

Two-Mode Biomedical Sensor Build-up: Characterization of Optical Amplifier

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Abstract: Intracavity absorption spectroscopy is a strikingly sensitive technique that has been integrated with a two-wavelength setup to develop a sensor for human breath. Various factors are considered in such a scenario, out of which Relative Intensity Noise (RIN) has been exploited as an important parameter to characterize and calibrate the said setup. During the performance of an electrical based assessment arrangement which has been developed in the laboratory as an alternative to the expensive Agilent setup, the optical amplifier plays a pivotal role in its development and operation, along with other components and their significance. Therefore, the investigation and technical analysis of the amplifier in the system has been explored in detail. The algorithm developed for the automatic measurements of the system has been effectively deployed in terms of the laser's performance. With this in perspective, a frequency dependent calibration has been pursued in depth with this scheme which enhances the sensor's efficiency in terms of its sensitivity. In this way, our investigation helps us in a better understanding and implementation perspective of the proposed system, as the outcomes of our analysis adds to the precision and accuracy of the entire system.

Keywords: Biomedical sensor; cavity optomechanics; spectroscopy; relative intensity noise; semiconductor laser diode

1 Introduction

In view of the health circumstances at present times, numerous techniques are being developed to counteract these diseases [1–3]. As the primary focus is human health, research remains concentrated towards various factors [4–10]. One of them is the air that is being exhaled from the human lungs. Information regarding numerous diseases can be ascertained with the help of this air. One of the underlying techniques that can be used for this purpose is spectroscopy, which aids in the analysis of spectrum of a substance of interest [11–14]. It has been found that this has



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lead to significant work in terms of research in physical and biological sciences [9,15–17], with much more potential on the way.

Semiconductor lasers have become a major focus of attention in the past decades, on account of their multiple applications in the biomedical sensors [18–20]. The medical experts have found diversified uses in the operations and surgical procedures in the hospitals [21–23]. The main reasons for their uses are precision, accuracy, and the exploration thresholds which had earlier not been possible [24,25]. The ongoing work shows promising future for the remedy of various diseases that had not been possible until now. A double-blinded placebo-controlled clinical trial has been successfully done in the near infra red regime [26]. Hair removal techniques [27,28] have been improved and precise ever since lasers have come into play by the surgeons. On account of these reasons, we resort to engage the lasers in infra red regime for the anticipated investigation and treatment of numerous diseases that can be prevalent in elder citizens.

Our work stems from the theory of intracavity absorption spectroscopy in which a substance of interest is placed inside the laser cavity [29–31]. Work in this connection has verified that this method is much sensitive as compared to intercavity spectroscopy, a fact that makes it an optimal choice for a biomedical sensor. We have explored this task in terms of the current work in which an optical system is being developed. To explore this principle further, our attempt is to use two modes (wavelengths). There are a few but strong technical grounds for that. First, the use of single mode does not yield very efficient results. Therefore, a system with two modes is better. Use of various modes can be very expensive, as well as complex. This is not desired as the setup is destined for a biomedical system. In view of these, this work endeavours to use a system that contains two modes, an idea that has not been anywhere else till now [9,15–17].

2 Measurement Setup and Related Issues

The laboratory system for this work has been elaborated in Fig. 1. This contains a Semiconductor Optical Amplifier (SOA) from which light is emitted in both directions in the Near Infra Red (NIR) range. To intensify its output, the principle of optical reflection [17,32] has been created with the aid of loop mirror on one side. Thus the output is provided into two Fiber Bragg Gratings (FBGs), namely FBG_i (FBG_l/FBG_1) and FBG_o (FBG_h/FBG_2). These are in reference to the inner (lower wavelength) and outer (higher wavelength) cavities respectively. These are separated with the help of optical couplers VC_i and VC_o which distinguish the two wavelengths (modes) M_i and M_o respectively.

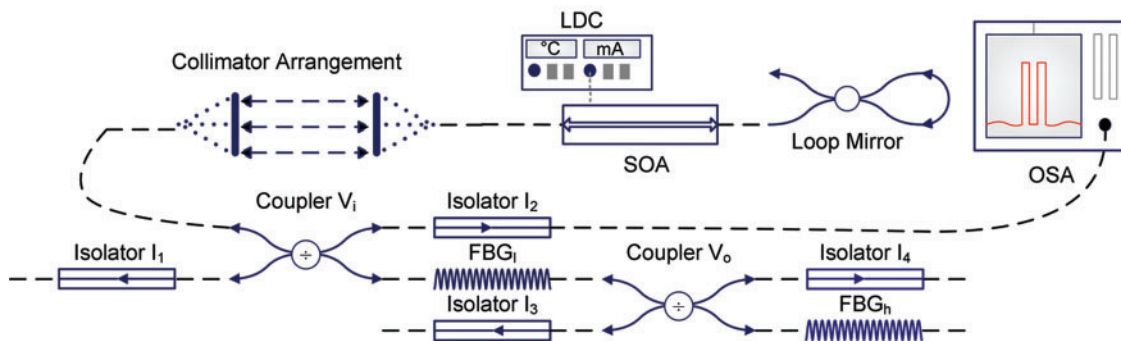


Figure 1: Experimental setup of the sensor laser under investigation [17]

The SOA is supplied with injection current from the Laser Diode Controller (LDC) which also controls the temperature. The collimator is the sample holder where the substance of interest can be placed. Isolators ensure unidirectional flow of optical light, for instance into the Optical Spectrum Analyzer (OSA) for the sake of measurement purpose [13,33–36].

The photodiode collects the light from the laser diode sensor. The electrical signal output from the photodiode contains DC signal as well as AC signal. To prevent saturation of the RF amplifier, the DC signal is filtered by using high frequency bandwidth Bias Tee. The DC signal from Bias Tee is measured using Digital Multimeter (DMM) and is equal to the average photocurrent I_p , which is proportional to the mean optical intensity. The AC signal which is proportional to the intensity noise of the laser is amplified by Low Noise Amplifier (LNA). It is displayed and measured using radio frequency Electrical Spectrum Analyzer (ESA) whose attenuator can be set at 0 dB for high sensitivity measurement. The ESA [36] has a minimum resolution bandwidth of 10 Hz and typical noise figure of 21 dB@3 MHz resolution bandwidth.

3 Technical Description and Analysis of the Hardware

In order to understand the experimental setup, the equipment and the software used must be analyzed. Here the operation of the optical components and their control must be specifically addressed [37]. We perform an in-depth characterization of SOA in this work. The measurement results of the characterization routines provide the basis for the operation and the performance of the sensor.

3.1 The Semiconductor Optical Amplifier

It is important to understand the technical perspective of the SOA. In the proposed system, this is the source of light as well as the amplifier which increases the output intensity. The principle is similar to an active material in a laser which uses a constant fraction of the injected electrons to emit a certain number of photons at a specified value of pumping current [32,35]. In this way, both modes in the laser receive injection current, thereby giving rise to a competition between them.

A C-band SOA1117S/P from Covega [35,36] has been used as an SOA. It is a non-linear, polarization-independent semiconductor optical amplifier which is packaged in a 14-pin butterfly housing. It has an operating current range until 600 mA, and wavelength range from 1528 to 1562 nm. At 1550 nm, the typical saturation output power is 9 dBm, small signal gain of 20 dB (for input power of -20 dBm), gain ripple of 0.2 dB, polarization dependent gain of 1 dB, Noise Figure of 10 dB, and a forward voltage of 1.4 V. With the help of the LM14S2 Thorlabs holder [37], the semiconductor optical amplifier is clamped and can be connected using two 9-pin D-sub connectors with a laser and temperature controller. For this purpose, the laser controller LDC-3900 from ILX Light wave has been used [38]. This comprises a controllable current source (Model: 39400, capable to provide up to 4 A), and a 32 watt thermoelectric controller (Model: 39034).

The semiconductor optical amplifier is controlled by the laser controller LDC-3900. This in turn has a GPIB (IEEE-488) interface. Thus, the injection current for the semiconductor amplifier and its temperature can be controlled by a PC. The communication is done via the standard VISA interface. VISA (Virtual Instrument Software Architecture) which is an industry standard of various test and measurement equipment manufacturers such as Rohde & Schwarz, Agilent, National Instruments and Tektronix [38,39]. For the implementation of the VISA communication, LabVIEW (version: 18.0.1) [40] is used.

Before the use of an SOA in the overall system, its behaviour with respect to its injection current and temperature must be known. For this purpose, we used the spectrum of the SOA as a function of the injection current and temperature is recorded at the Optical Spectrum Analyzer (OSA), which is Yokogawa model AQ6370C [39]. In order to ensure the accuracy of the device behaviour, the spectrum has to be measured many times. To meet this requirement, Algorithm 1 for the automated characterization of the semiconductor amplifier is designed and implemented in Lab VIEW. This has the pronounced advantage in the sense that the characterization can be performed autonomously with a very high resolution, thereby refraining from continuous manual experimentation. The algorithm is so designed that it can be implemented in any programming language [38,41].

For the practical implementation of the characterization procedure in this work, the parameters used are given in Tab. 1. Here v_{SOA} is the temperature of the controller, and I_{inj} is the pumping current of the SOA. λ_{SOA} is the wavelength range of the spectrum analyzer in which the spectrum is being recorded. The corresponding algorithm is provided in Tab. 2.

Table 1: List of parameters and their values

No.	Parameter	Start	Stop	Step size
1	v_{SOA}	10°C	30°C	1°C
2	I_{inj}	1 mA	550 mA	1 mA
3	λ_{SOA}	1450 nm	1650 nm	0.04 nm

Table 2: Algorithm 1 Pseudo code for the characterization procedure of an SOA

```

1: Define  $I_{Start}$ ,  $I_{Stop}$ ,  $I_{Step}$ ,  $v_{Start}$ ,  $v_{Stop}$ ,  $v_{Step}$ 
2:
3: for  $v_{Set} = v_{Start}$ ,  $v_{Start} + v_{Step}$ , ...,  $v_{Stop}$  do
4:   for  $I_{Set} = I_{Start}$ ,  $I_{Start} + I_{Step}$ , ...,  $I_{Stop}$  do
5:     Send  $v_{Set}$ ,  $I_{Set}$  to Laser Controller
6:     Wait till Laser controller is adjusted
7:     Measure the Spectrum (OSA)
8:     Transfer Spectrum  $\rightarrow$  Computer
9:   end for
10: end for

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3.2 Evaluating the Characterizing Measurements of the SOA

Due to the amount of data which is needed for evaluation, the characterization is implemented as a script in Python. It is characterized by particularly a simple structure, few keywords and a simple syntax. Furthermore, it has an object-oriented semantics, whereby a good program readability is achieved in this manner. Moreover, Python is under the GPL (General Public License) and is therefore also available free for commercial use, thereby justifying one of the reasons of our biomedical system.

For the evaluation of the measured data of the SOA, two separate scripts have been written. The first script reads sequentially a series of measurements and analyzes this relative half-width, red shift, blue shift and laser fine structure (so called gain ripple) from this data. The analyzed data is then stored in separate ASCII files into the directory of the script.

The second script loads the previously saved files and restores the data analyzed using the Matplotlib extension for Python graphical form. The behaviour of the maximum wavelength λ_{max} with the pumping current I_{inj} at four temperatures is shown in Fig. 2. It shows that with increasing pumping current I_{inj} , maximum wavelength λ_{max} of the SOA's broadband spectrum moves to shorter wavelengths. This behaviour is called blue shift.

Fig. 2 also shows that certain wavelengths are independent of injection currents than others. This can be an effect of the multi-quantum well structure of the SOA which is being used. Another explanation could be that during these measurements, only the spectrum in each wavelength is used at its maximum intensity. By using a Pseudo-Voigt [42] or Gaussian distribution fit [43] to the spectra, we obtain a much smoother relationship, as shown in Fig. 3. The gray area marks the area around the operation at a pump current of about 450 mA. If we are in this part of the graph and change the injection current up to ± 10 mA, the change in wavelength is smaller than 1 nm. The figure also shows that within this part of the graph, a change in temperature has significantly greater impact on the wavelength as compared to a change in the injection current.

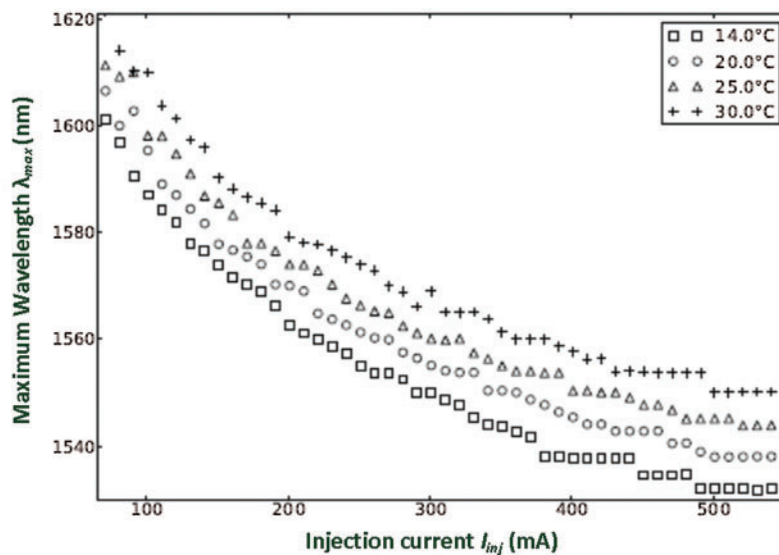


Figure 2: Comparison of the maximum wavelength λ_{max} with the injection current I_{inj}

The dependence of the temperature on the wavelength is shown in Fig. 4. The maximum wavelength λ_{max} is nearly linearly dependent on the temperature. This behaviour is also called red shift.

The physical effects that are responsible for the blue-and red-shifts in an SOA, would exceed the theoretical framework of this work and are therefore not pursued further here. Instead, these phenomena are in accordance with the red shift [44] and blue shift [6,41,45–47] investigated earlier.

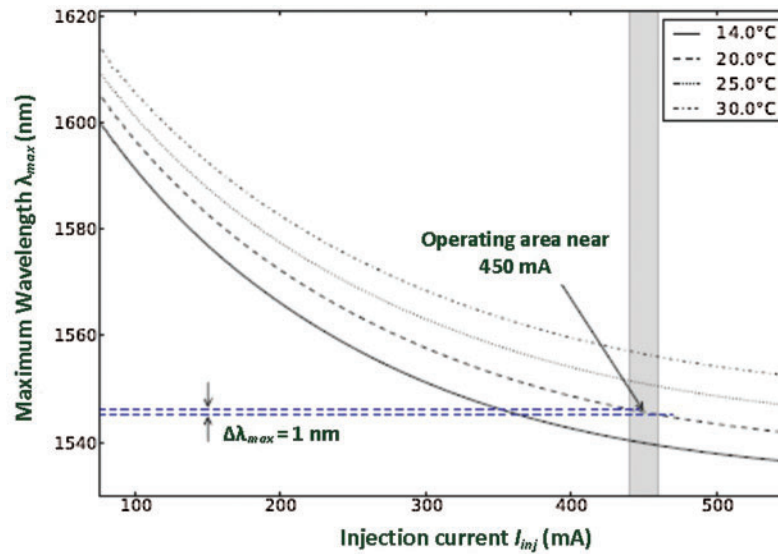


Figure 3: Behaviour of the maximum wavelength with the pumping current, matched by pseudo-Voigt function spectra. The gray area denotes the working area of the SOA. At an operating temperature of 20°C we have a change in the maximum wavelength of about 1 nm

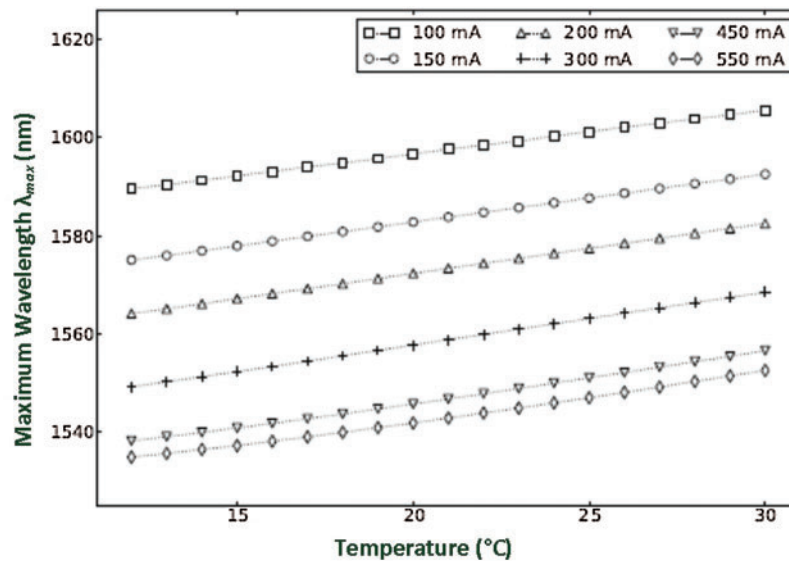


Figure 4: Behavior of the maximum wavelengths with respect to the temperature, matched by the pseudo-Voigt function spectra

Much more important are the gradients of the red and blue shifts. These minor drifts can significantly affect the stability of the control loop at a later stage and must be brought into information [48,49].

Thus it can be stated at this level that a shift in the temperature at an operating point has significantly greater impact on the intensity than a drift of the pumping current at the same

operating point. It is now imperative with this information and algorithm to do a frequency dependent calibration of the system.

4 Calibration Results and Discussion

The determination of the frequency response of optical receiver noise is very important in order to validate RIN calculation of different lasers. For this purpose, we use the setup presented in Fig. 5. The optical output from the laser system VC_i is going into the attenuator which is fed into the optical receiver. The receiver consists of a PIN-Photodiode (PIN-PD), a Bias-Tee and a Low Noise Amplifier (LNA). The PIN-PD collects the light from the laser diode. The incoming PD signal has DC and AC components. The former is directly proportional to the average optical power input to the photodiode. On the contrary, the noise components from the PD and LDC comprise the AC counterpart. The Bias Tee (filtering abilities), separates the DC from AC, which is found by the digital multimeter having a low input impedance. As the strength of AC signal is not strong, LNA intensifies it and adds noise inherently, whose intensity is straight away dependent on the amplifier's noise figure. In this way, this value of noise is obtained at the ESA. One output from the receiver goes to the Electronic Spectrum Analyzer (ESA) (from the LNA terminal), and the other one goes to the Voltmeter (through the Bias-Tee terminal). The complete mathematical details and interpretation can be found in [17,48,49].

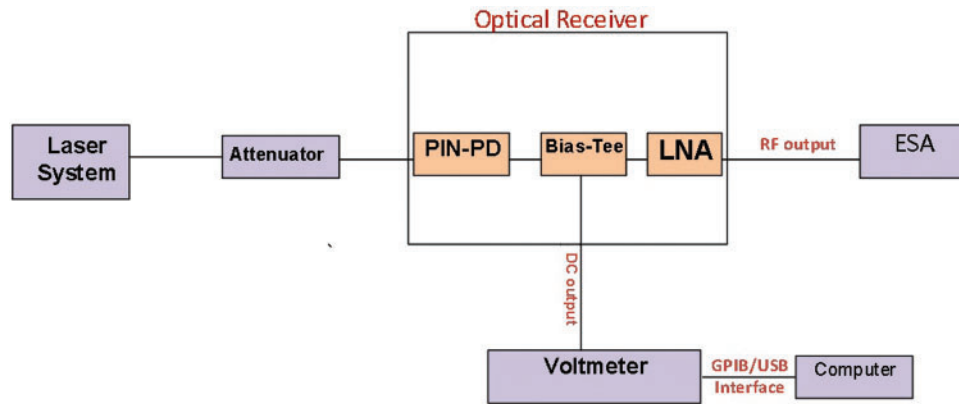


Figure 5: Setup for optical receiver characterization

In our work, we approach the system RIN into a Poisson or Shot noise component using a RIN standard expression for the frequency dependent calibration factor (κ). This includes all noise added by the receiver front end [50,51]. This method regulates the response of our RIN system to the input RIN of the laser under consideration. This is achieved by using a laser which emits coherent beam of constant intensity (Poisson laser) with a variable optical attenuator. In this way, we express this approached for the frequency dependent calibration κ as

$$\kappa(\omega) = \frac{2qV}{\delta P_p \omega},$$

where, δP_p is the RF-noise power measured from ESA, q is the electrical charge while V is the DC voltage which is represented as $V = IR$, R is the load resistance and I is the photocurrent in the electrical circuit represented as $I = \rho P_o = \eta qP/h\nu$, where ρ is the responsivity, η is the quantum efficiency, h is the Plank's constant and ν is the frequency of the photo-detector

respectively [52,53]. Moreover, the calibration of the RIN system can be performed with a Poisson limited laser without knowing the RIN explicitly [54,55]. The frequency dependent calibration method was chosen for characterizing our optical receiver setup because of its simplicity and accuracy.

4.1 Amplitude Analysis with Frequency

Fig. 6 shows the result of our measurement taken from ESA. The variation of the intensity noise in dBm for different values of attenuated power ranging from 80 to 200 μW against frequency in GHz has been shown. It is observed that the amplitude increases with an increase in frequency, attains a maximum value and then starts to decrease. This trend is for all values of attenuated power with the highest values being found at 120 μW . This implies an increased sensitivity of the laser at this value reflecting the sensor's principle.

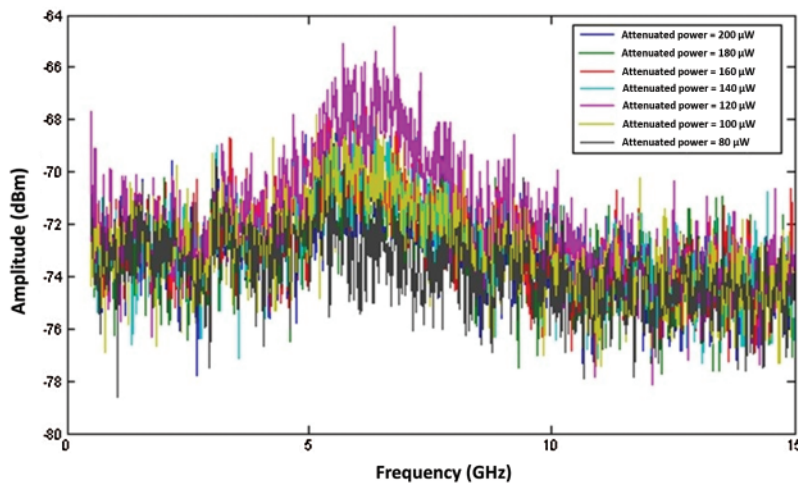


Figure 6: Amplitude vs. frequency at different attenuated powers

4.2 Variation of Calibration Factor κ with Frequency

Fig. 7 shows a graph of the frequency dependent calibration function κ obtained for the optical system under consideration at an optical power of 200 μW . The graph shows a linear increase of κ with frequency after some particular frequency (around 7 GHz). At a frequency range (around 5.4 to 6.5 GHz) the graph shows a dip. At lower frequencies κ shows more oscillations as compared to the situation at higher frequencies. This sort of variation of κ with frequency is likely due to the fact that the amplifier gain and bias tee performance are frequency dependent.

Fig. 8 shows the κ obtained for another optical power at 160 μW . This plot also shows a similar behaviour of the plot explained above. The behaviour was observed for several attenuated power ranging from 200–80 μW , for instance one is presented in Fig. 9. Fig. 10 provides the comparison between the values of κ obtained for three different optical powers at 100, 160 and 200 μW . The similarities of different curves show that the system is stable and at different powers of κ shows a common behaviour for the selected frequency range. In continuation with the same trend, Fig. 11 shows the difference between the values of κ at an optical power of 300 and

500 μW for the given frequency range. A mean difference of 0.58 dBm between these values of κ has been found. However, κ follows a constant behavior, but the exact values are different.

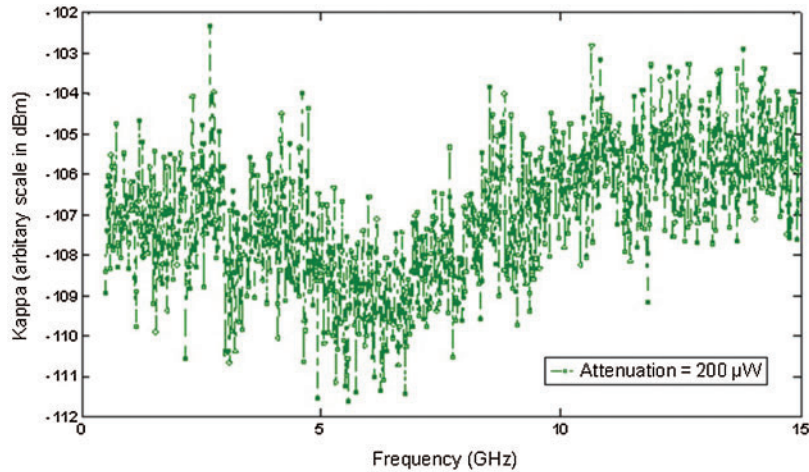


Figure 7: Calibration factor κ vs. the frequency at an optical power of 200 μW

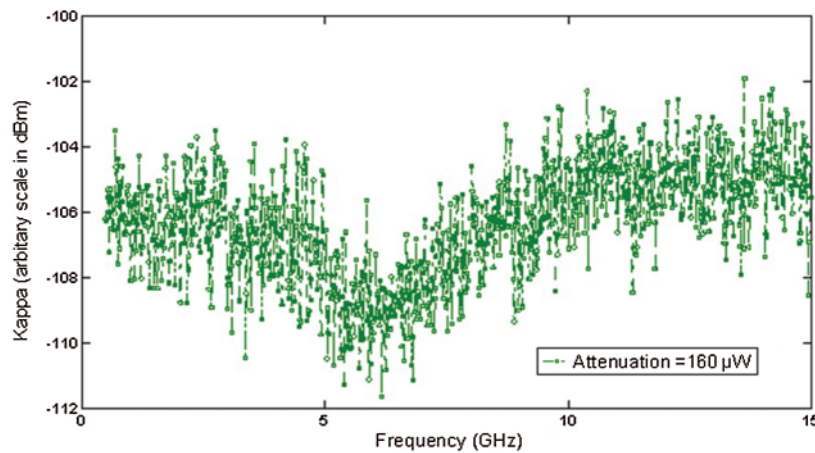


Figure 8: Calibration factor kappa κ vs. the frequency at an optical power of 160 μW

4.3 Comparison of RIN Results

In order to analyze the performance of our method, we compare the RIN of our system with that of the Agilent measurement setup [56]. The results have been shown in Fig. 12 where we can observe a significant difference. It can be clearly seen that the value of average RIN is greater for the system that we have developed in the laboratory. This means that the system can be used to provide sensitive information in an economic manner once the biomedical sensor is put in practice. Therefore, these findings are consistent with the results that have been earlier brought in [57] with the technical reasons hitherto.

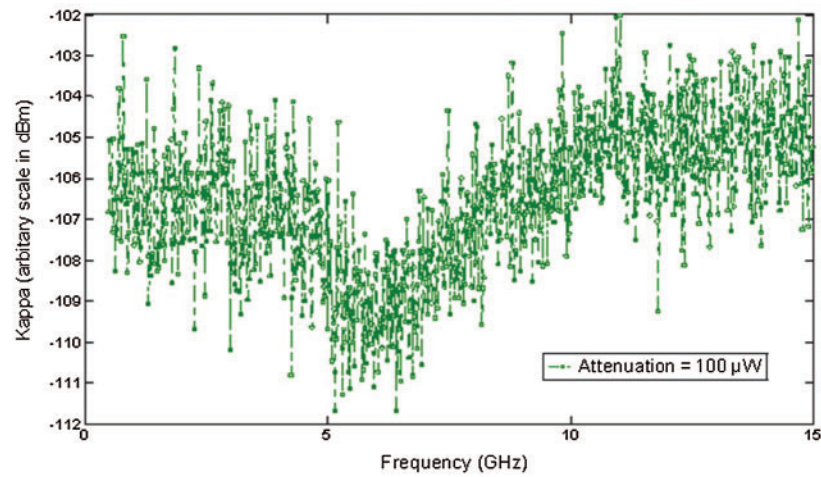


Figure 9: Calibration factor κ vs. the frequency at an optical power of 100 μ W

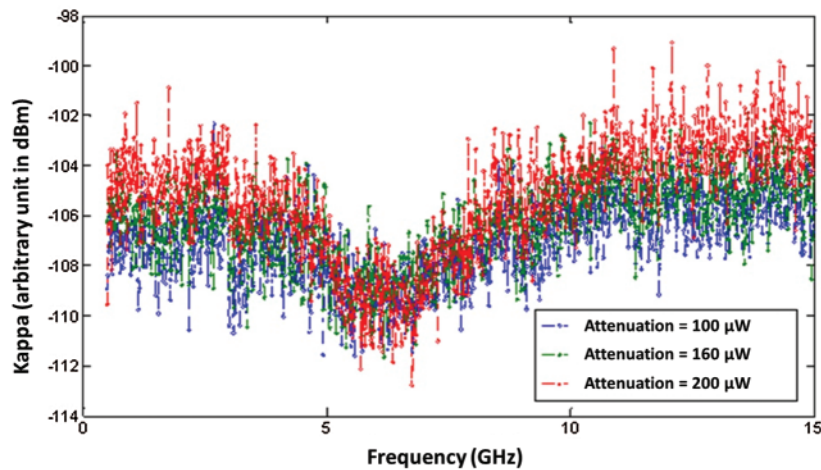


Figure 10: Calibration factor κ vs. the frequency at optical powers of 100, 160 and 200 μ W

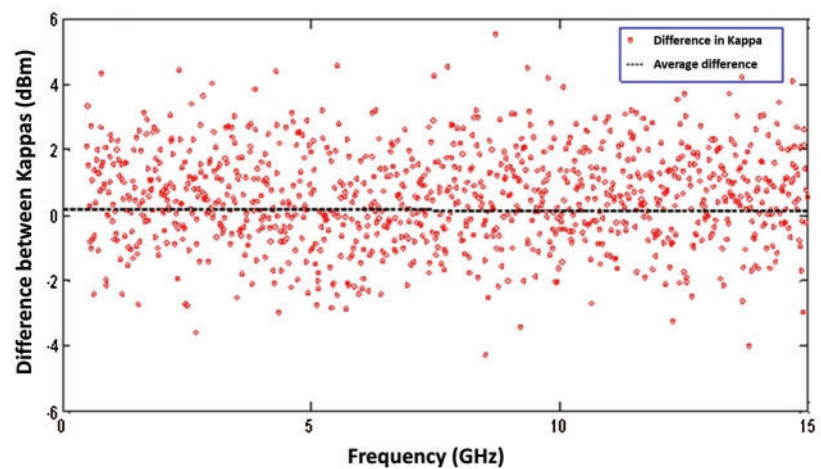


Figure 11: Difference between the kappas κ at the optical power values of 300 and 500 μ W for different frequencies

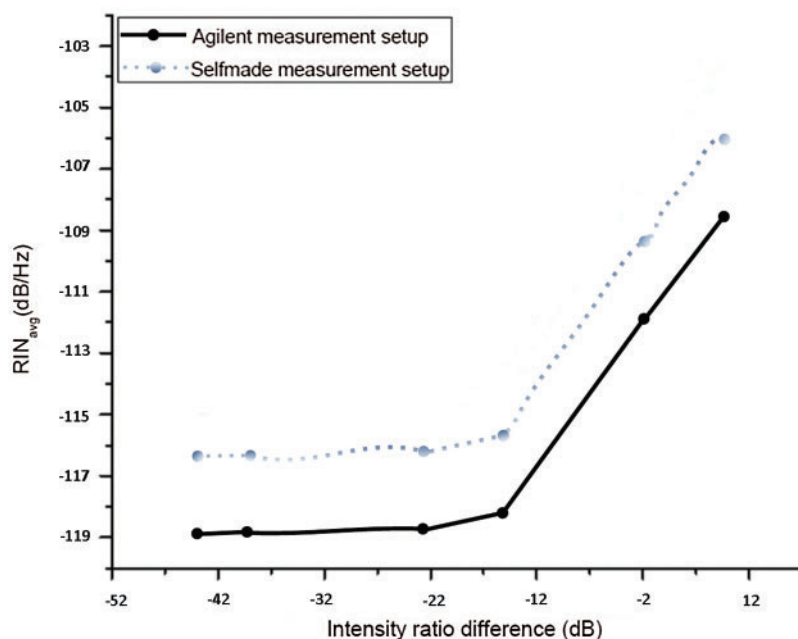


Figure 12: Comparing average RIN from both measurement setups

Table 3: List of symbols

OSA	Optical Spectrum Analyzer
ESA	Electrical Spectrum Analyzer
SOA	Semiconductor Optical Amplifier
LNA	Low Noise Amplifier
VC _i /VC1	Variable Coupler corresponding to the inner cavity
VC _o /VC1	Variable Coupler corresponding to the outer cavity
M _i /M1	Mode corresponding to the inner cavity
M _o /M1	Mode corresponding to the outer cavity
h	Planck's constant
I	Output photocurrent
I_d	Dark current
I_p	Average photocurrent
P	Power; energy flow per unit time
Kappa κ	Frequency dependent calibration factor
δP_p	RF-noise power measured from ESA
q	Electrical charge
η	Quantum efficiency
λ	Wavelength of light
λ_B	Bragg wavelength
ω	Angular frequency
ρ	responsivity
RIN	Relative Intensity Noise
I_{inj}	Injection current
I_{th}	Threshold current
PIN-PD	PIN-Photodiode
LNA	Low Noise Amplifier

5 Conclusion

The current experimental analysis provides an investigation of a biomedical sensor for human health. The laser setup must be analyzed in depth for all the components. Therefore, the SOA has been investigated in detail in terms of characterization, calibration and technical analysis. Using the proposed algorithm and the set of defined parameters, the system has been evaluated in terms of the variation of the maximum wavelength with the injection current in a prescribed range of temperature, thereby providing worthwhile information regarding its red-shift and blue-shift.

A detailed test of the proposed technique and a simple description of the implementation complete this task. The whole procedure took quite some time, as it was performed under the stated experimental conditions. Here the system performance is explained on the basis of the RIN of the receiver system. We analyze the performance of the optical receiver for a frequency range up to 15 GHz by using the theoretical formulation of frequency dependent calibration function κ . It was observed from the experimental results that at lower frequencies, κ shows more oscillations as compared to the higher frequencies. We also found that the frequency dependent calibration factor κ has a common characteristic behaviour, which follows for different optical powers. This system calibration factor will naturally account for the frequency responsivity, gain, noise, mismatch losses, resolution bandwidth etc., of the system across the whole measurement range, which will be some of the extensions [58,59] for the future work. Tab. 3 provides a list of acronyms that have been used in this work.

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Conflicts of Interest: The authors declare that they have no conflicts of interest to report about the present study.

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