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ARTICLE

Mesoscopic-Scale Numerical Investigation Including the Influence of Process Parameters on LPBF Multi-Layer Multi-Path Formation

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ABSTRACT

As a typical laser additive manufacturing technology, laser powder bed fusion (LPBF) has achieved demonstration applications in aerospace, biomedical and other fields. However, how to select process parameters quickly and reasonably is still the main concern of LPBF production. In order to quantitatively analyze the influence of different process parameters (laser power, scanning speed, hatch space and layer thickness) on the LPBF process, the multilayer and multi-path forming process of LPBF was predicted based on the open-source discrete element method framework Yade and the open-source finite volume method framework OpenFOAM. Based on the design of experiments method, a four-factor three-level orthogonal test scheme was designed, and the porosity and surface roughness data of each calculation scheme were extracted. By analyzing the orthogonal test data, it was found that as the laser power increased, the porosity decreased, and as the scanning speed, hatch space, and layer thickness increased, the porosity increased. In addition, the influence of laser power and scanning speed on surface roughness showed a trend of decreasing first and then increasing, while the influence of scanning distance and layer thickness on surface roughness showed a monotonous increasing trend. The order of the influence of each process parameter on porosity was: scanning speed > laying thickness > laser power > hatch space, and the order of the influence of each process parameter on surface roughness was: hatch space > layer thickness > laser power > scanning speed. So the porosity of the part is most sensitive to scanning speed, and the surface roughness is the most sensitive to hatch space. The above conclusions are expected to provide process control basis for actual LPBF production of the 316L stainless steel alloy.

KEYWORDS

Laser powder bed fusion; process parameter; porosity; surface roughness; orthogonal test method; numerical simulation

1 Introduction

As a typical laser additive manufacturing technology, laser powder bed fusion (LPBF) has gradually been used for direct forming of complex metal parts, and has achieved exemplary applications in aerospace, biomedical and other fields [1,2]. However, the current LPBF production still faces many limitations, for example, the focus of LPBF engineers is still how to quickly and



reasonably select process parameters so that the porosity [3] and surface roughness [4] are at a low level. Therefore, in-depth study of the influence of process parameters on the LPBF process plays an important role in accelerating the industrial application of LPBF technology.

Regarding the influence of process parameters on the LPBF process, scholars have carried out a large number of experimental studies. Among them, the process parameters mainly include laser power [5,6], exposure time [7], scanning speed [8,9], hatch space [10,11] and layer thickness [12], and the quality indicators mainly include porosity [13], surface roughness [14], residual stress [15], deformation [16,17], microstructure [18] and mechanical properties (yield strength [19], tensile strength [20], elongation [21] and microhardness [22]). Jiang et al. [23] used the normalization method to comprehensively analyze the influence of multiple process parameters on the LPBF process, and evaluated the influence of laser power, scanning speed, hatch space and their combination on density, surface roughness and microhardness through analysis of variance, and found that laser power had the greatest influence on the forming quality. The obtained experimental research results [5–23] are of great value to deeply understand the influence mechanism of process parameters on the LPBF process.

The core of the LPBF process is that the metal particles gradually melt after being heated by the laser, and then solidify to form a solidified track. This process is a typical high temperature and high transient physical process, where the highest temperature can reach 4000°C [24], and the characteristic time of molten pool flow is on the order of microseconds [25]. Although the current experimental methods such as X-ray in-situ imaging technology and high-speed cameras can observe the LPBF process in real time [26], the experimental methods are difficult to accurately obtain the three-dimensional information of the LPBF process, such as the evolution of the three-dimensional shape of the molten pool. As a typical quantitative research method, numerical simulation has become a powerful auxiliary method for analyzing LPBF process [27-29]. At present, the simulation research for the LPBF process is mainly based on the following three scales: (a) macroscopic-scale, that is, by establishing a simplified model, the transition between the three phases "powder bed-metal liquid-phase-metal solid-phase" is equivalently handled to obtain the temperature field and stress field distribution [30-35]; (b) Mesoscopic-scale, that is, the heating effect of the laser on the metal particles is directly calculated to describe the dynamic behavior of the mesoscopic molten pool [36-41]; (c) Microscopic-scale, that is, based on the thermal field information of the LPBF process, the growth behavior of dendrites is described [42,43]. Yuan et al. [44] predicted the LPBF process at different scanning speeds based on the mesoscopic scale, and identified three mesoscopic molten pool states (unstable state, transition state, and steady state), and found that a stable molten pool with a small recessed area was beneficial to obtain a higher density part. The obtained simulation research results [27-44] provide a way to predict the temperature, molten pool flow, stress and other information of the LPBF process, but the current simulation research lacks a comprehensive analysis of the influence of process parameters on the LPBF multi-layer and multi-path process based on the mesoscopic scale, which is also the focus of this paper.

This paper was based on the open-source discrete element method (DEM) framework Yade and the open-source finite volume method (FVM) framework OpenFOAM to predict the multi-layer multi-path process of LPBF. In order to quantitatively analyze the effects of different process parameters (laser power, scanning speed, hatch space and layer thickness) on the porosity and surface roughness, based on the design of experiments (DOE) method, a four-factor threelevel orthogonal test scheme was designed, and the calculated results were compared with the experimental results. This paper is expected to provide a basis for process control in actual LPBF production.

2 Computer Model of LPBF

2.1 Mathematical Model

(1) Modeling the spreading powder process

The premise of describing the LPBF process based on the mesoscopic scale is to obtain the particle distribution of the powder bed. As a numerical calculation method for solving and analyzing the motion law and mechanical characteristics of complex discrete systems, DEM can be used to characterize collision and friction behaviors in particle systems [45]. The LPBF spreading powder process was predicted here based on DEM [39], and the calculation process was divided into the following four steps: (a) The metal particles were regarded as elastic spheres with contact friction effect, and the particle size distribution curve of the powder was obtained by means of experimental methods or literature data; (b) A particle cluster was generated in a certain space above the substrate and spread loosely on the substrate under the action of gravity; (c) The roller was moved to spread the powder, during which the contact friction between the roller and the particles and between the particles were considered; (d) After spreading powder, the sphere center coordinates and radius of the powder bed particles were derived.

(2) Laser heat source model

The way the laser energy is applied is very important to describe the LPBF process based on the mesoscopic scale. In order to ensure the reasonable application of laser energy and high calculation efficiency, the multi-reflection absorption effect was ignored and the "metal phase-gas phase" interface was traced firstly in real time, then the elements directly acted by the laser were determined according to the laser spot center and radius. Using the elements directly acted by the laser as the starting points, the elements within a certain distance along the direction of gravity were found and marked as the elements indirectly acted by the laser, and finally the laser energy was applied in the form of a body heat source. Eqs. (1)-(5) is the laser heat source model established herein, in which, f_{metal} represents the proportion of laser energy in the horizontal local area of a certain element acted by the laser, and Eqs. (4) and (5) is the volume of fluid (VOF) model [46]. It should be noted that Eqs. (1)-(3) are original.

$$Q_{laser} = f_{metal} \cdot \frac{q_{laser}}{\Delta \tau} \tag{1}$$

$$q_{laser} = \frac{2\eta P_{laser}}{\pi R^2} \exp\left(-2\frac{(x - x_0 - v_{laser}t)^2 + (y - y_0)^2}{R^2}\right)$$
(2)

$$f_{metal} = \frac{V_{metal}}{V_{sum}} \tag{3}$$

$$\frac{\partial \alpha_1}{\partial t} + \nabla \cdot (\alpha_1 \boldsymbol{u}) = 0 \tag{4}$$

$$\alpha_1 + \alpha_2 = 1 \tag{5}$$

(7)

where, Q_{laser} is the laser body energy density, W/m³; f_{metal} is the laser energy distribution coefficient; q_{laser} is the laser surface energy density, W/m²; Δz is the equivalent size of the element, such as the side length of a cube, m; η is the laser absorption rate of the metal; P_{laser} is the laser power, W; R is the spot radius, m; x, y are the horizontal coordinates of the element's center, m; x_0 , y_0 are the horizontal coordinates of the spot's center, m; v_{laser} is the scanning rate, m/s; t is the time, s; V_{metal} is the metal-phase volume of the element, m³; V_{sum} is the sum of the metal-phase volumes of the element, metal-phase of the element, respectively; u is the velocity, m/s.

(3) Mesoscopic molten pool dynamics model

Eqs. (6)–(12) is the LPBF mesoscopic molten pool dynamics model established herein, in which Eqs. (6) and (7) is the energy conservation equation, Eqs. (8)–(11) is the momentum conservation equation, and Eq. (12) is the mass conservation equation. In order to ensure the efficiency of numerical solution, two assumptions were made: the flow of liquid metal and gas were regarded as laminar flow of incompressible Newtonian fluid, and the mass loss caused by metal gasification was not considered.

$$\frac{\partial \overline{\rho} \, \overline{c}_e T}{\partial t} + \nabla \cdot (\overline{\rho} \boldsymbol{u} \overline{c}_e T) = \nabla \cdot \left(\overline{k} \nabla T\right) + Q_{laser} - |\nabla \alpha_1| \frac{2\overline{\rho} \, \overline{c}_e}{\rho_1 c_1 + \rho_2 c_2} \left\{ h_{con} \left(T - T_{con}\right) + \sigma_s \varepsilon \left(T^4 - T_{rad}^4\right) + 0.82 \frac{L_{gas} m}{\sqrt{2\pi m k_B T}} P_0 \exp\left[\frac{L_{gas} m}{k_B} \left(\frac{1}{T_{gas}} - \frac{1}{T}\right)\right] \right\}$$
(6)

 $\overline{\rho} = \alpha_1 \rho_1 + \alpha_2 \rho_2$

$$\frac{\partial \overline{\rho} \boldsymbol{u}}{\partial t} + \nabla \cdot (\overline{\rho} \boldsymbol{u} \otimes \boldsymbol{u}) = -\nabla p + \nabla \cdot \boldsymbol{\tau} + \overline{\rho} \boldsymbol{g} - \overline{\rho} K_C \left[\frac{\left(1 - f_{liquid}\right)^2}{f_{liquid}^3 + C_K} \right] \boldsymbol{u} + \left\{ \sigma \kappa \boldsymbol{n} + \frac{d\sigma}{dT} \left[\nabla T - \boldsymbol{n} \left(\boldsymbol{n} \cdot \nabla T \right) \right] \right. \\ \left. + 0.54 P_0 \exp\left[\frac{L_{gas} m}{k_B} \left(\frac{1}{T_{gas}} - \frac{1}{T} \right) \right] \boldsymbol{n} \right\} \left| \nabla \alpha_1 \right|$$

$$(8)$$

$$\boldsymbol{\tau} = 2\overline{\mu} \left[\frac{1}{2} \nabla \boldsymbol{u} + \frac{1}{2} \left(\nabla \boldsymbol{u} \right)^T \right]$$
(9)

$$\boldsymbol{n} = \frac{\nabla \alpha_1}{|\nabla \alpha_1|} \tag{10}$$

$$\kappa = -\nabla \cdot \boldsymbol{n} \tag{11}$$

$$\nabla \cdot \boldsymbol{u} = 0 \tag{12}$$

where, $\overline{\rho}$, ρ_1 , ρ_2 are the mixed, metal and gas densities, respectively, kg/m³; *T* is the temperature, K; \overline{c}_e , c_1 , c_2 are the equivalent [41], metal and gas specific heat capacities, respectively, J/(kg · K); \overline{k} is the mixed thermal conductivity, W/(m · K); h_{con} is the interface convection heat transfer coefficient, W/(m² · K); T_{con} is the external convection temperature, K; σ_s is the Stefan– Boltzmann constant, W/(m² · K⁴); ε is the emissivity; T_{rad} is the outside radiation temperature, K; L_{gas} is the metal vaporization latent heat, J/kg; *m* is the metal molecular mass, kg; k_B is the Boltzmann constant, J/K; P_0 is the standard atmospheric pressure, Pa; T_{gas} is the metal vaporization temperature, K; p is the pressure, Pa; τ is the stress tensor; $\overline{\mu}$ is the hybrid viscosity, Pa·s; g is the acceleration of gravity, m/s²; K_C is the drag coefficient of the mushy zone [47], 1/s; f_{liquid} is the liquid-phase ratio; C_K is a self-defined smaller value, such as 10^{-6} ; σ is the surface tension coefficient, N/m; $\frac{d\sigma}{dT}$ is the coefficient of surface tension change with temperature, N/(m·K); κ is the interface curvature, 1/m; **n** is the normal vector of the interface.



Forming the third layer of powder bed

Figure 1: Calculation flow of LPBF multi-layer multi-path process: (a1–a3) spreading the first layer of powder bed (particle size distribution \rightarrow generation a particle cluster \rightarrow complete spreading powder); (b1–b3) forming the first layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the first formed layer); (c1–c3) spreading the second layer of powder bed (particle size distribution \rightarrow generation a particle cluster \rightarrow complete spreading powder); (d1–d3) forming the second layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the second layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the second layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the second layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the second layer of powder bed (geometry model \rightarrow CFD simulation \rightarrow STL model of the second formed layer)

2.2 Numerical Solution

The open-source DEM framework Yade was used to calculate the spreading powder process, and the open-source FVM framework OpenFOAM was used to predict the LPBF multi-layer multi-path process. Fig. 1 shows the calculation flow of LPBF multi-layer multi-path process, which mainly includes the following steps: (a) Import the particle size distribution data into Yade, generate a particle cluster on the substrate, then move the roller to complete the spreading powder work of the first layer, and export the particles' center coordinates and radius data of the first layer of powder bed; (b) Import the particle information of the first layer of powder bed into the 3D modeling software to obtain the geometric model, develop the LPBF process solver based on OpenFOAM, predict the forming process of the first layer of powder bed, and derive the STL model of the first formed layer; (c) Import the STL model obtained in step (b) into Yade, calculate the spreading powder process for the second layer, and derive the particles' center coordinates and radius data of the second layer of powder bed; (d) Import the particle information of the second layer of powder bed into the 3D modeling software to obtain the geometric model, predict the forming process of the second layer based on OpenFOAM, and derive the STL model of the second formed layer; (e) Repeat steps (c, d) to predict the forming process of the subsequent layer. It should be noted that the molten pool had been cooled down to the room temperature when anther spreading powder process started.

3 Results and Discussion

3.1 Calculation Parameters

The metal powder used here was 316L stainless steel, and its alloy composition (mass percentage) is: Fe 65.395%–Cr 17.0%–Ni 12.0%-Mo 2.5%–Mn 2.0%–Si 1.0%–P 0.045%–C 0.03%–S 0.03%. Tab. 1 shows the physical properties of 316L stainless steel and air obtained with the software JMatPro v7.0. The particle size distribution of the stainless steel powder satisfied a Gaussian distribution (the central value is 25 μ m, and the variance is 5 μ m), and the particle size was artificially limited between 15 μ m and 35 μ m. When simulating the spreading powder process based on Yade, the set material parameters included density (7270 kg/m³), contact friction angle (0.1), Young's modulus (195 GPa) and Poisson's ratio (0.3).

The focus of this paper is to analyze the influence of process parameters on the LPBF multi-layer multi-path process based on the mesoscopic scale, and the considered process parameters include laser power, scanning speed, hatch space and layer thickness. In order to analyze the sensitivity of each process parameter, the orthogonal experiment method for the design of experiments was adopted, and Tab. 2 is the four-factor and three-level parameter table of process parameters, and Tab. 3 is the corresponding orthogonal test schemes. The reason for choosing the parameter values in Tab. 2 is that these parameter values are commonly used in actual LPBF schemes. Fig. 2 is a schematic diagram of the multi-layer multi-path forming process of each calculation scheme. Three layers of powder bed were formed together, and the laser scanned three paths for each layer of the powder bed. In order to control the size of the calculation domain as much as possible, the geometric dimensions of the calculation domain of each calculation scheme were X-direction (650 μ m), Y-direction (2 * hatch space + 100 μ m) and Z-direction (layer thickness * current forming layer number + 100μ m). In addition, the laser spot diameter was 70 μ m, the mesh size was 2.5 μ m, the calculation time step was 4×10^{-7} s, the laser absorption rate was 0.35, the ambient temperature was 300 K, and the computing resource used was configured as Intel Xeon Gold 5120 CPU (dual CPU, 56 threads, 96 GB memory).

Parameter	Value	Unit
Density of metal	7270	kg/m ³
Specific heat of metal	790	J/(kg⋅K)
Thermal conductivity of metal	24.55	$W/(m \cdot K)$
Solidus temperature	1658	Κ
Liquidus temperature	1723	Κ
Evaporation temperature	3090	K
Latent heat of melting	2.7×10^{5}	J/kg
Latent heat of gasification	7.45×10^{6}	J/kg
Viscosity of liquid metal	0.00345	Pa · s
Surface tension	1.6	N/m
Temperature coefficient of surface tension	-8×10^{-4}	$N/(m \cdot K)$
Molecular mass	9.3×10^{-26}	kg
Ambient pressure	101325	Ра
Boltzmann constant	1.380649×10^{-23}	J/K
Emissivity	0.26	
Stefan-Boltzmann constant	5.67×10^{-8}	$W/(m^2 \cdot K^4)$
Density of air	1	kg/m ³
Specific heat of air	718	$J/(kg \cdot K)$
Thermal conductivity of air	0.02346	$W/(m \cdot K)$
Viscosity of air	1.48×10^{-5}	$Pa \cdot s$

Table 1: Physical properties of 316L stainless steel and air

 Table 2: Four-factor and three-level parameter table

Factor level	Laser power (W)	Scanning speed (m/s)	Hatch space (μm)	Layer thickness (µm)
1	150	1	50	30
2	200	1.5	60	40
3	250	2	70	50

Table 3: Orthogonal test schemes

Calculation scheme	Laser power	Scanning speed	Hatch space	Layer thickness
1	level 1	level 1	level 1	level 1
2	level 1	level 2	level 2	level 2
3	level 1	level 3	level 3	level 3
4	level 2	level 1	level 2	level 3
5	level 2	level 2	level 3	level 1
6	level 2	level 3	level 1	level 2
7	level 3	level 1	level 3	level 2
8	level 3	level 2	level 1	level 3
9	level 3	level 3	level 2	level 1



Figure 2: Schematic diagram of the multi-layer multi-path forming process

3.2 Extraction of Porosity and Surface Roughness Data

Firstly, the simulation results were illustrated. Here, calculation Scheme 1 was taken as an example. Fig. 3 shows the temperature and molten pool distributions when forming each layer and each path. From the calculation results, it could be seen that, on one hand, the metal particles were rapidly melted by the laser heating, forming a molten pool, and even gasification; on the other hand, as the laser beam was in motion, the overheated molten pool continuously conducted heat to the surrounding metal and radiated heat to the external environment, making the molten pool in a quasi-steady state during the forming process. So it could be considered basically that the shape of the molten pool had always maintained a "droplet" shape. Fig. 4 shows the surface morphology of each formed layer. It could be clearly seen that there were bumps between adjacent solidified tracks. The reason for the bumps is that, on one hand, the surface of the molten pool formed a depression under the action of the gasification recoil, the so-called pinhole effect, so that the liquid metal in the molten pool was squeezed from the center of the laser spot to the surroundings; on the other hand, because the temperature of the molten pool surface presented an obvious distribution of "high spot center-lower surroundings," the liquid metal near the molten

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pool surface tended to flow from the spot center to the surroundings under the Marangoni effect. Under the combined action of the above two reasons, the height of the side of the molten pool was higher than that of the adjacent solidified track, and the side was too late to recover during the subsequent cooling and solidification process, and a bump was formed. It should be noted that in the actual LPBF process, spatter and powder bed erosion also have an important influence on the forming process [48,49]. In summary, the simulation results showed that the LPBF multi-layer multi-path process were very complicated. In order to realize the sensitivity analysis of the process parameters, it is necessary to extract the key information from the simulation results to achieve the purpose of quantitative analysis.



Figure 3: Simulation results of temperature field under calculation Scheme 1 (the yellow curve represents the boundary of the molten pool; parts $1\sim3$ represent different scanning paths): (a) Forming the first layer of powder bed; (b) Forming the second layer of powder bed; (c) Forming the third layer of powder bed

The porosity and surface roughness of the parts are the main quality indicators of concern in actual production, so the porosity and surface roughness were token here as the extraction information of the simulation results. Taking calculation Scheme 1 as an example, Fig. 5 shows the final gas-solid interface obtained after forming three layers and three path, and the method to obtain this interface was to extract the isosurface of $\alpha_1 = 0.5$. It could be seen from Fig. 5 that since the laser did not act on the front and rear ends of the X and Y directions, a large number of gas-solid interfaces appeared in these areas, so these areas needed to be avoided when extracting information on porosity and surface roughness. Fig. 6 is a partial volume area used for calculating porosity, and the top surface of the partial volume area needed to be lower than the upper surface of the formed zone in Fig. 5. The post-processing software ParaView v5.4.0 provided the element information summing operation for the local volume area, so the calculation method of porosity is as follows:

$$V_{total} = \sum_{n=1}^{N} V_i$$

$$V_{gas} = \sum_{i=1}^{N} V_i \phi_i$$
(13)
(14)

$$\phi = \frac{V_{gas}}{V_{total}} \tag{15}$$

where, V_i is the volume of the element, m^3 ; ϕ_i is the gas volume ratio of the element; N is the number of elements; V_{total} is the total volume of the statistical area, m^3 ; V_{gas} is the total volume of the gas-phase in the statistical area, m^3 ; ϕ is the porosity of the statistical area. V_{total} and V_{gas} could be provided by ParaView, and the extracted porosity data of each calculation scheme can be seen in Tab. 4.



Figure 4: Surface morphology of each formed layer under calculation Scheme 1: (a) The first formed layer; (b) The second formed layer; (c) The third formed layer



Figure 5: The final gas-solid interface under calculation Scheme 1

For the extraction of surface roughness data, a partial surface area (Fig. 7) was cut out from the upper surface of the interface in Fig. 5, and it was thought that the degree of fluctuation of the partial surface area could reflect the surface roughness of the part. Fig. 8 shows the local area used to calculate the surface roughness under calculation Scheme 3. It could be clearly seen CMES, 2021, vol.126, no.1

that due to the large hatch space at this time, there were metal particles that were not completely melted between the solidified tracks, and they would have a significant impact on the surface roughness, which was consistent with the actual situation. It should be noted that the size of the local area analyzed herein was limited to a few hundred microns, which is quite different from the actual surface size of the part, therefore, the so-called surface roughness data extracted here could only be regarded as a certain mapping of the actual surface roughness of the part, and the specific value could not represent the actual surface roughness. ParaView provides the operation of extracting the node information of the partial surface area, so the calculation method of surface roughness is as follows:

$$z_{average} = \frac{\sum_{i=1}^{m} z_i}{m} \tag{16}$$

$$S_{rough} = \frac{\sum_{i=1}^{m} \left| z_i - z_{average} \right|}{m} \tag{17}$$

where, z_i is the height coordinate of the node, m; *m* is the number of nodes; $z_{average}$ is the average height of the nodes in the local area, m; S_{rough} is the surface roughness, m. z_i could be provided by ParaView, and the extracted surface roughness data of each calculation scheme can be seen in Tab. 4.



Figure 6: The local volume area used to calculate the porosity under calculation Scheme 1 (the blue wire frame represents the calculation domain)

Calculation scheme	Porosity (%)	Surface roughness (μm)
1	4.56	2.414
2	13.64	2.932
3	19.43	5.830
4	9.59	3.191
5	8.72	3.651
6	12.77	2.322
7	6.41	4.591
8	10.85	2.763
9	7.75	2.820

Table 4: Porosity and surface roughness data of each calculation scheme



Figure 7: The local surface area used to calculate the surface roughness under calculation Scheme 1 (the blue wire frame represents the calculation domain)



Figure 8: The local surface area used to calculate the surface roughness under calculation Scheme 3 (the blue wire frame represents the calculation domain)

3.3 Sensitivity Analysis of Process Parameters

(A) The influence of different levels of process parameter on porosity

Based on the porosity and surface roughness data of each calculation scheme in Tab. 4, the influence of process parameters on the LPBF multi-layer multi-path process could be quantitatively analyzed. For each process parameter, the influence of different level parameters on porosity was analyzed. Taking laser power as an example, according to the data analysis strategy of the orthogonal experiment method, the level 1 parameter of laser power was used in calculation Schemes 1-3, so the porosity data of calculation Schemes 1-3 should be summed and averaged, and the results reflected the influence of the level 1 parameter of laser power on porosity. Similarly, the influence of level 2 and 3 parameters of laser power on porosity could be obtained (Fig. 9a). According to this strategy, the influence of different level parameters of scanning speed (Fig. 9b), hatch space (Fig. 9c) and layer thickness (Fig. 9d) on porosity could be obtained. It can be seen from the data in Fig. 9 that the effects of laser power, scanning speed, hatch space and layer thickness on porosity all exhibited monotonicity. Among them, as the laser power increased, the porosity decreased, and as the scanning speed, hatch space and layer thickness increased, the porosity increased. Experimental research [50,51] also revealed the same law. The reason for this law is that the larger the laser power, the smaller the scanning speed, the hatch space and the layer thickness meant that the metal particles in a certain volume absorbed more laser energy, so that the metal particles could be more fully fused, and the gas in the molten pool had more sufficient escape time. It should be noted that since the highest laser power selected herein was only 250 W, the data in Fig. 9a did not reflect the entrainment phenomenon caused by the excessively high laser power, which easily causes the porosity to increase.



Figure 9: Influence of different levels of process parameter on porosity (the abscissa represents different levels; the ordinate represents the porosity, unit: %): (a) Laser power; (b) Scanning speed; (c) Hatch space; (d) Layer thickness

(B) The influence of different levels of process parameter on surface roughness

With reference to the above data analysis strategy, Fig. 10 shows the influences of different level parameters of laser power (Fig. 10a), scanning speed (Fig. 10b), hatch space (Fig. 10c) and layer thickness (Fig. 10d) on surface roughness. It can be seen from the data in Fig. 10 that the influence of laser power and scanning speed on surface roughness showed a trend of first decreasing and then increasing, while the influence of hatch space and layer thickness on surface roughness showed a monotonous increasing trend. Experimental research [50] also revealed the same law. The reason is that, on one hand, too low laser power and too high scanning speed meant that the laser energy applied to the powder bed per unit time was too little, and it was difficult to fully fuse metal particles to obtain a rough surface. Too high laser power and too low scanning speed meant that too much laser energy was applied to the powder bed per unit time, which caused the pinhole phenomenon and the Marangoni effect to be too significant, thereby obtaining an uneven solidified track surface. On the other hand, because the hatch space and layer thickness gradually increased, the laser

energy applied to a certain volume of the powder bed was reduced, and it was difficult to fully fuse the metal particles to obtain a rough surface.



Figure 10: Influence of different levels of process parameter on surface roughness (the abscissa represents different levels; the ordinate represents the surface roughness, unit: μ m): (a) Laser power; (b) Scanning speed; (c) Hatch space; (d) Layer thickness

(C) Degree of influence of each process parameter on porosity and surface roughness

Then, the degree of influence of each process parameter on porosity and surface roughness was analyzed, that is, comparing each process parameter horizontally, and ranking the influence of each process parameter on porosity and surface roughness. Taking the influence of laser power on porosity as an example, according to the data analysis strategy in the orthogonal experiment method, the range (the difference between the maximum value and the minimum value) in Fig. 9a could represent the influence of laser power on porosity. According to this strategy, the influence of each process parameter on porosity (Fig. 11a) and surface roughness (Fig. 11b) could be obtained. It can be seen from the data in Fig. 11 that the order of the influence of each process parameter on porosity is: scanningspeed > layerthickness > laserpower > hatchspace, and the order of the influence of each process parameter on surface roughness is: hatchspace > layerthickness > laserpower > scanningspeed, that is, the porosity of the part is most sensitive to scanning speed, and the surface roughness of the part is the most sensitive to hatch space. The order of the influence of process parameters obtained herein was not consistent with [23]. The reason is that the degree of influence of each process parameter on porosity and surface roughness was closely related to the specific values of the parameters, and the ranges of the parameters' values set herein were not completely consistent with the ranges of [23]. The above-mentioned data analysis conclusions help to provide a basis for process control for actual LPBF production of the 316L stainless steel alloy.



Figure 11: Degree of influence of each process parameter on porosity and surface roughness (1~4 in the abscissa represent laser power, scanning speed, hatch space and layer thickness, respectively): (a) Porosity range under each process parameter (unit: %); (b) Surface roughness range under each process parameter (unit: μ m)

4 Conclusions

- (1) Based on the open-source DEM framework Yade and the open-source FVM framework OpenFOAM, the multi-layer multi-path forming process of LPBF was predicted herein. In order to quantitatively analyze the influence of different process parameters (laser power, scanning speed, hatch space and layer thickness) on the LPBF process, based on the DOE method, a four-factor three-level orthogonal test scheme was designed, and the porosity and surface roughness data of each calculation scheme were extracted.
- (2) By analyzing the orthogonal test data, it was found that as the laser power increased, the porosity decreased, and as the scanning speed, hatch space, and layer thickness increased, the porosity increased. In addition, the influence of laser power and scanning speed on surface roughness showed a trend of decreasing first and then increasing, while the influence of hatch space and layer thickness on surface roughness showed a monotonous increasing trend.
- (3) The order of the influence of each process parameter on porosity is: scanning speed > layer thickness > laser power > hatch space, and the order of the influence of each process parameter on surface roughness is: hatch space > layer thickness > laser power > scanning speed. The above conclusions are helpful to provide process control basis for actual LPBF production of the 316L stainless steel alloy.

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