

Throughput Enhancement for NOMA Systems Using Intelligent Reflecting Surfaces

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Abstract: In this article, we optimize the powers associated to Non Orthogonal Multiple Access (NOMA) users, sensing and harvesting duration for Cognitive Radio Networks (CRN). The secondary source harvests energy from node A signal. Then, it senses the channel to detect primary source. Then, the secondary source transmits a signal that is reflected by Intelligent Reflecting Surfaces (IRS) so that all reflections have a zero phase at any user. A set Ii of reflectors are associated to user Ui. The use of M = Mi = 512, 256, 128, 64, 32, 16, 8 reflectors per user offers 45, 42, 39, 36, 33, 30, 27 dB gain *vs.* the absence of IRS. We also suggest the use of IRS in energy harvesting. The use P = 8 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain *vs.* one IRS M = Mi = 8 and the absence of IRS. The use of P = 16 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 9 and 42 dB gain *vs.* one IRS M = Mi = 8 and the absence of IRS.

Keywords: CRN; NOMA; spectrum sensing; energy harvesting; throughput maximization

1 Introduction

IRS are used to maximize the throughput of wireless systems as all reflections have a zero phase at the destination [1–5]. The phase of the p-th reflector is computed using the phase of channel gains of the links between the source and IRS as well as that of the link between IRS and the destination [6–8]. IRS have been used in NOMA systems where a set Ii of reflectors are associated to user Ui [9]. The results of [9] are not valid for CRN as a single network was studied without energy harvesting and spectrum sensing. IRS have been deployed to maximize the throughput of millimeter wave and optical systems [10–12]. The asymptotic behavior of wireless systems using IRS was derived in [13–16]. Experimental results of IRS were provided in [17–19]. Continuous reserve skyline queries in Wireless Sensor Networks (WSN) was proposed in [20]. A self adaptive multivariate data compression with error bound was proposed in [21] for WSN. A particle swarm optimization was used in [22] to enhance the coverage in WSN. A hamilton loop based data collection algorithm can also be used in WSN [23].



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Optimal coverage using multipath scheduling scheme was suggested in [24]. In [25], asynchronous clustering has been combined with data gathering scheme for WSN. In [26], the authors proposed a power efficient gathering technique in sensor information systems. A minimal connected dominant set was optimized in [27] to enhance WSN routing protocol. Coverage and network connectivity were optimized in [28] for mobile sensor networks.

In this article, we optimize NOMA powers, sensing and harvesting durations to maximize the throughput. After energy harvesting from node A signal, secondary source SS senses the channel to detect primary activity. When no activity is detected, the secondary source transmits a signal that is reflected by IRS so that all reflections have a zero phase at any NOMA user. A set Ii of reflectors are associated to user Ui. The use of M = Mi = 512, 256, 128, 64, 32, 16, 8 reflectors per user offers 45, 42, 39, 36, 33, 30, 27 dB gain *vs.* wireless systems without IRS [29]. We also improve the energy harvesting process using IRS between A and SS. In this case, energy harvesting uses reflected signals with zero phase at SS. A second IRS contains different sets of optimized reflectors to deliver reflections with a zero phase at any user Ui. The use P = 8 reflectors for energy harvesting and M = Mi = 8 and the without IRS [29]. Using P = 16 reflectors for energy harvesting and M = Mi = 8 and the without IRS [29]. Using P = 16 reflectors for energy harvesting and M = Mi = 8 and the without IRS [29]. Using P = 16 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain vs. one IRS M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain vs. one IRS M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain vs. one IRS M = Mi = 8 reflectors per user for data communications offers 9 and 42 dB gain vs. one IRS M = Mi = 8 and the absence of IRS [29].

Next section optimizes the NOMA powers, sensing and harvesting durations. Section 3 improves the energy harvesting process using IRS. Section 4 gives some results and Section 5 concludes the paper.

2 Throughput Analysis with a Single IRS

2.1 System Model

In Fig. 1, there are a Primary Destination and Source PD and PS, a Secondary Source SS and K secondary users, node A and IRS used as a reflector. In the first phase, energy harvesting is performed at SS over μ T s using the signal of A where T is frame length in s and $0 < \mu < 1$. Then, SS senses the channel over $(1-\mu)\zeta$ T s using samples of the received signal from PS. When PS is inactive, SS broadcasts a signal to K NOMA users over $(1-\mu)(1-\zeta)$ T s. The aim of the paper is to optimize the powers of NOMA users as well as sensing and harvesting durations throughput the parameters μ and ζ to maximize the total throughput while using intelligent reflecting surfaces.



Figure 1: Network model

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2.2 Energy Harvesting Without IRS

The harvested energy is given by

$$E = \beta \mu T P_A |f|^2 = \beta \mu L_0 E_A |f|^2 \tag{1}$$

where β is an efficiency coefficient, $P_A = E_A/T_s$ is the power of A, Ts is the symbol duration, f is channel gain from A to SS, $L_0 = T/T_s$. We can write $E(|f|^2) = 1/dAS_s^{ple}$ where d_{XY} is the distance from X to Y and ple is the path loss exponent.

The symbol energy of S_s is computed as:

$$E_{ss} = \frac{E}{L_0 (1 - \mu) (1 - \zeta)} = \frac{\beta \mu E_A |f|^2}{(1 - \mu) (1 - \zeta)}$$
(2)

In Fig. 1, the users are ranked as follows: U1 is the strong user, Ui is the i-th strong user and UK is the weak user. The transmitted NOMA symbol by S_s is equal to

$$s = \sqrt{E_{SS}} \sum_{i=1}^{K} PO_i s_i, \tag{3}$$

si is the symbol of user Ui and $0 < PO_i < 1$ is the power allocated to Ui such that $0 < PO_1 < PO_2 < \cdots$

$$< PO_K < 1 \text{ and } \sum_{i=1}^{n} PO_i = 1.$$

Let hp be the channel from S_s to p-th IRS reflector. Let gp be the channel from p-th IRS reflector to Ui. Ii is a set of reflectors associated to Ui and contains Mi = |Ii| reflectors. We have: $E(|hp|^2) = 1/dSSIRS^{ple}$. Furthermore, we have $E(|gp|^2) = 1/dIRSUi^{ple}$.

We have hp = apexp(-jbp) where ap = |hp|. $E(aq) = \Gamma(m + 0.5)/[\Gamma(m)\sqrt{Md_{SSIRS}^{ple}}]$ and $E(aq^2) = 1/d_{SSIRS}^{ple}$ [30]. We have gp = cpexp(-jep) where cp = |gp| and ep is the phase of gp. We have $E(cq) = \Gamma(m + 0.5)/[\Gamma(m)\sqrt{Md_{IRSU}^{ple}}]$ and $E(aq^2) = 1/d_{IRSU}^{ple}$ [30].

The phase of p-th reflector is equal to [1]

$$\mathbf{p} = \mathbf{b}\mathbf{p} + \mathbf{e}\mathbf{p}.$$

The received signal at Ui is given by

$$r_i = s \sum_{i \in I_i} h_p g_p exp\left(-j\varphi_p\right) + n_i,$$
(5)

where ni is a Gaussian r.v. of variance N0.

Eq. (3) gives

$$r_i = s \sum_{i \in Ii} a_p c_p + n_i = \sqrt{Y_i} s + n_i, \tag{6}$$

where

 φ

$$Y_i = E_{ss} F_i^2 \tag{7}$$

$$F_i = \sum_{i \in I_i} a_p c_p,\tag{8}$$

(4)

In (6), we notice that the phase shifts of reflectors given in (4) have been chosen so that all reflections have a zero phase at user Ui.

Using (2), we deduce

$$Y_{i} = F_{i}^{2} \frac{\beta \mu E_{A} |f|^{2}}{(1-\mu)(1-\zeta)}$$
(9)

Fi follows a Gaussian distribution with mean $mFi = Mi \Gamma(m + 0.5)^2 / [\Gamma(m)^2 d_{SSIRS}^{ple/2} d_{IRSUi}^{ple/2}]$ and variance $\sigma Fi^2 = M / [d_{SSIRS}^{ple} d_{IRSUi}^{ple}] [1 - \Gamma(m + 0.5)^4 / Mi^2 / \Gamma(m)^4]$. Therefore, Fi² has a non-centralchisquare distribution with degree of freedom one. For Rayleigh channels, $|f|^2$ has also a centralchisquare distribution with degrees of freedom 2 m. Therefore, Yi is the product of a non-central and a central chisquare random variables and we have [31]

$$P_{Y_{i}}(x) = P(Y_{i} < x) = \frac{e^{-0.5} \frac{m_{\chi}^{2}}{\sigma_{\chi}^{2}}}{\Gamma(m)} \sum_{q=0}^{+\infty} \frac{\left(\frac{m_{\chi}^{2}}{\sigma_{\chi}^{2}}\right)^{q}}{2^{q} \Gamma(q+0.5)} G_{1,3}^{2,1}\left(\frac{N_{0}(1-)(1-\zeta) xmd_{ASS}^{ple}}{2\beta\mu E_{A}}|_{q+0.5,m,0}\right), \quad (10)$$

where $G_{n,m}^{p,l}(x)$ is the Meijer G-function.

We deduce

$$r_i = \sqrt{Y_i} \sum_{j=1}^{K} PO_j s_j, + + n_i$$
(11)

2.3 Signal to Interference Plus Noise Ratio (SINR) and Throughput Analysis

Ui performs Successive Interference Cancelation (SIC) and detects first s_K since $PO_K > PO_i$. The corresponding SINR is

$$\Gamma^{i \to K} = \frac{Y_i P O_K}{N_0 + Y_i \sum_{p=1}^{K-1} P O_p}$$
(12)

The contribution of the detected symbol sK is removed and Ui estimates s_{K-1} with the following SINR

$$\Gamma^{i \to K-1} = \frac{Y_i P O_{K-1}}{N_0 + Y_i \sum_{p=1}^{K-2} P O_p}$$
(13)

The process is continued by detecting sl with SINR

$$\Gamma^{i \to l} = \frac{Y_i P O_l}{N_0 + Y_i \sum_{p=1}^{l-1} P O_p}$$
(14)

The probability of an outage event at Ui is computed as

$$Pout, i (x) = 1 - P(\Gamma^{i \to i} > x, \dots, \Gamma^{i \to K} > x)$$
$$= P_{Yi} \left(max_{i \le l \le K} \frac{N_0 x}{PO_l - x \sum_{p=1}^{l-1} PO_p} \right)$$
(15)

where $P_{Y_i}(y)$ is provided in (10). In Eq. (15) $\Gamma^{i \to l} > x$ corresponds to $Y_i > \frac{N_0 x}{PO_l - x \sum_{p=1}^{l-1} PO_p}$. Therefore, Yi should be larger than the maximum of these values for l = i, ..., K which is $max_{i \le l \le K} \frac{N_0 x}{PO_l - x \sum_{p=1}^{l-1} PO_p}$

The Packet Error Probability (PEP) at Ui is equal to [32]

$$PEPi(PO1, PO2, \dots, POK, \mu, \zeta) < P_{outage}(T_0)$$
(16)

where T_0 is defined as [12]

$$T_{0} = \int_{0}^{+\infty} 1 - \left[1 - 2\left(1 - \frac{1}{\sqrt{Q}}\right) erfc\left(\sqrt{\frac{3ulog_{2}\left(Q\right)}{2Q - 2}}\right)\right]^{PL} du,\tag{17}$$

where PL is packet length.

The total throughput is equal to

$$Thr (PO_{1}, ..., PO_{K}, \mu, \zeta) = (1 - \mu) (1 - \zeta) \log 2 (Q) Pidle (1 - Pf) \\ \times \sum_{i=1}^{K} [1 - PEP_{i} (PO_{1}, ..., PO_{K}, \mu, \zeta)]$$
(18)

where Pf is the probability of a false alarm

$$P_{f} = \frac{\Gamma\left(\lfloor (1-\mu)\,\zeta L0\rfloor, T1/2\right)}{\Gamma\left(\lfloor (1-\mu)\,\zeta L0\rfloor\right)},\tag{19}$$

where T1 is the energy detector threshold

The powers of NOMA users, sensing and harvesting durations μ and ζ are optimized as follows: $(PO_1^{opt}, \dots, PO_K^{opt}, \mu^{opt}, \zeta^{opt}) = \operatorname{argmaxThr}(PO_1, \dots, PO_K, \mu, \zeta)$ (20)

3 IRS to Enhance the Energy Harvesting Process

3.1 System Model

Fig. 2 shows that data transmission can use two IRS. IRS_1 contains P reflectors between A to SS to enhance the energy harvesting process. IRS_2 is between SS and users Ui with Mi reflectors to improve the throughput.



Figure 2: IRS used in energy harvesting

3.2 Energy Harvesting Using IRS

When energy harvesting uses IRS, we have

$$\mathbf{E} = \beta \mu \mathbf{L}_0 \mathbf{E}_{\mathbf{A}} \mathbf{C}^2,$$

(21)

where

$$Z = \sum_{p=1}^{P} \delta_p \eta_p \tag{22}$$

where $\delta p = |up|$, up is the channel from A to p-th IRS1 reflector and $\eta p = |vp|$, vp is the channel from p-th reflector of IRS1 to SS.

The mean and variance of C are equal to

$$m_{c} = \frac{P\Gamma(m+0.5)^{2}}{m\Gamma(m)^{2} d_{AIRS1}^{ple/2} d_{RS1SS}^{PLE/2}}$$
(23)

$$\sigma_{C}^{2} = \frac{P}{d_{AIRS1}^{ple/2} d_{IRS1SS}^{ple/2}} \left[1 - \frac{\Gamma \left(m + 0.5\right)^{4}}{M_{1}^{2} \Gamma \left(m\right)^{4}}\right]$$
(24)

We deduce

$$E_{ss} = \frac{E}{L_0 (1 - \mu) (1 - \zeta)} = \frac{\beta \mu E_A C^2}{(1 - \mu) (1 - \zeta)}$$
(25)

The variable Yi should be replaced by Zi written as

$$Y_{i} = F_{i}^{2} \frac{\beta \mu E_{A} C^{2}}{(1-\mu)(1-\zeta)}$$
(26)

where Fi is defined in (8).

Zi is the product of two non central chisquare r.v. Therefore, we have [31]

$$P_{Zi}(x) = e^{-0.5} \frac{m_{Fi}^2}{\sigma_{Fi}^2} e^{-0.5} \frac{m_C^2}{\sigma_C^2} \sum_{q=0}^{+\infty} \sum_{l=0}^{+\infty} \frac{\left(\frac{m_{Fi}^2}{\sigma_C^2}\right)^l \left(\frac{m_C^2}{\sigma_C^2}\right)^q}{2^{q+l}\Gamma\left(q+0.5\right)\Gamma\left(l+0.5\right)q!\,l!} \times G_{1,3}^{2,1}\left(\frac{N_0\left(1-\right)\left(1-\zeta\right)xm}{\beta E_A 2}|_{q+0.5,\,l+0.5,\,0}\right),$$
(27)

4 Numerical Results

Fig. 3 depicts the total throughput for K = 2 users, QPSK modulation, m-fading figure m = 2, $\beta = 0.5$, T1 = 1, dASS = 1.1, dSSIRS = 1.2, dIRSU1 = 1.1, dIRSU2 = 1.5 and ple = 3. We notice that the use of M = Mi = 512, 256, 128, 64, 32, 16, 8 reflectors per user offers 45, 42, 39, 36, 33, 30, 27 dB gain *vs.* the absence of IRS [29]. Fig. 3 corresponds to optimal PO_i, μ and ζ .

Figs. 4 and 5 compares the total throughput for M = Mi = 8, 16 with optimal μ and ζ to ($\mu = 1/3$, $\zeta = 1/2$). We observe that optimal harvesting and sensing duration μ and ζ offers a better throughput than ($\mu = 1/3$, $\zeta = 1/2$), ($\mu = 1/3$, optimal ζ) and (optimal μ , $\zeta = 1/2$).

Fig. 6 shows the total throughput for K = 3 users and 16QAM modulation, m-fading figure m = 2, T1 = 1, d = 1, dSSIRS = 1.2, dIRSU1 = 1.1, dIRSU2 = 1.3, dIRSU3 = 1.5. M = Mi = 512, 256, 128, 64, 32, 16, 8 reflectors per user offers 47, 44, 41, 38, 35, 32, 29 dB gain *vs.* NOMA without IRS [29]. In Fig. 6, we used an optimal powers as well as optimal μ and ζ .

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Figure 3: Total throughput for two users and QPSK



Figure 4: Total throughput for two users QPSK and M = 8



Figure 5: Total throughput for two users, QPSK and M = 16



Figure 6: Total throughput for three users and 16QAM

Fig. 7 depicts the throughput for M = Mi = 16 reflectors per user. We optimized NOMA powers in Fig. 7. We observe that optimal sensing and harvesting durations ζ and μ offers a better throughput than ($\mu = 1/3$, $\zeta = 1/2$), ($\mu = 1/3$, optimal ζ) and (optimal μ , $\zeta = 1/2$).



Figure 7: Total throughput for three users, 16QAM and M = 16

Fig. 8 shows the total throughput for the same parameters as Fig. 6. We have studied the effect of m-fading figure. For m = 3, we observe up to 8 and 2 dB gain vs. m = 1 and m = 2 that corresponds to Rayleigh channels.



Figure 8: Total throughput for three users, 16QAM and M = 16

In Fig. 9, we plotted the total throughput for K = 3 users and 16QAM modulation. The parameters are the same as Fig. 6. We have plotted the throughput when a energy harvesting uses IRS. The parameters are dAIRS1 = 1.1 and dIRS1SS = 1.3. The use P = 8 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain vs. one IRS M = Mi = 8 and without IRS [29]. The use of P = 16 reflectors for energy harvesting and M = Mi = 8 and without IRS [29]. The use of for 9 and 42 dB gain vs. one IRS M = Mi = 8 and without IRS [29].



Figure 9: Total throughput using two IRS: three users, 16QAM

5 Conclusion

In this article, we optimized the powers of NOMA users, sensing and harvesting duration for CRN. Secondary source senses the channel over $(1-\mu)\zeta T$ s to detect primary activity. If no activity is detected, SS broadcasts a signal during $(1-\mu)(1-\zeta)T$ s to NOMA users. The signal is reflected by Intelligent Reflecting Surfaces (IRS) towards K users. A set Ii of reflectors is associated to user Ui. The use of M = Mi = 512, 256, 128, 64, 32, 16, 8 reflectors per user offers 45, 42, 39, 36, 33, 30, 27 dB gain *vs.* wireless systems without IRS [29]. We also suggest the use of IRS in energy harvesting. The use P = 8 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 7 and 38 dB gain *vs.* one IRS M = Mi = 8 and without IRS [29]. The use of P = 16 reflectors for energy harvesting and M = Mi = 8 reflectors per user for data communications offers 9 and 42 dB gain *vs.* one IRS M = Mi = 8 and without IRS [29].

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