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ARTICLE



The Effect of the Gap Ratio on the Flow and Heat Transfer over a Bluff Body in Near-Wall Conditions

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ABSTRACT

In order to study the effect of different gap ratios on the thermofluid-dynamic field around a bluff body located in proximity to a heated wall, a series of experiments and numerical simulations have been conducted. The former were carried out using an open circulating water tank experimental platform and a single cylinder and square column as geometrical models (their characteristic length being D). The latter were based on the well-known SIMPLE algorithm for incompressible flow. The results show that the gap ratio is an important factor affecting the wake characteristics of near-wall bluff bodies. When the gap ratio is small, the influence of the wall on the bluff body wake is large. With an increase in the gap extension, periodic vortex shedding is enabled and heat transfer is strengthened accordingly; in addition, the vortex shedding period is larger for the square column. The square column displays hysteresis compared with the cylinder at the same gap ratio (the critical gap ratio of cylinder is $0.2 \sim 0.4$, while that of square column is $0.4 \sim 0.6$).

KEYWORDS

Transition flow; gap ratio; near-wall; flow characteristic; enhanced heat transfer

Nomenclature

1 (omenenata	
\overline{Cf}	Time-spatial averaged Skin Friction Coefficient
$\overline{Cf_t}$	Time-averaged Skin Friction Coefficient
Cp	Specific heat capacity
D	Characteristic length of model
k	Thermal conductivity
L	Gap between the model and wall
L/D	Gap ratio
Nu	Time-spatial averaged Nusselt Number
$\overline{Nu_t}$	Time-averaged Nusselt Number
Р	Pressure
Re	Reynolds Number
Reg	Grid Reynolds Number
Т	Temperature of fluid
t	Time



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Uin	Mainstream velocity
$\Delta X_{\rm max}$	The maximum grid size
ΔX_{\min}	The minimum grid size

Greek Symbols

δ	Thickness of the boundary layer
ρ	Density of fluid
μ	Dynamic viscosity
ϕ	Transport variables
$\Gamma \phi$	Diffusion coefficient
S_{ϕ}	Source term

1 Introduction

Energy is the basis for the survival and development of the industrial field, its total consumption continues to grow in recent years, how to improve energy efficiency is a problem that we need to pay attention to. When the fluid flows on the wall, there will be a boundary layer [1]. Affected by the boundary layer, there will be disturbance near the wall. Inserting a bluff body near the wall can effectively destroy the wall boundary layer, and make the stable flow state near the wall change to the unstable flow state in advance, so as to change the flow state of the flow field. This has been applied in the design of heat exchanger, enhanced heat transfer in the tube is an effective way to improve the energy utilization and heat transfer efficiency.

According to the previous research results, we generally accept that the flow is insensitive to Re, but strongly depends on L [2]. Most experimental studies are carried out at Re > 1000 [3–9]. Bearman et al. [3] studied the vortex shedding of flow over a cylinder with different gap ratio at Re = 4.5×10^4 . They found that there is a critical gap ratio that affects vortex shedding. Next, some authors (Grass et al. [4], Taniguchi et al. [5]) found that the critical gap ratio is related to δ , but there is no unified conclusion. Lei et al. [6] study the wake of near-wall cylinder at Re = $1.3 \times 10^4 \sim 1.45 \times 10^4$. It was demonstrated that there are three flow modes in different gap ratios. Wang et al. [7] studied the effect of flow over near-wall cylinder using particle image velocimetry (PIV) experiments at Re = 1.2×10^4 and δ = 0.4D. It was concluded that the flow has periodic vortex shedding when L/D \geq 0.3, and the wake shows obvious asymmetry around the center line of the cylinder when L/D \leq 0.6.

In addition, the heat transfer over near-wall cylinder are also studied. Fujita et al. [8] obtained the distribution of heat transfer coefficient through experiment when $L/D = 0 \sim 1.0$ at $Re = 7.0 \times 10^3$. They found that D, U_{in}, δ and the insertion position all have an impact, but gap ratio is the main factor. Suzuki et al. [9] studied the flow over near-wall cylinder with different gap ratio in turbulence through experiment. It was demonstrated that the interaction between the cold fluid flowing to the wall and the hot fluid flowing out of the wall is the main reason for the difference between heat transfer and momentum transfer. Wang et al. [10] demonstrated that the variation of turbulent boundary layer and the heat transfer performance is significantly related to the interaction between the cylinder and the wall boundary layer through large eddy simulation (LES).

Compared with the cylinder, the flow over near-wall square column has received limited attention. Martinuzzi et al. [11] studied the pressure distribution of near-wall square column with $L/D = 0.07 \sim 1.6$ at $Re = 1.89 \times 10^3$ and $\delta = 0.5D$. They found that four gaps related to the flow patterns. Durao et al. [12] analyzed the frequency spectrum of flow over square column with different gap ratio at $Re = 1.4 \times 10^4$. It was concluded that 0.35 is the critical gap ratio to suppress the vortex street. Bosch et al. [13] conducted a visualization experiment on the flow over near-wall square column at $Re = 2.2 \times 10^4$. It was found that the critical gap ratio to suppress vortex shedding is $0.35 \sim 0.5$.

In terms of the effect on heat transfer over near-wall square column, Yao et al. [14] studied it at Re \succ 6,000 through visual experiments. They found that there are three peaks in the local Nusselt Number distribution. And the second peak is the main reason for the whole heat transfer enhancement, the scrubbing effect of discrete vortex islands generated by it enhances heat transfer. In order to maximize the total heat transfer efficiency, Icoz et al. [15] used the numerical simulation and real-time experiment to study the near-wall square model in the rectangular tube channel at Re = $2.0 \times 10^3 \sim 4.0 \times 10^3$. They found that the heat transfer efficiency of inserting a bluff body is about $27\% \sim 50\%$ higher than that without bluff body. And square column has better heat transfer performance than cylinder. Dhinakaran et al. [16] simulated the square column near a moving wall through finite volume method and came to a conclusion similar to the above. Tanweer et al. [17] studied the square column near moving wall on laminar through three-dimensional direct numerical simulation. It was demonstrated that the Nusselt Number is closely related to gap ratio, and the critical gap ratio may be 0.5. But transition from laminar to turbulence and instabilities associated with this transition have not been addressed.

Generally speaking, most studies are mainly on laminar or turbulence, little research on heat transfer enhancement on transition flow has been concerned. The critical value from transition flow to turbulence is difficult to determine. However, the flow instability on transition flow usually shows the law of periodicity or quasi periodicity, which is different from the randomness of turbulence. It is highly significant to study the condition on transition flow. And the research on near-wall cylinder and square column on transition flow is still lack of further comparison and induction. This can play a certain theoretical guiding role for practical application in some engineering fields. In this study, we choose Re = 300 to study them with same characteristic length D in the same experimental device, so that they can be compared directly.

2 Experimental Facility and Instrumentation

2.1 Experiment Platform

The test bench includes the water tank, water pump, diaphragm valve, honeycomb device, rectification, contraction, test and transition sections, as shown in Fig. 1. Water is driven from the lower tank to the upper tank by the water pump firstly. The flow velocity is controlled by diaphragm valve, then water flows into the rectification section and contraction section. There are two different honeycomb devices in the rectification section, which ensure the acceleration and rectification of the flow. In order to prevent the back flow from affecting the test, the transition section is set much longer. At last, water flows into the lower water tank through the right water tank and the bottom pipe, thus forming a complete circulation process.



Figure 1: Schematic of open-loop, recirculating water test bench

2.2 Particle Image Velocimetry (PIV) System

Fig. 2 shows the schematic of PIV System, which includes a dual-pulse laser, cooler, CCD camera, synchronous controller, and computer. Silver-plated hollow glass spheres $(13\sim15 \,\mu\text{m})$ in diameter) with good light scattering and follow ability are added into test bench as tracer particles. Experimental models are made of smooth and transparent acrylic material, which can effectively suppress the optical pollution caused by reflection. The synchronization controller can synchronize the frequency of laser and camera. The laser produces a sheet light source to water surface and irradiates vertically in the middle of models. Meanwhile, the camera takes photos of the shooting area which are transmitted to computer in real time. Then all photos are post-processed by software (Insight 4G) to obtain the information we need.



Figure 2: Schematic of PIV system

Fig. 3 shows the schematic of shooting area. In this study, the Reynolds Number Re is defined by the following equation:

$$\operatorname{Re} = \frac{\rho U_{in} D}{\mu} \tag{1}$$

In experiment, we choosed Re = 300, $T = 25^{\circ}C$, and D = 15 mm. The frequency of laser is 20 Hz, 400 photos are taken with CCD camera in each condition.



Figure 3: Schematic of the shooting area

2.3 Test Bench Verification

The schematic of verifying the stability of test section is shown in Fig. 4. In the middle of X direction, we selected 60 points to obtain the average velocity distribution in the horizontal direction as shown in Fig. 5a. We can see that the water flow is relatively stable in middle position. Then we selected 15 laser surfaces in Z direction, and selected the same x and y coordinate points on these 15 sections to obtain the velocity vector diagram of each point. As shown in Fig. 5b, the velocity is approximately equal in the horizontal plane of $50\sim250$ mm, which means the flow is stability and uniformity.



Figure 4: Schematic of test section verification



Figure 5: The average velocity distribution (a) the horizontal direction; (b) the vertical direction

3 Numerical Calculation Models and Methods

In recent years, computational fluid dynamics (CFD) has developed rapidly due to the rapid progress of computer technology. The software Fluent we used in this study is a commercial CFD software package with high popularity in the world, which has strong universality.

3.1 Numerical Calculation Model and Boundary Conditions

The numerical calculation models is shown in Fig. 6. X is the direction of flow, the Y direction is perpendicular to the X direction. H its the height of test section. The red wall (Hot Wall) represents the uniformly heated wall, Twall = 328 K. Two models are not heated. The inlet boundary (*Xup*) and outlet boundary (*Xdown*) are 15D and 70D from the model, respectively. Tin is inlet temperature, Tin = 298 K.



Figure 6: Schematic of numerical calculation models

3.2 Governing Equation

In this study, the continuous and incompressible water (physical parameters are constant) was assumed, and it belongs to two-dimensional numerical simulation. The governing equations can be considered as follows:

$$\rho \frac{\partial U}{\partial X} + \rho \frac{\partial U}{\partial Y} = 0 \tag{2}$$

Momentum equation in X direction:

$$\rho \frac{\partial U}{\partial t} + \rho \frac{\partial U^2}{\partial X} + \rho \frac{\partial UV}{\partial Y} = -\frac{\partial P}{\partial X} + \mu \left(\frac{\partial^2 U}{\partial X^2} + \frac{\partial^2 U}{\partial Y^2}\right)$$
(3)

Momentum equation in Y direction:

$$\rho \frac{\partial V}{\partial t} + \rho \frac{\partial UV}{\partial Y} + \rho \frac{\partial V^2}{\partial Y} = -\frac{\partial P}{\partial Y} + \mu \left(\frac{\partial^2 V}{\partial X^2} + \frac{\partial^2 V}{\partial Y^2}\right) \tag{4}$$

Energy equation:

$$\rho \frac{\partial T}{\partial t} + \rho \frac{\partial UT}{\partial X} + \rho \frac{\partial VT}{\partial Y} = \frac{k}{Cp} \left(\frac{\partial^2 T}{\partial X^2} + \frac{\partial^2 T}{\partial Y^2} \right)$$
(5)

3.3 Grid Division

As shown in Fig. 7, in order to effectively capture characteristics of the separated shear layer around models, an O-type grid was used and further refined around the cylinder; for the square column, the surrounding grid is directly performed encryption. In order to ensure the calculation accuracy, the maximum grid width does not exceed 15 times the minimum grid width.

3.4 Discretization of Governing Equations

The Finite Volume Method (FVM) commonly used in numerical heat transfer has accurate integral conservation, and the coefficients of the discrete equation have clear physical significance. Most CFD software such as Fluent and Flotherm both adopt this method.



Figure 7: Locally enlarged grids distribution of models

We used this method to rewrite the above control Eqs. (2)–(5) into the general format, the equation is as follow:

$$\rho \frac{\partial \theta}{\partial t} + \rho U \frac{\partial \theta}{\partial x} + \rho V \frac{\partial \theta}{\partial x} + \rho W \frac{\partial \varphi}{\partial x} = \Gamma_{\varphi} \left(\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} + \frac{\partial^2 \varphi}{\partial z^2} \right) + S_{\varphi}$$
(6)

Integrating the general form of the governing equation, the convection term adopts the first-order upwind style, the diffusion term adopts the central difference format, and the two-dimensional discretization equation of the following form is obtained:

$$a_p\varphi_p = a_E\varphi_E + a_W\varphi_W + a_N\varphi_N + a_S\varphi_S + a_T\varphi_T + a_B\varphi_B + b$$
(7)

3.5 Coupling and Correction of Pressure & Velocity

In the governing equations, the pressure as the source term appears in the momentum equation in the form of first derivative, the pressure and velocity are coupled with each other. As shown in Fig. 8, we use the SIMPLE Algorithm [18] based on staggered grid to correct the pressure field and velocity field in each iteration.

3.6 Grid Independence Verification

The grid density has an important influence on calculation results. And Reg is used to represent the grid density [19], which is defined in Eq. (8).

$$\operatorname{Reg} = \frac{\rho U_{in} \Delta X_{\min}}{\mu} \tag{8}$$

Taking the near-wall single cylinder as an example, three different densities (Reg = 2, 6 and 10) grids were tested for numerical calculation, the values for local Nusselt number on the wall are shown in

Fig. 9. The comparison shows that there are small differences between three densities at the peak. As shown in Table 1, the difference between Reg = 6 and Reg = 2 is very limited (only 0.908%). To balance the grid accuracy and the computing cost, Reg = 6 was chosen in this study.



Figure 8: Flow chart of SIMPLE algorithm



Figure 9: Grid independence verification

Grid accuracy	ΔX_{\min}	Total number of grids	\overline{Nu}	Error* (%)
Reg=2	0.0001	330719	2.534	0
Reg = 6	0.0003	211312	2.511	-0.908
Reg = 10	0.0005	108039	2.481	-2.092

Table 1: Comparison of different grid accuracy at Re = 300

Note: *The error rates of grid accuracy are all based on Reg = 2.

4 Results and Discussion

4.1 Numerical Simulation Verification

The instantaneous vorticity field of the case with L/D = 0.4 were chosen to verify the accuracy and reliability of the numerical calculations, Fig. 10 presents the comparison between numerical calculation and experiment results.



Figure 10: Comparison of simulation and experimental results (a) experimental results (b) simulation results

It can be seen that the numerical simulation result is in good agreement with the experimental results. For L/D = 0.4, the vorticity scale and intensity of them are basically same. It can be considered that the calculation results in this study are accurate and reliable.

4.2 The Time-Average Flow Field

Considering the generality of the time-averaged characteristics, the time-averaged streamline and velocity field (Figs. 11a and 11b) and vorticity of models are compared through experiment. In flow field, the changes of flow are mainly manifested in the changes of the separation shear layer and the scale of vortexes. Vorticity is generally defined as the curl of the velocity vector. In Figs. 12a and 12b, blue represents negative vortex which guides clockwise flow; red indicates positive vortex which guides counter clockwise flow. The depth of color indicates the strength of the vorticity.



Figure 11: (a): Time-averaged streamline of cylinder at different L/D (b): Time-averaged streamline of square column at different L/D

When L/D = 0.2, flow over models forms a double-sided separation shear layer, the upper shear layer forms a clockwise recirculation, the vorticity intensity is high. At this time, the development of shear layer on the lower side is restrained, the velocity through the gap is accelerated, and a counter clockwise negative vortex is formed, a clockwise back flow is formed at a distance. When $L/D = 0.4 \sim 0.6$, the vorticity intensity of clockwise vortex on the upper side is smaller, the shear layer on the lower side develops slowly. And the strength of counter clockwise vortex pairs of square column is larger than before. When L/D = 0.8, the inhibition of the wall weakens, the scale and intensity of vortex gradually increase. The vortex pair behind square column is larger than that of cylinder. When L/D = 1.0, the inhibition is further weakened, the vortex pair behind models tends to be symmetrical. However, the scale and vorticity intensity of vortexes have no changes, which is similar to that without wall. It is indicated that the influence of the wall is already very small.

4.3 Analysis of the Velocity Section

In order to study the influence on the flow instability of the wall at different L/D, the cross-sectional distribution of time-averaged velocity was analyzed, as shown in Fig. 13. Take the case with L/D = 1.0 as an example, three sections were selected at X/D = 1.5, 3.0, and 4.5, respectively.

At X/D = 1.5 section, the distribution of cylinder and square column are shown in Figs. 13a and 13d, respectively. When L/D = 0.2, the inhibitory effect of the wall is strong, the acceleration effect of flow is not obvious; when $L/D = 0.4 \sim 0.6$, the near-wall velocity of cylinder is significantly accelerated, while it has not changed significantly for square column. When L/D = 0.8, the weakening of inhibitory effect causes the near-wall velocity of flow to increase continually. At this time, the reflux area at the far side of square column disappears, the velocity near the wall begins to increase significantly. When L/D = 1.0, the lower shear layer is fully developed, and the acceleration effect of flow near the wall reaches the strongest.

At X/D = 3.0, as shown in Figs. 13b and 13e, respectively. When L/D = 0.2, X/D = 3.0 is at the edge of the far clockwise recirculation zone, so the near-wall velocity of flow is almost zero, the wall disturbance is weak at this time. When L/D = 0.4, the velocity near the wall of cylinder does not change significantly, and the disappearance of the clockwise reflux area causes the velocity on the back of cylinder to increase significantly, the velocity of square column is also accelerated. When $L/D = 0.6 \sim 1.0$, the velocity near the wall of models gradually increases, it reaches the fastest when L/D = 1.0.

At X/D = 4.5, as shown in Figs. 13c and 13f, respectively. When $L/D = 0.2 \sim 0.4$, X/D = 4.5 section is near the clockwise recirculation zone, the near-wall velocity is negative at this time. When L/D increases to 0.6, the velocity on the back side of cylinder increases. However, there is still a clockwise recirculation zone in the far side of square column, and its velocity which is smaller than that of cylinder has no obvious change. When $L/D = 0.8 \sim 1.0$, the velocity curve of square column is similar to that of X/D = 1.5 and 3.0. And the scale of the vortex pair behind cylinder is small at X/D = 4.5, resulting in less impact on the speed at the same conditions which makes it gradually close to the speed in the main flow.

4.4 Transient Periodic Flow Characteristics

The flow field under the transition flow has a periodic change law. In order to explore the flow periodicity of near-wall models, the wake monitoring point in Y direction over time of the case with L/D = 0.2, 0.6, 1.0 was chosen to analyze. The point is selected at the position with a lateral distance of X = 2.5D from the center of models. The vertical distance varies with the change of gap.

Figs. 14 and 15 show the fluctuation diagram (V-t) and power spectral density diagram (PSD*f*) of velocity of the monitoring point in Y direction with time respectively. It can be seen that the velocity of two models varies irregularly with t near the horizontal axis. And the amplitude is relatively small at



L/D = 0.2. The power spectral density also has different peaks at multiple frequencies, indicating that there is no periodic characteristics at this time.

Figure 12: (a): Time-averaged vorticity of near-wall cylinder at different L/D (b): Time-averaged vorticity of near-wall square column at different L/D

When L/D = 0.6, the amplitude of velocity of near-wall cylinder is bigger, while there is no obvious change for square column. The results show that there are peaks at frequency of 1.5 Hz and 1.2 Hz for two models, respectively, which means that the periodic vibration with main frequency of 1.5 Hz and 1.2 Hz are formed respectively. When L/D = 1.0, the vibration of velocity remains periodic and the main

vibration frequency decreases slightly, but the amplitudes in Y direction of them are different. The amplitude of velocity and the disturbance degree of square column increases, while those of cylinder decreases. In general, the main vibration frequency for square column decreases gradually, which is slightly smaller than that of cylinder, indicating that the period of square column is much longer.



Figure 13: The velocity of different cross-sections of cylinder (a–c) and square column (d–f) at different L/D Single cylinder (a–c) Single square column (d–f)



Figure 14: Velocity fluctuation diagram at different L/D (a) Single cylinder (b) Single square column

The preceding discussion shows that two models both have periodic characteristics. Therefore, the transient characteristics of flow in a periodic cycle are discussed in detail. The instantaneous streamlines and velocity magnitude fields in a periodic cycle for the case with L/D = 1.0 are presented in Figs. 16a and 16b. The yellow and blue arrows present the clockwise vortex A and counter clockwise vortex B,

respectively. At the beginning, the vortex A formed. With the development, the scale of vortex A continues to increase and gradually moves to the far side of models, and finally disappears completely; at the same time, the vortex B also experiences a process from formation, development to shedding, and the phenomenon of alternating shedding of positive and negative vortex is shown in the wake of flow. This indicates that the periodic vortex motion of the wake near the wall increases the flow instability.



Figure 15: Power spectral density diagram at different L/D (a) Single cylinder (b) Single square column



Figure 16: (a): Streamlines and velocity field in a periodic cycle of cylinder at L/D = 1.0 (b): Streamlines and velocity field in a periodic cycle of square column at L/D = 1.0

4.5 Heat Transfer Enhancement Characteristics of the Wall

Fig. 17 presents the instantaneous temperature fields of two models at different L/D. It can be seen that their instantaneous temperature fields have the similar characteristics. When L/D = 0.2, the gap is small, the heat transfer effect is poor and the wall temperature boundary layer is thick. With the increase of L/D, the viscosity of the wall decreases, and the thickness of temperature boundary layer becomes thinner, which indicates that the heat transfer effect is gradually enhanced. Significantly, the temperature boundary layer behind cylinder is thinner than that of square column when L/D = 0.6.



Figure 17: Instantaneous temperature fields at different L/D

Figs. 18a and 18b show the $\overline{Nu_t}$ curves of models at different L/D, respectively. With the increase of L/D, the $\overline{Nu_t}$ curves are divided into unimodal curve and bimodal curve. For cylinder, the $\overline{Nu_t}$ curve is unimodal curve when L/D ≤ 0.4 , and it becomes bimodal curve when L/D ≥ 0.6 . And the square column displays hysteresis compared with the cylinder. The range of unimodal and bimodal curve is L/D ≤ 0.6 and L/D ≥ 0.8 , respectively.



Figure 18: The time-averaged nusselt Number at different L/D: (a) cylinder; (b) square column

In general, the $\overline{Nu_t}$ curves of two models are similar. The positions of the first peak are both basically fixed which do not change with the varies of gaps. And the values of the first peak of models decrease with the increase of L/D. Different from the first peak, the values of the second peak both increase with the increase of L/D. At the second peak, the values of the peak first increase and then decrease when $L/D = 0.8 \sim 1.0$, and they reaches the maximum at L/D = 0.8 and L/D = 1.0, respectively.

Then time-averaged Friction Coefficient ($\overline{Cf_t}$) of the wall was further analyzed. Figs. 19a and 19b show the $\overline{Cf_t}$ curves of models at different L/D, respectively. The values of the first peak also decrease with the increase of L/D, which is similar to the trend of the $\overline{Nu_t}$ curves. While, there is a smaller peak appears at the second peak of the $\overline{Cf_t}$ curve.



Figure 19: The time-averaged friction Coefficient at different L/D: (a) Single cylinder; (b) Single square column

According to the analysis, it can be known that the flow through the gap is squeezed and accelerated, which makes the heat transfer to be strengthened and produces the first peak of $\overline{Nu_t}$ curve at the same time. With the increase of the velocity, the friction between the flow and wall increases which makes the friction coefficient increases. The position of the first peak of $\overline{Cf_t}$ curve is exactly the position of the first peak of $\overline{Nu_t}$ curve, which indicates that the increase of heat transfer effect is accompanied by the increase of friction.

In order to further explore the enhanced heat transfer effect at different L/D, we analyzed the time-spatial averaged Nusselt Number \overline{Nu} and the time-spatial averaged Friction Coefficient \overline{Cf} , respectively. And a summary of errors of them is given in Table 2. It can be seen that the \overline{Nu} of cylinder is always larger than that of square column in Fig. 20, which indicates that the inserted a cylinder near the wall has better heat transfer enhancement effect. When L/D = 0.8, the value of \overline{Nu} reaches the maximum in all conditions, which means that L/D = 0.8 is the best gap ratio for the wall heat transfer enhancement.

L/D	Model	Nu	Error ₁ * (%)	\overline{Cf}	Error ₂ * (%)
0.2	Cylinder	2.8315	0	0.0106	0
	Square column	2.6281	0	0.0090	0
0.4	Cylinder	2.6604	-6.04	0.0116	9.43
	Square column	2.6211	-0.27	0.0105	16.67
0.6	Cylinder	2.7195	-3.96	0.0107	0.94
	Square column	2.6867	2.23	0.0110	22.22
0.8	Cylinder	3.0700	8.42	0.0131	23.58
	Square column	3.0391	15.64	0.0110	22.22
1.0	Cylinder	2.5112	-11.31	0.0109	2.83
	Square column	2.2124	-15.82	0.0081	-10.00

Table 2: Comparison of the heat transfer and friction loss at different L/D

Note: * The errors of gap ratios are all based on L/D = 0.2.



Figure 20: Time-spatial averaged nusselt number of models at different L/D

As we can see, the \overline{Cf} of cylinder is also larger than that of square column except for L/D = 0.6 in Fig. 21. The value of the \overline{Cf} means the friction resistance, which also represents that the inserted bluff body enhances the heat transfer enhancement effect on the wall. Compared with the case of L/D = 0.2, the heat transfer coefficient increase by 8.42% and the friction loss increases by 23.58% in the case of L/D = 0.8 for square column; while the heat transfer coefficient increase by 15.64% and the friction loss increases by 22.22% in the case of L/D = 0.8 for cylinder. In general, it can be concluded that the heat transfer enhancement effect of cylinder is better.



Figure 21: Time-spatial averaged friction coefficient of models at different L/D

5 Conclusions

In transition flow (Re = 300), we analyzed the effect of different gap ratios (L/D = $0.2 \sim 1.0$) on flow and heat transfer over single bluff body near the wall. The main conclusions drawn from the results provided are as follows:

- (1) The gap ratio is an important factor affecting the wake characteristics of bluff body in near-wall condition. When it is small, the inhibition effect of the wall is strong, the heat transfer effect is poor and the temperature boundary layer on the wall is thick, models have no periodic characteristics; with its increasing, the inhibition effect decreases, the thickness of wall temperature boundary layer becomes thinner which means the heat transfer effect is obviously enhanced, and periodic vortex shedding motion is finally formed which strengthens the flow instability;
- (2) The wake of square column has fixed separation points (on the front and rear sides), while the cylinder is not. And the vortex size and vorticity intensity of square column are greater. In addition, the vortex shedding period of the flow around square column is also longer. However, the heat transfer effect of near-wall cylinder is much better and reaches the best when L/D = 0.8.
- (3) The square column displays hysteresis compared with the cylinder at the same gap ratio (the critical gap ratio of cylinder is in $0.2 \sim 0.4$, while that of square column is $0.4 \sim 0.6$).

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