes all colonies converge to Pareto optimal solution. The detailed pseudo-process of ICA is described in the following part.

#### 3.1 Initial Empires Creation

Compared with other artificial intelligence optimization algorithm, ICA begins with the initial evolution country population. One generates  $N_{pop}$  initial countries based on the orthogonal design method [24]. Denote these initial countries as  $\text{cou.}(j) = (z_1^{(j)}, z_2^{(j)}, \dots, z_n^{(j)}) \in [l, u]$ , where  $j = 1 \sim N_{pop}$ ; then, the cost of each  $\text{cou.}(j)$  is defined as follows:

$$C_j = \text{rand}(\text{cou.}(j)) \quad (9)$$

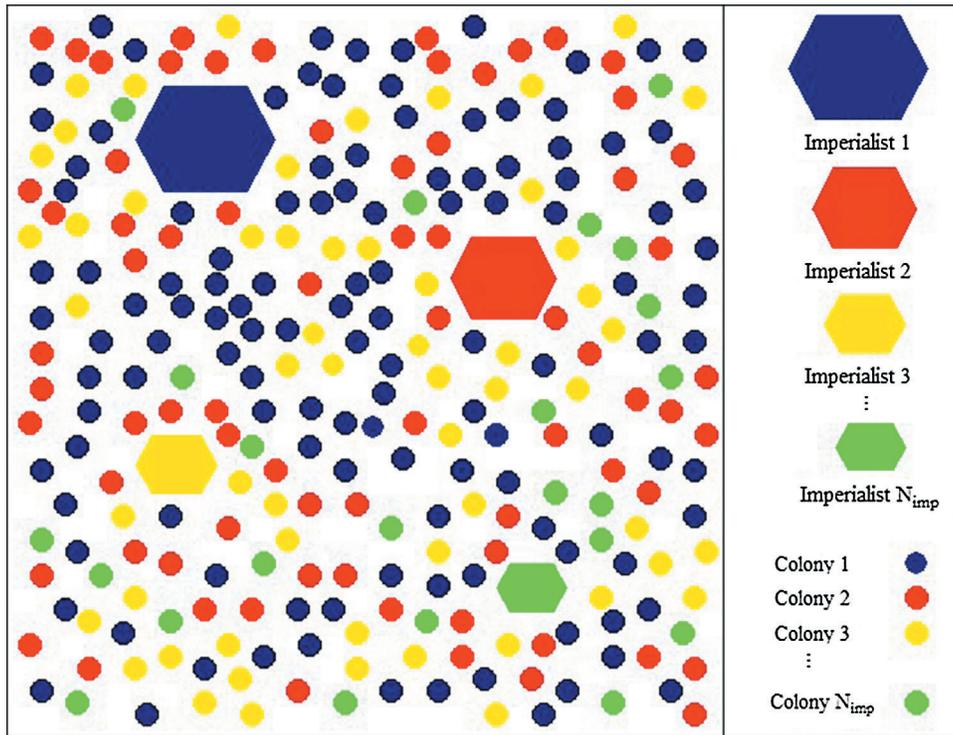
Choose  $N_{imp}$  better countries with smaller accumulation rank from the initial evolution population to compose the initial imperialists, and the rest  $N_{col}(N_{col} = N_{pop} - N_{imp})$  countries would be the colonies allocated into these imperialists according to their powers, which can be calculated by the formula (8). Thus, every empire has got a certain number colonies. Fig. 1 illustrates the process in detail.

Mark each imperialist as  $\text{imp.}(i)$  and each colony as  $\text{col.}(j)$ , where  $i = 1 \sim N_{pop}$  and  $j = 1 \sim N_{col}$ . At the same time, we assign those colonies to different imperialists using the method of proportion selection according to their power and generate the initial empires.

Step 1: Based on the following formula (10), compute the normalized power for each of imperialists,

$$p_j = 1 - \left| \frac{C_j}{\sum_{\tau=1}^{N_{imp}} C_\tau} \right| \quad (10)$$

where  $C_j = \max_{1 \leq k \leq N_{imp}} \{\text{rank}_k\} - \text{rank}_j$  is normalized cost of  $\text{imp.}(j)$ , and  $p_j$  is normalized power of  $\text{imp.}(j)$ ,



**Figure 1:** Generating the initial imperialists and colonies

where  $j = 1 \sim N_{pop}$ ,  $rank_j$  is accumulation rank value of  $imp.(k)$ , where  $k = 1 \sim N_{pop}$ . The imperialist which has less accumulation rank value will have more normalized cost value.

Step 2: Based on the following formula, we obtain a positive integer

$$C.N._k = \text{round}\{N_{col} \cdot p_k\} \tag{11}$$

where  $C.N._k$  represents the number of the colonies in the  $k$ -th imperialist, and  $N_{col}$  represents the amount of the colonies.

Step 3: Randomly choose  $C.N._k$  colonies and assign them to  $imp.(k)$ , these colonies and  $imp.(k)$  constitute the  $k$ -th empire (denoted as  $emp.(k)$ ,  $k = 1 \sim N_{pop}$ ). The initial imperialist and colonies of each empire are showed in Fig. 1 with different colors, and it is clearly shown that the more power an imperialist has, the bigger its relevant area of hexagon.

### 3.2 Simple-Colony Moving Operator with Random Perturbation

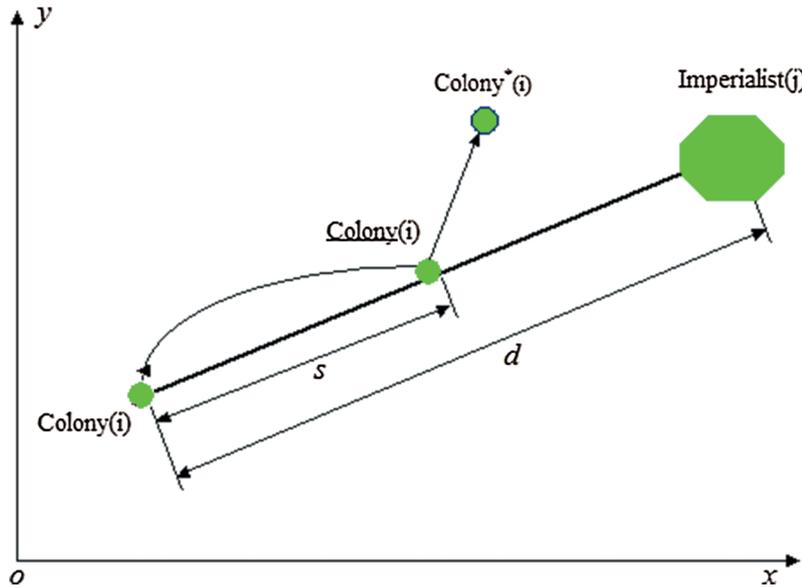
In practice, all the imperialists attempt to expand and develop their colonies by means of assimilation and force their colonies to approach them. When the colony moving method mentioned in [20] is used, it is difficult to make portfolio Pareto optimal solutions quickly converge the portfolio true Pareto frontier and also maintain the otherness and diversity of the country population. Considering the characteristics of biobjective portfolio optimization model proposed in subsection 2.2, a simple-colony moving operator with random perturbation is given.

Step 1: Assume colony(1), colony(2),  $\dots$ , colony( $C.N._j$ ) are  $C.N._j$  colonies included in the  $j$ -th empire, we make colony( $i$ ) =  $(x_1^{(i)}, x_2^{(i)}, \dots, x_n^{(i)})$  move to its relevant imperialist along the direction which is a vector connecting point colony( $i$ ) and imperialist( $j$ ), where  $\underline{\text{colony}}(i) = (y_1^{(i)}, y_2^{(i)}, \dots, y_n^{(i)})$  is the

stopping position of colony(*i*)’s moving. This movement step is modeled in Fig. 2 from colony(*i*) to colony(*i*) in which the colony moves to the imperialist by *s* units, i.e.,

$$s \sim U(0, \beta \times d) \tag{12}$$

where parameter *s* is the uniformly distributed random variable,  $\beta > 0$  is the expansion coefficient, and  $d = \|\text{colony}(i) - \text{imperialist}(j)\|_2$ , parameter  $\beta$  causes colony(*i*) to approach imperialist(*j*) from both sides.



**Figure 2:** Moving colony(*i*) toward their relevant imperialist(*j*)

Step 2: Give a random number  $r_i \in (0, 1)$ ; if  $r_i < p_m$  hold, generate the new moving position colony\*(*i*) = ( $z_1^{(i)}, z_2^{(i)}, \dots, z_n^{(i)}$ ) of colony(*i*) according to the following random perturbation operator, i.e.,

$$\text{colony}^*(i) = \begin{pmatrix} y_1^{(i)} \\ y_2^{(i)} \\ \vdots \\ y_n^{(i)} \end{pmatrix} + \begin{pmatrix} |x_1^{(j)} - y_1^{(i)}| & 0 & \dots & 0 \\ 0 & |x_2^{(j)} - y_2^{(i)}| & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & |x_n^{(j)} - y_n^{(i)}| \end{pmatrix} \cdot \Delta\Gamma \tag{13}$$

where  $x_k^{(j)}$  is the *k*-th component of imperialist(*j*).  $\Delta\Gamma$  represents Gaussian distribution,  $\Delta\Gamma \sim N(0, 1)$ . This movement step is modeled in Fig. 2 from colony(*i*) to colony\*(*i*) in which the colony(*i*) makes normal random perturbation operator and gets the new position colony\*(*i*) of the initial colony(*i*).

### 3.3 Position Change between Imperialist and Colony

When a colony approaches an imperialist and acquires a new position, it may achieve a better fitness function than that of the imperialist. In this case, we can replace the imperialist with the colony, and vice versa. The proposed algorithm will continue to use this new colony as an imperialist. The detailed description can be found in [20,21].

### 3.4 Multi-Colony Levy Distribution Crossover Operator

How to make algorithm quickly converge to the portfolio efficient Pareto front and maintain the diversity of the population is critical for multiobjective portfolio method. In order to find new feasible solution region and further improve the robustness and diversity of the empire, a multi-colony levy distribution crossover operator is proposed in the following section.

Step 1: Select  $\zeta$  colonies (denoted as colony(1), colony(2),  $\dots$ , colony( $\zeta$ )) from the empire( $j$ ), where  $j = 1, 2, \dots, N_{imp}$ .

Step 2: Let colony\* =  $\sum_{i=1}^{\zeta} l_i$  colony( $i$ ), where  $\sum_{i=1}^{\zeta} l_i = 1$ .

Step 3: Carry out multi-colony levy distribution crossover operator, generate the offspring colony $^{\oplus}$  of colony\*, i.e.,

$$\text{colony}^{\oplus} = \text{colony}^* + \alpha \varsigma \sum_{i=1}^n L_i(\beta) \cdot e_i \quad (14)$$

$L_i(\beta)$  is the random number satisfying levy distribution,  $\alpha = \frac{1}{N_{imp}} \sum_{i=1}^{N_{imp}} \left\| \text{colony}(i) - \sum_{j=1}^{N_{imp}} \text{colony}(j) \right\|_2$ ,  $e_i$  is the unit vector,  $\varsigma = \exp\{\eta_1 N(0, 1) + \eta_2 N(0, 1)\}$ ,  $N(0, 1)$  is the random normal distribution in which its mean is 0 and variance is 1, and  $n$  is the number of dimensions of the colony,  $\eta_1 = \frac{1}{\sqrt{2N}}$ ,  $\eta_2 = \frac{1}{\sqrt{2}\sqrt{N}}$ ,  $\beta = 0.6$ .

### 3.5 Imperialistic Competition

For ICA [20], imperialistic competition plays an important role. During the competition process, weaker imperialists (own high accumulation rank value) will lose their colonies, and their power will begin to wane; meanwhile, the power of those stronger empires will begin to increase. The imperialistic competition process can be described as follows:

(1) Let  $C.t.k$  represent the power probability of the  $k$ -th empire; then,  $C.t.k$  is defined as follows:

$$C.t.k = \text{rank}(\text{imperialist}^*) + r \frac{1}{C.n.k} \sum_{j=1}^{C.n.k} \text{rank}(\text{colony}(j)) \quad (15)$$

where  $r \in (0, 1)$ , imperialist\* represents the imperialist of the  $k$ -th empire,  $C.n.k$  represents the number of the colonies included in the  $k$ -th empire.

(2) Based on the following formula (16), generate power probability value  $P.e.k$  of every empire( $k$ ) for  $k = 1 \sim N_{imp}$ , i.e.,

$$P.e.k = 1 - \left| \frac{C.n.t.k}{\sum_{j=1}^{N_{imp}} C.n.t.j} \right| \quad (16)$$

$C.n.t.k = \max_{1 \leq j \leq N_{imp}} \{C.t.j\} - C.t.k$  represents the power probability of the  $k$ -th empire.

(3) Compute the cost (rank value) of each colony, and give these costs an ascending order. Then, we select  $N_{imp}$  colonies from large to small in order and assign them to each empire according to its probability of power, let

$$P = (P.e.1, P.e.2, \dots, P.e.N_{imp}) \quad (17)$$

and generate random vector  $V_{1 \times N_{imp}}$  with uniformly distributed elements, i.e.,

$$V = (\Lambda_1, \Lambda_2, \dots, \Lambda_{N_{imp}}) \quad (18)$$

where  $\Lambda_i \sim U(0, 1)$  for  $i = 1, 2, \dots, N_{imp}$ . Furthermore, let

$$Q = (P.e._1 - \Lambda_1, P.e._2 - \Lambda_2, \dots, P.e._{N_{imp}} - \Lambda_{N_{imp}}) \quad (19)$$

Let  $p_j = \text{rand}(0, 0.5)$ . If  $p_j \leq (P.e._j - \Lambda_j)$  hold, we can assign the colony( $j$ ) selected from the  $N_{imp}$  colonies mentioned above into the  $j$ -th empire; otherwise, delete the colony( $j$ ), where  $j = 1, 2, \dots, N_{imp}$ .

### 3.6 Eliminating the Powerless Empires

During the process of competition, the colonies of weaker empire will be less and less. Finally, when an empire becomes powerless, it will be eliminated. To model this mechanism, we consider an empire collapses when it loses all of its colonies and the imperialist itself becomes a colony of another empire.

### 3.7 Stop Condition

The competition operator will continue until each of the empires, except the strongest empire (lowest accumulation rank value), collapses and every colony included in the evolution population is controlled by this empire. That is to say, all the colonies have obtained the same costs (lower accumulation rank value) as the powerful empire. Under the circumstance, we stop the imperialist competition and output these portfolio Pareto optimal solutions whose accumulation rank value are equal to 1.

## 4 Hybrid Imperialist Competitive Evolutionary Algorithm

The proposed hybrid evolutionary algorithm (denoted in DPEA) for solving the biobjective portfolio optimization problem (6) is described as following:

**Step 1:** Give initial country size  $N_{pop}$  and initial imperialist size  $N_{imp}$ . Generate  $N_{imp}$  initial countries  $\text{cou}^{(1)}(0), \text{cou}^{(2)}(0) \dots, \text{cou}^{(N_{imp})}(0)$  based on the orthogonal design method [24] in the search space  $[l, u]$ . Then, all of the initial countries constitute set  $A(0)$ , and let  $t = 0$ .

**Step 2:** Compute the accumulation rank value of these initial countries which is included in set  $A(t)$ , and denote all of the countries whose accumulation rank value is equal to 1 as set  $B(0)$  and let  $t = 0$ .

**Step 3:** Select  $N_{imp}$  powerful countries based on the power of each country and allocate the rest of the countries into them, and then, generate  $N_{imp}$  initial empire, i.e.,  $\text{empire}(i), i = 1 \sim N_{imp}$ .

**Step 4:** Let each colony among the empire approach the imperialist according to the simple-colony moving operator with random perturbation in Section 3.2, and exchange the position of the imperialist and the best colony included in the empire.

**Step 5:** Perform the multi-colony levy distribution crossover operator proposed in Section 3.4 and imperialistic competition operator proposed in Subsection 3.5, and generate the next country population  $A(t + 1)$ .

**Step 6:** Find out the countries which accumulation rank value are equal to 1 in set  $A(t + 1) \cup B(t)$ , use them to replace those individuals included in set  $A(t)$ , and constitute new set  $B(t + 1)$ .

**Step 7:** If the stopping criterion meets, output these Pareto optimal solutions in the external set  $B(t + 1)$ ; otherwise, return to Step 3.

## 5 Simulation Result and Analysis

To compare the effectiveness and robustness of DPEA with other advanced multiobjective intelligent computation algorithms, three classical performance metric indicator methods, C-measure [24], H-measure [25] and U-measure [26], are cited, where C-measure is usually used to test the domination of the portfolio Pareto optimal solutions obtained by two different multi-objective optimization methods, H-measure is used to assess whether the optimal solutions obtained by one multiobjective optimization algorithm is better than that of the other, and the third measure (U-measure) is used to test the augmentability and uniformity of these solutions distributed on Pareto front.

Furthermore, we choose four benchmark portfolio optimization problems  $Port_i (i = 1, 2, 3, 4)$ , in which the data of the mean, the variance and the correlation covariance matrix come from the Web of OR-library (<http://people.brunel.ac.uk/~mastjjb/jeb/info.html>). The index of test problems, the data source and the number of portfolio asserts are described in Tab. 1.

**Table 1:** Basic data of the test problems

Index of problem	Data source	Number of portfolio
Port1	Hong Kong Hang Seng	31
Port2	German DAX 100	85
Port3	British FTSE 100	89
Port4	US S & P 100	98

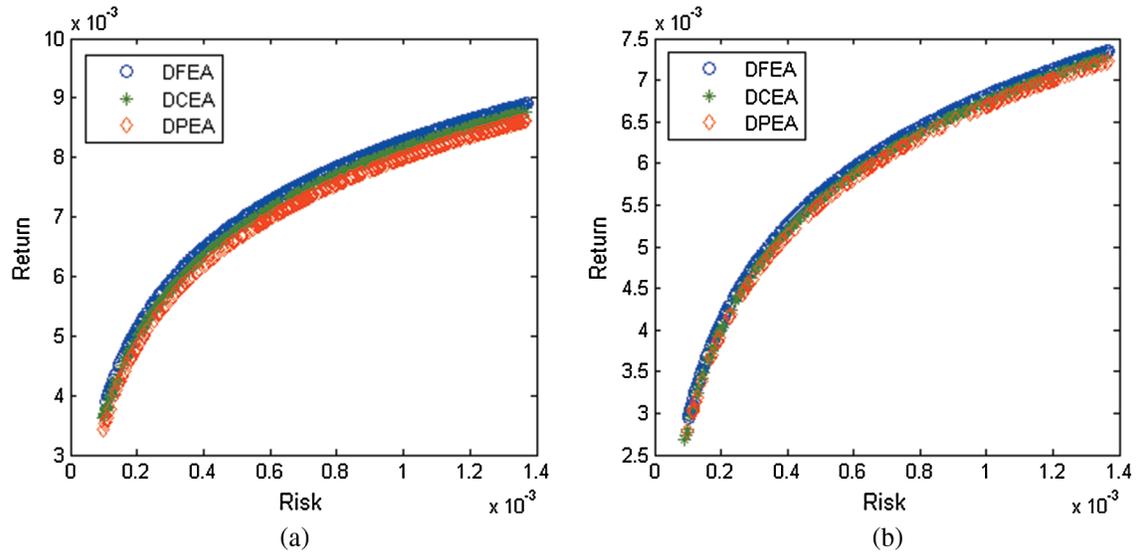
It's impossible to make an absolute equitable comparison result among the same kinds of algorithm based on no free lunch theorem. Thus, the identical test parameters are used in the simulation for both our algorithm DPEA and the other compared algorithms. Each benchmark portfolio problems were tested by two superior multiobjective methods DFEA [19], DCEA [23] and the proposed method DPEA. We implement each of algorithms on an Intel Pentium IV 2.8-GHz personal computer, and each test problems was carried out 30 runs using MATLAB 7.0. During the process of numerical test, the initial population (countries) size  $N_{pop} = 500$ , the initial stronger countries (imperialists) size  $N_{imp} = 10$ , and the maximum iterations of algorithm is 200. Moreover, in order to test the sensitivity of parameter  $r$  mentioned in formula (15) for the algorithm's performance and the quality of Pareto portfolio optimal solution obtained by the compared algorithms, we execute three algorithms, DFEA, DCEA, and DPEA, on each test problem at different parameter value  $r = 0.2, 0.4, 0.6$  and  $0.8$ .

In the stimulation, the portfolio efficient Pareto frontiers obtained by three compared methods in a typical run are recorded; moreover, we utilize three metric indicator methods (C-measure, H-measure and U-measure) to test the sensibility and robustness for algorithm DFEA, DCEA and DPEA at different values of parameter  $r$  where  $r$  is a weight coefficient in formula (15).

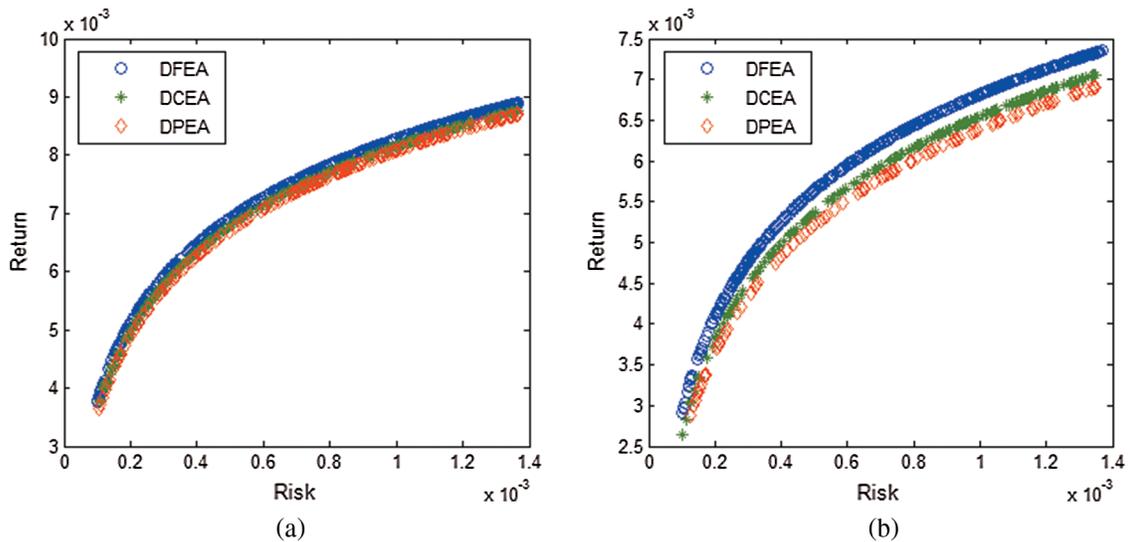
We depict the portfolio efficient Pareto frontiers obtained by three algorithms for four test problems in Figs. 3 and 4. The boxplot of C-measure obtained by three algorithms at different parameter value  $r$  in a typical run are given from Figs. 5–10 show the H-measure and U-measure value obtained by each compared method in a typical run at different parameter value  $r$  respectively.

By comparing the portfolio efficient Pareto frontiers (Figs. 3 and 4) obtained by three compared algorithms DFEA, DCEA and DPEA in a typical run, we can easily know that our algorithm DPEA can obtain the true portfolio Pareto frontier more easily than algorithm DFEA and DCEA. Meanwhile, it can be observed from Fig. 5 to Fig. 8 that  $C(A_3, A_s) > C(A_s, A_3)$  for  $s = 1, 2$  in different parameter value  $r$ , which indicates that the Pareto solution set obtained by algorithm DPEA contains sufficient number of

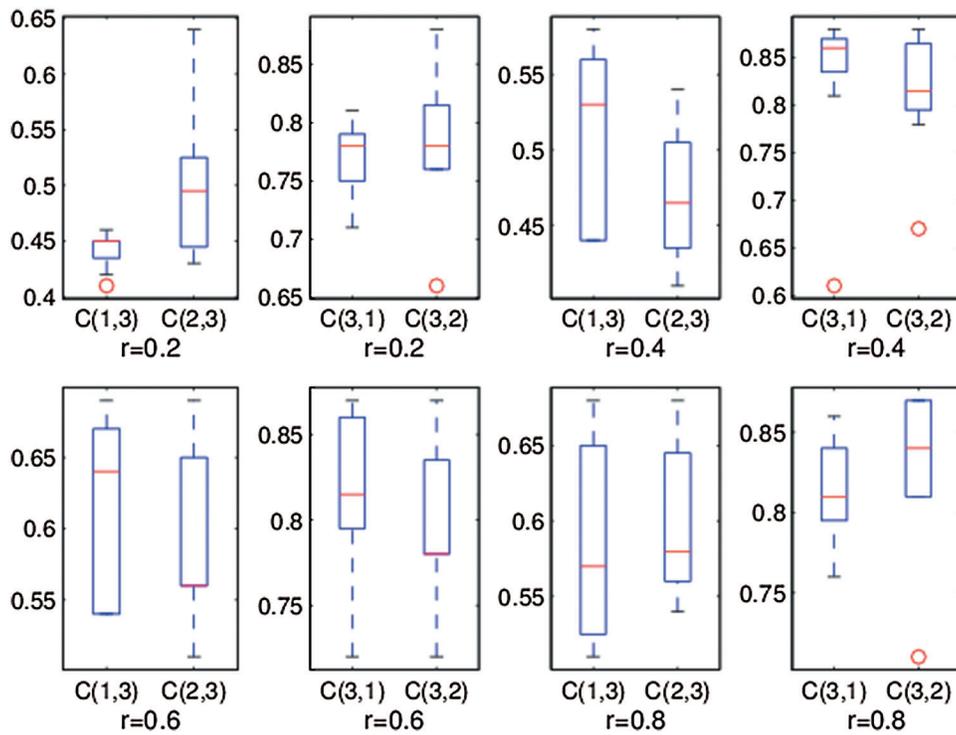
better solutions than that of the compared algorithms DFEA and DCEA, where  $A_s$  and  $A_m$  are two Pareto solution sets obtained by the compared methods  $s$  and  $m$ ,  $C(A_s, A_m)$  presents the C-measure value obtained by algorithm  $i$  and  $j$ , and the natural number 1, 2 and 3 present algorithms DFEA, DCEA and the proposed algorithm DPEA.



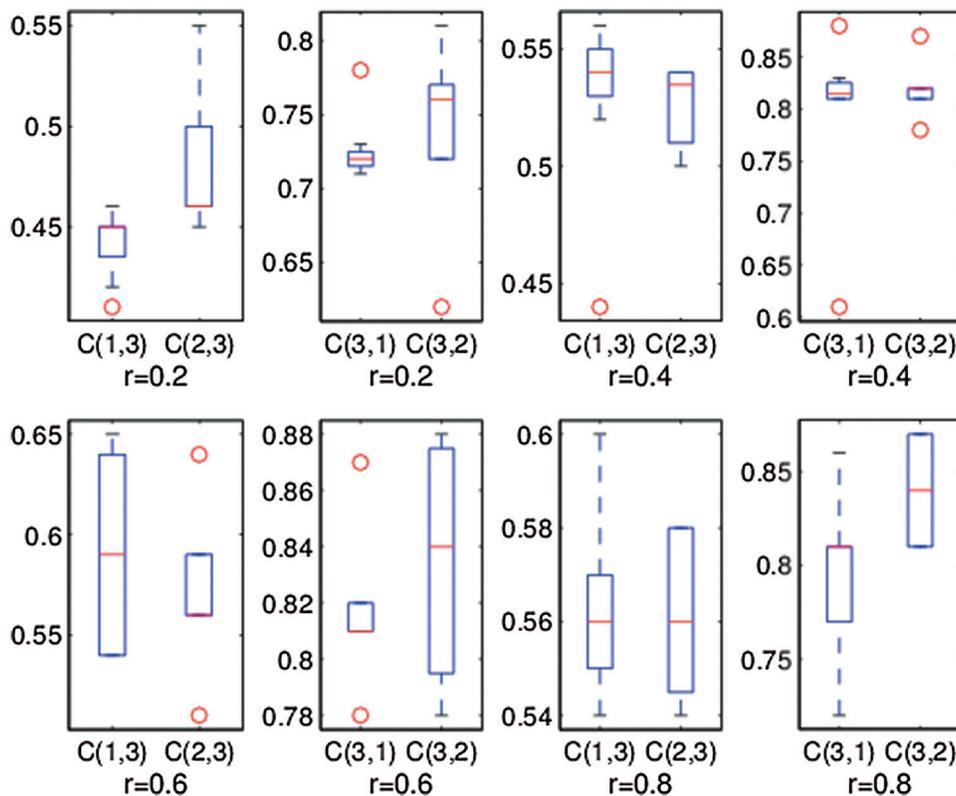
**Figure 3:** Comparison of portfolio efficient Pareto frontiers obtained by DFEA, DCEA and DPEA for Port1 and Port2 in a typical run. (a) Port1; (b) Port2



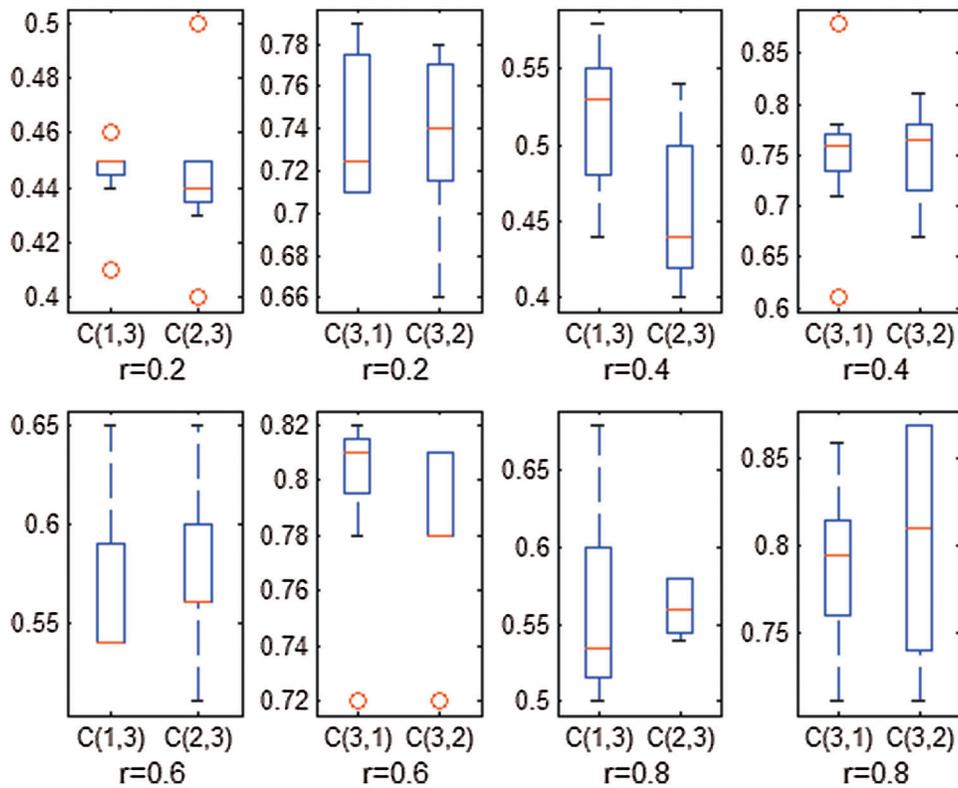
**Figure 4:** Comparison of portfolio efficient Pareto frontiers obtained by DFEA, DCEA and DPEA for Port3 and Port4 in a typical run. (c) Port3; (d) Port4



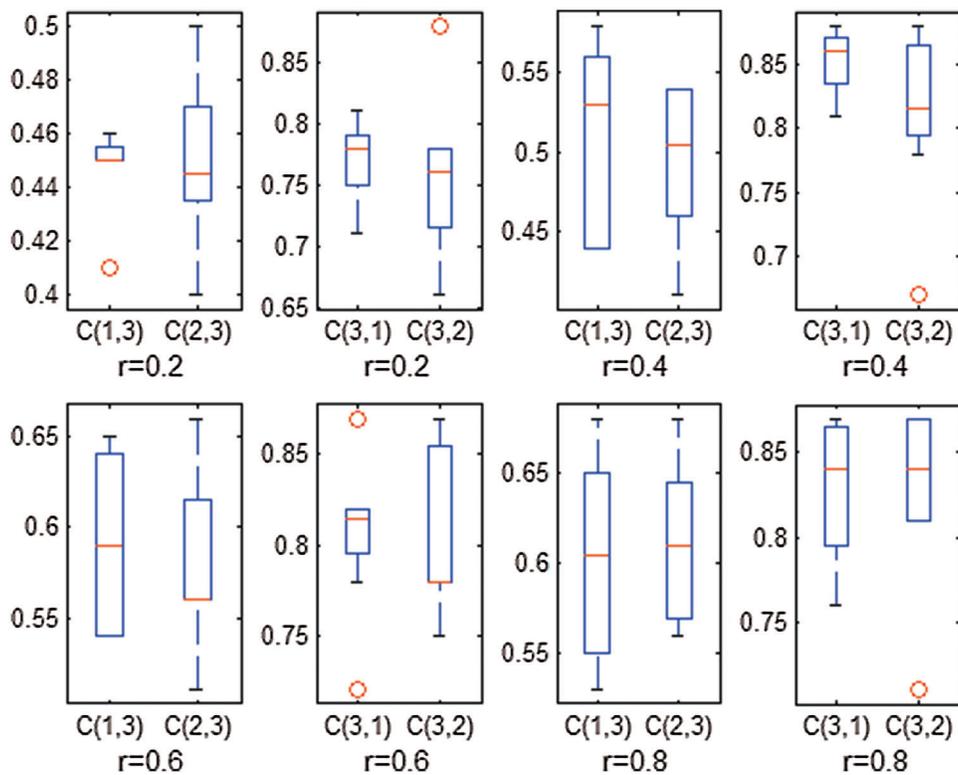
**Figure 5:** Comparison of C-measure obtained by algorithm  $s$  and  $m$  on Port1 in four values of parameter  $r$ , where  $C(s, m)$  represents  $C(A_s, A_m)$  for  $s, m = 1, 2, 3$



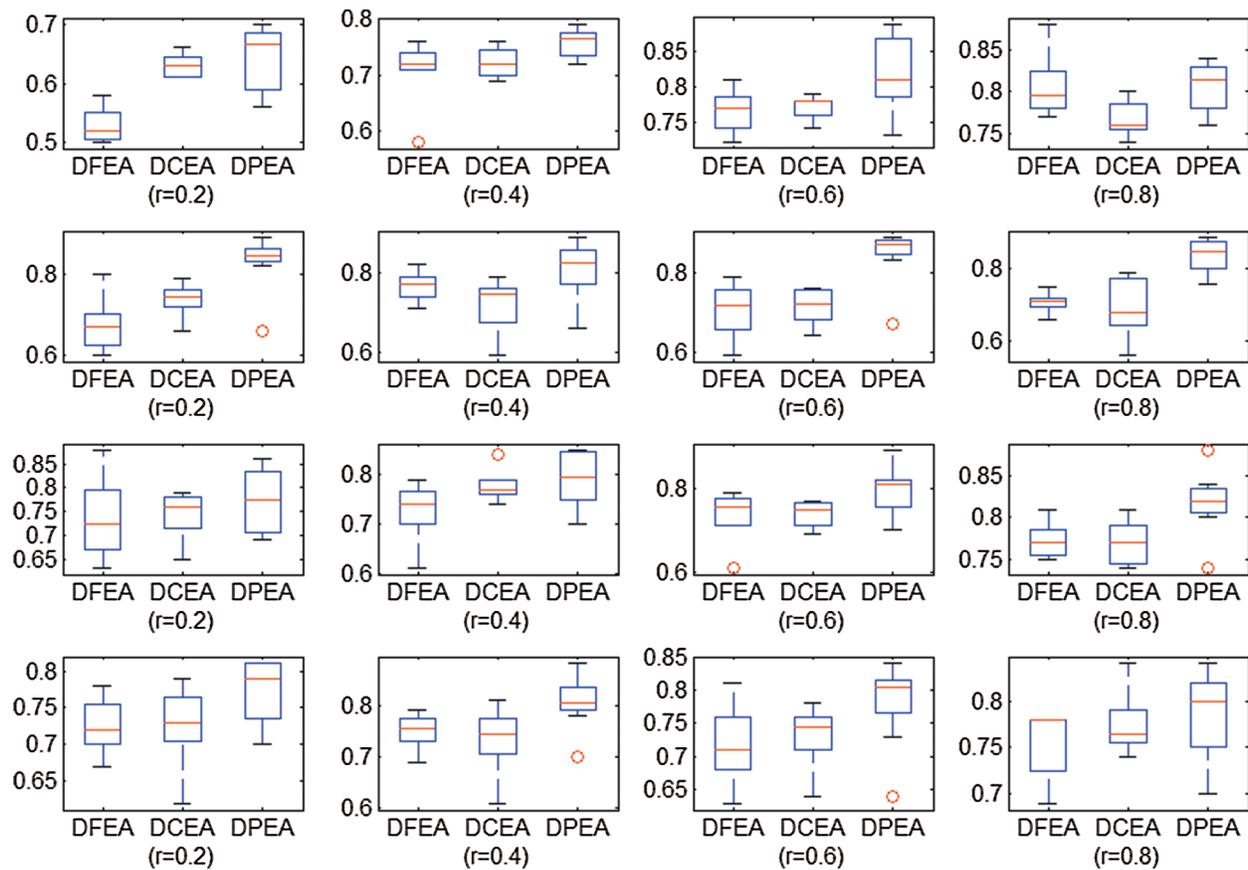
**Figure 6:** Comparison of C-measure obtained by algorithm  $s$  and  $m$  for Port2 in four values of parameter  $r$ , where  $C(s, m)$  represents  $C(A_s, A_m)$  for  $s, m = 1, 2, 3$



**Figure 7:** Comparison of C-measure obtained by algorithm  $s$  and  $m$  for Port3 in four values of parameter  $r$ , where  $C(s, m)$  represents  $C(A_s, A_m)$  for  $s, m = 1, 2, 3$

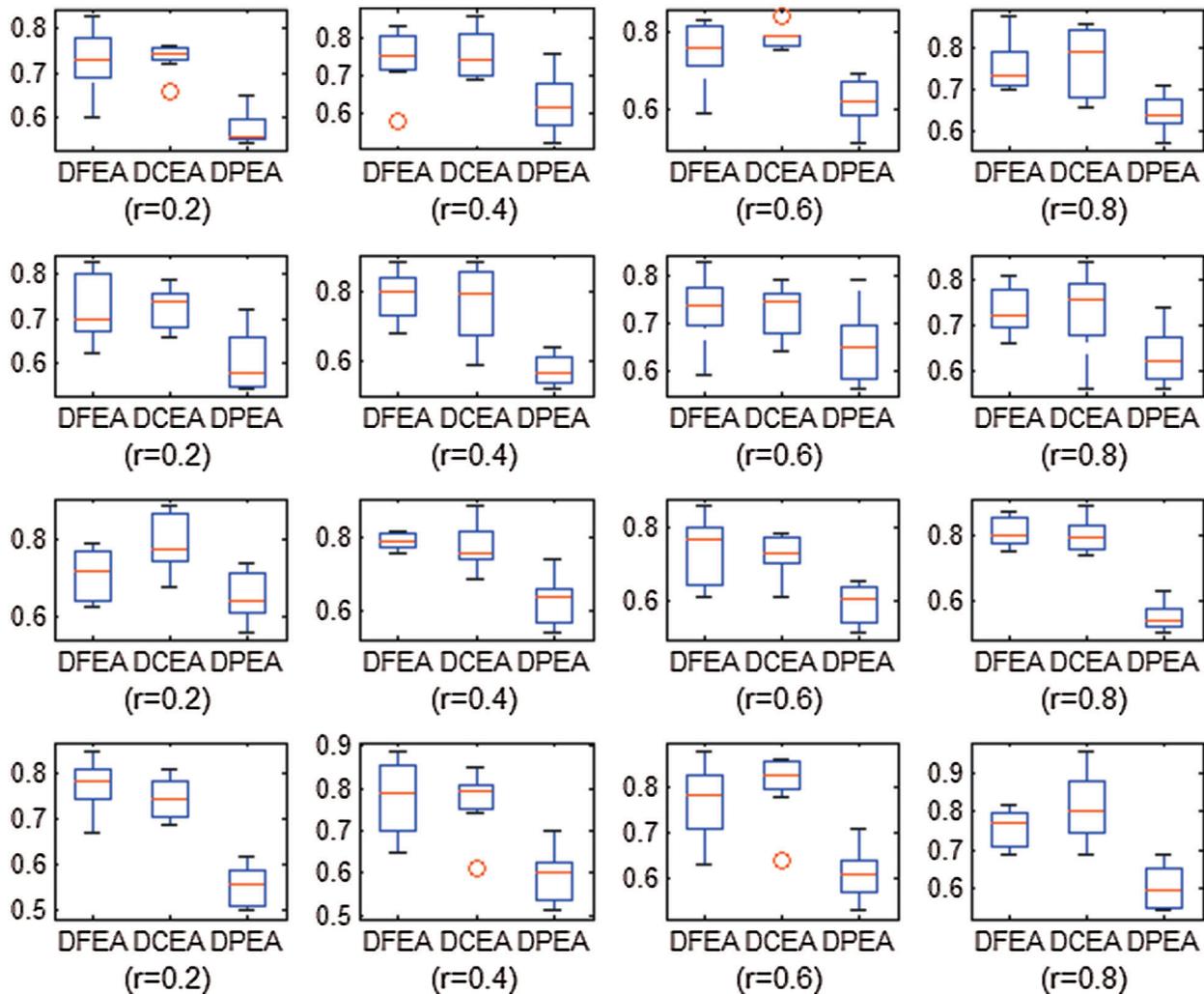


**Figure 8:** Comparison of C-measure obtained by algorithm  $i$  and  $j$  for Port4 in four values of parameter  $r$ , where  $C(s, m)$  represents  $C(A_s, A_m)$  for  $s, m = 1, 2, 3$



**Figure 9:** Comparison of H-measure values obtained by three algorithms in different parameter  $r$ . The  $i$ -th row of the Figure representing the compared results of H-measure obtained by different algorithms for the  $i$ -th portfolio problem  $Port_i$  in parameter  $r$ ,  $i = 1, 2, 3, 4$

Moreover, comparing the Boxplot results in each row of [Figs. 9](#) and [10](#), we can see that our algorithm DPEA produces bigger values of H-measure and much smaller values of U-measure than the compared algorithms DFEA and DCEA. These mean that the portfolio Pareto frontiers obtained by DPEA have better extension and uniform distribution than the two algorithms DFEA and DCEA, and the results also showed that the portfolio optimal solutions obtained by algorithm DPEA are superior to algorithm DFEA and DCEA. So, the given method DPEA is efficient in exploring and finding the portfolio optimal solutions for the biobjective portfolio problem (6).



**Figure 10:** Comparison of U-measure obtained by three algorithms in different parameter  $r$ . The  $i$ -th row of the Figure representing the compared results of U-measure obtained by three algorithms for the  $i$ -th portfolio problem Port $i$  in parameter  $r$ ,  $i = 1, 2, 3, 4$

## 6 Conclusion

In this paper, a hybrid ICA for solving biobjective portfolio problem and a new portfolio biobjective optimization model based on portfolio risk measure function and return measure function are given. In order to accelerate the convergence and produce quality Pareto portfolio fronts, a multi-colony levy crossover operator and a simple-colony moving operator with random perturbation are integrated into the proposed algorithm.

We utilized four portfolio benchmark problems to test the performance of the given algorithm DPEA according to three indicators C-measure, H-measure and U-measure. The results illustrate that algorithm DPEA can identify better portfolio optimal solutions and bring adequate diversity of the evolution population. That is to say, the portfolio efficient Pareto frontier obtained by DPEA is closer to the portfolio true Pareto front than the compared algorithms and its distribution is broader towards the boundary of the feasible search region. The results can not only help investors allocate and manage asset

effectively but also provide better idea and method for solving other complicated constrained finance and economy problem.

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